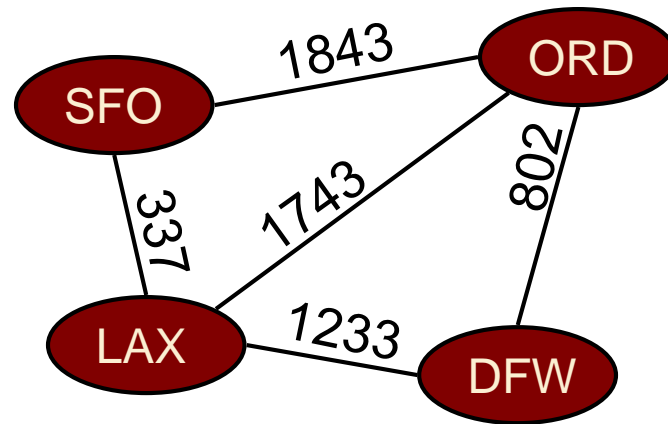
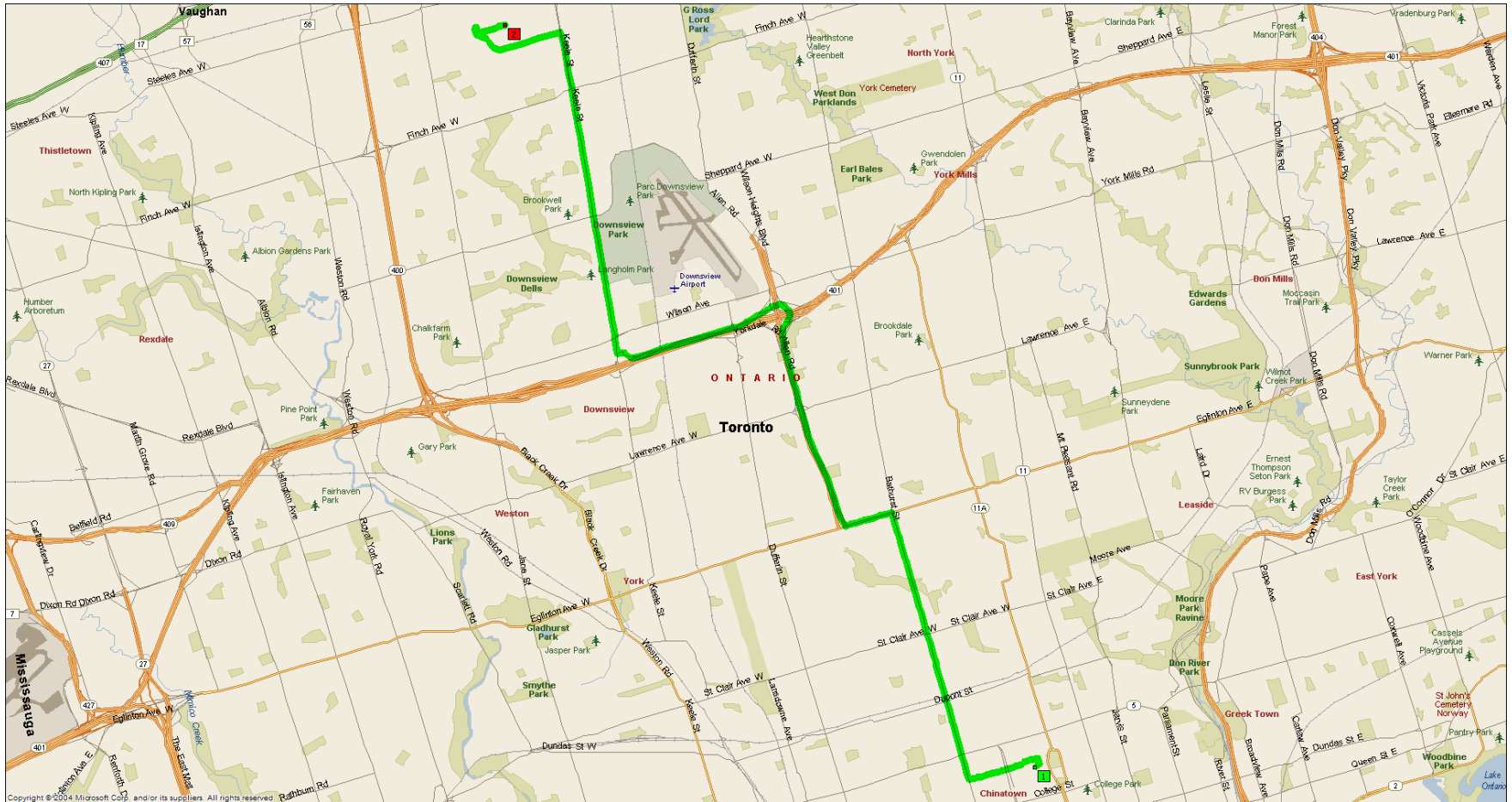


Graphs – Depth First Search



Graph Search Algorithms



Outline

- DFS Algorithm
- DFS Example
- DFS Applications

Outline

- **DFS Algorithm**
- DFS Example
- DFS Applications

Depth First Search (DFS)

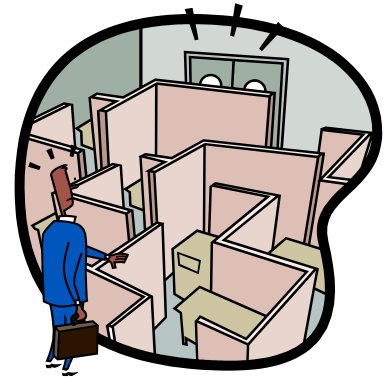
➤ Idea:

- ❑ Continue searching “deeper” into the graph, until we get stuck.
- ❑ If all the edges leaving v have been explored we “backtrack” to the vertex from which v was discovered.
- ❑ Analogous to Euler tour for trees

➤ Used to help solve many graph problems, including

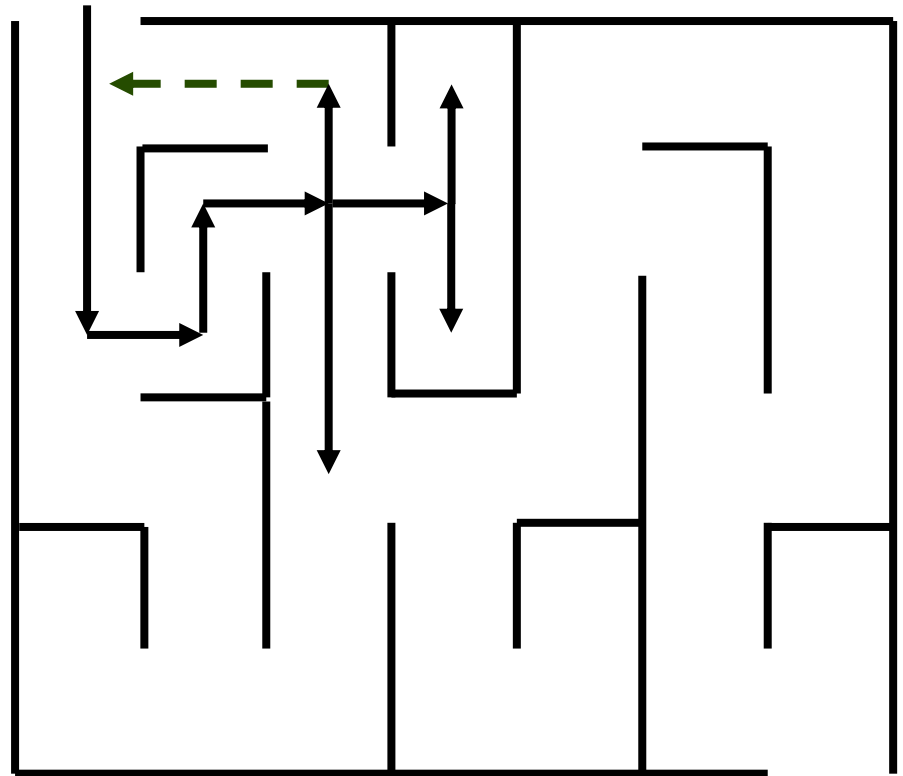
- ❑ Nodes that are reachable from a specific node v
- ❑ Detection of cycles
- ❑ Extraction of strongly connected components
- ❑ Topological sorts

Depth-First Search



➤ The DFS algorithm is similar to a classic strategy for exploring a maze

- ❑ We mark each intersection, corner and dead end (vertex) visited
- ❑ We mark each corridor (edge) traversed
- ❑ We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)

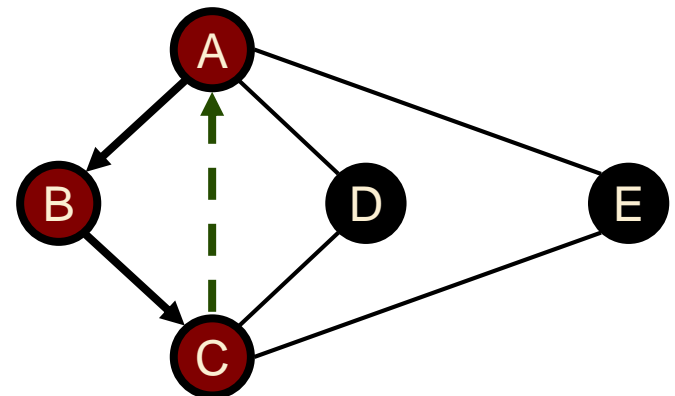
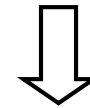
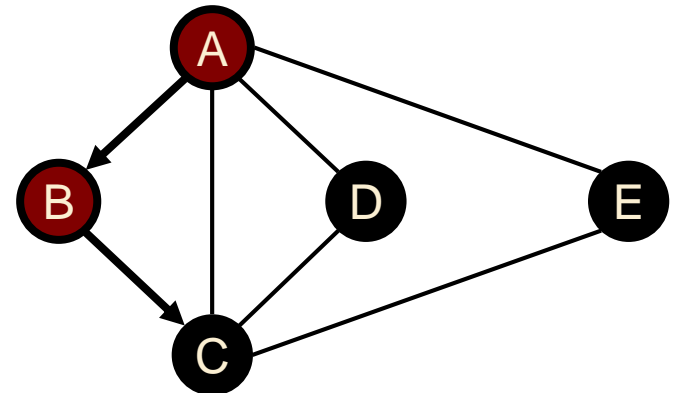
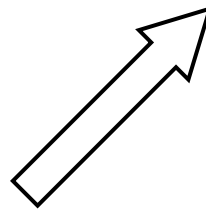
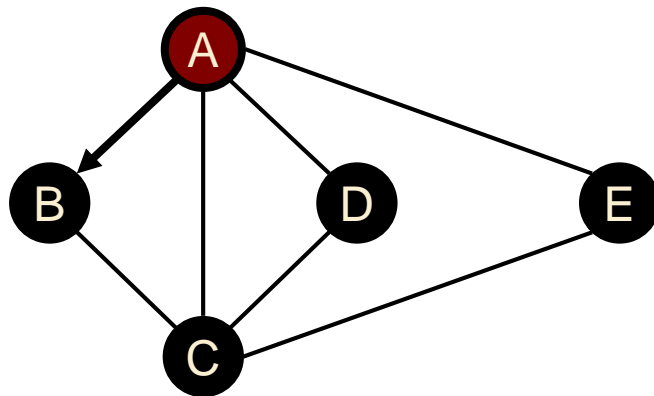
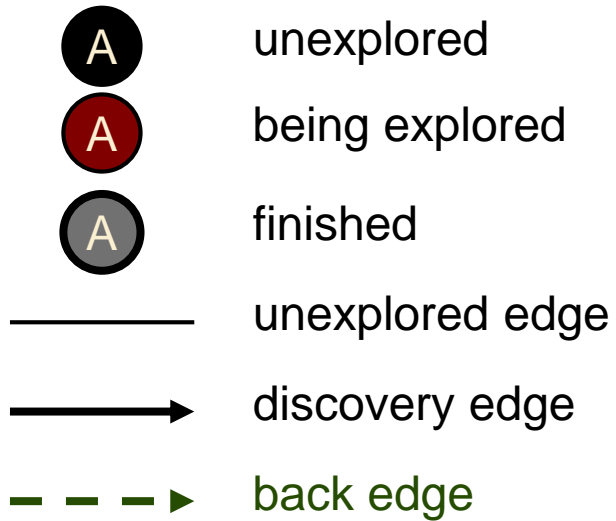


Depth-First Search

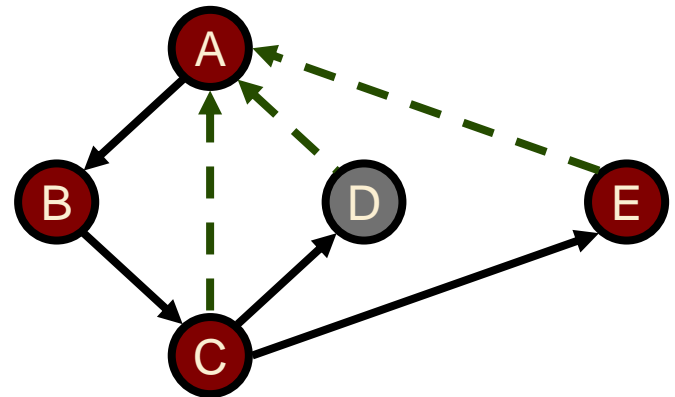
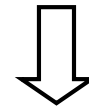
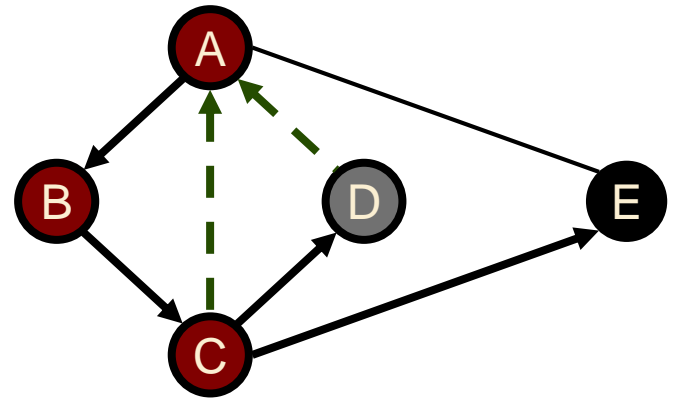
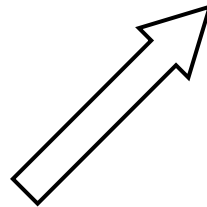
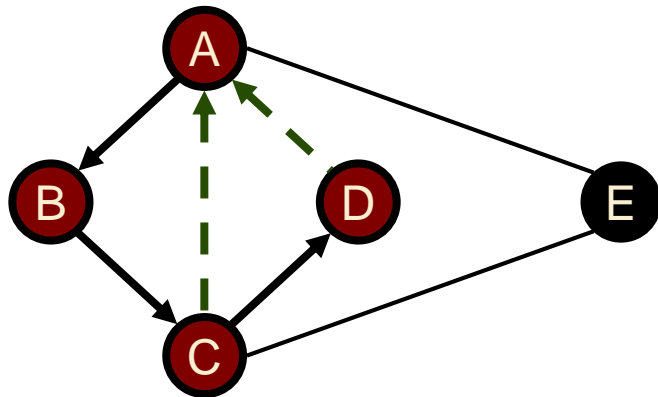
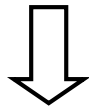
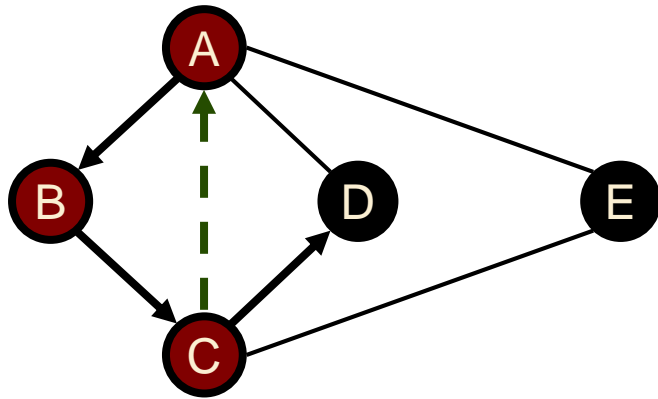
Input: Graph $G = (V, E)$ (directed or undirected)

- Explore *every* edge, starting from different vertices if necessary.
- As soon as vertex discovered, explore from it.
- Keep track of progress by colouring vertices:
 - ❑ Black: undiscovered vertices
 - ❑ Red: discovered, but not finished (still exploring from it)
 - ❑ Gray: finished (found everything reachable from it).

DFS Example on Undirected Graph



Example (cont.)



DFS Algorithm Pattern

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

 color[u] = BLACK //initialize vertex

for each vertex $u \in V[G]$

 if color[u] = BLACK //as yet unexplored

 DFS-Visit(u)



DFS Algorithm Pattern

DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

$\text{colour}[u] \leftarrow \text{RED}$

for each $v \in \text{Adj}[u]$ //explore edge (u,v)

if $\text{color}[v] = \text{BLACK}$

 DFS-Visit(v)

$\text{colour}[u] \leftarrow \text{GRAY}$



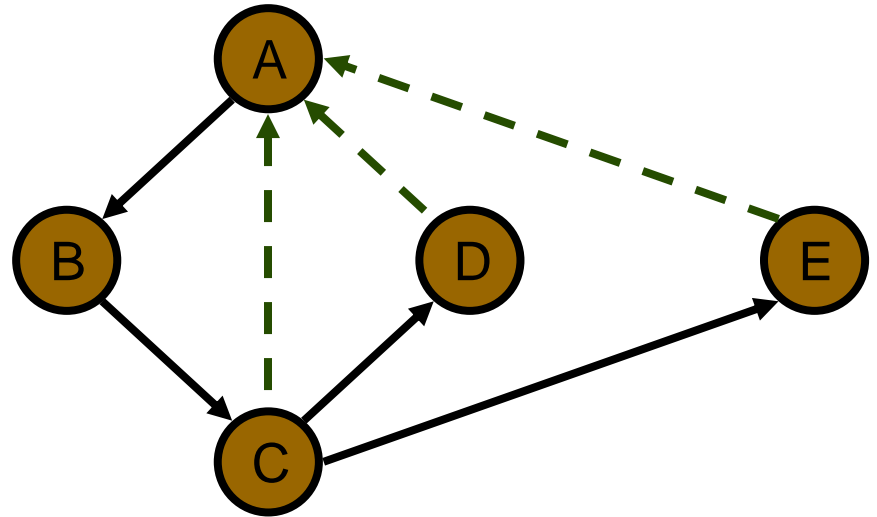
Properties of DFS

Property 1

DFS-Visit(u) visits all the vertices and edges in the connected component of u

Property 2

The discovery edges labeled by *DFS-Visit*(u) form a spanning tree of the connected component of u



DFS Algorithm Pattern

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

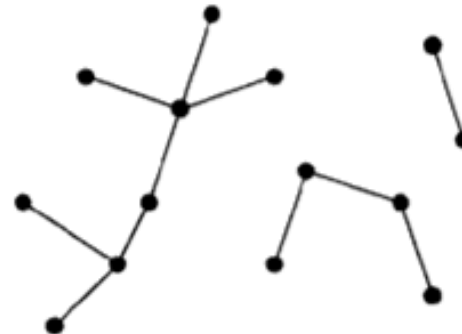
 color[u] = BLACK //initialize vertex

for each vertex $u \in V[G]$

 if color[u] = BLACK //as yet unexplored

 DFS-Visit(u)

} total work
= $O(V)$



DFS Algorithm Pattern

DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

$\text{colour}[u] \leftarrow \text{RED}$

for each $v \in \text{Adj}[u]$ //explore edge (u,v)

if $\text{color}[v] = \text{BLACK}$

DFS-Visit(v)

$\text{colour}[u] \leftarrow \text{GRAY}$

} total work
= $\sum_{v \in V} |\text{Adj}[v]| = q(E)$



Thus running time = $q(V + E)$

(assuming adjacency list structure)

Variants of Depth-First Search

- In addition to, or instead of labeling vertices with colours, they can be labeled with **discovery** and **finishing** times.
- 'Time' is an integer that is incremented whenever a vertex changes state
 - ❑ from **unexplored** to **discovered**
 - ❑ from **discovered** to **finished**
- These **discovery** and **finishing** times can then be used to solve other graph problems (e.g., computing strongly-connected components)

Input: Graph $G = (V, E)$ (directed or undirected)

Output: 2 timestamps on each vertex:

$d[v]$ = discovery time.

$f[v]$ = finishing time.

$$1 \leq d[v] < f[v] \leq 2|V|$$

DFS Algorithm with Discovery and Finish Times

DFS(G)

Precondition: G is a graph

Postcondition: all vertices in G have been visited

for each vertex $u \in V[G]$

```
color[u] = BLACK //initialize vertex
```

time $\neg 0$

for each vertex $u \in V[G]$

```
if color[u] = BLACK //as yet unexplored
```

DFS-Visit(u)



DFS Algorithm with Discovery and Finish Times

DFS-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: all vertices reachable from u have been processed

colour[u] \leftarrow RED

time \leftarrow time + 1

d[u] \leftarrow time

for each $v \in \text{Adj}[u]$ //explore edge (u, v)

if color[v] = BLACK

DFS-Visit(v)

colour[u] \leftarrow GRAY

time \leftarrow time + 1

f[u] \leftarrow time



Other Variants of Depth-First Search

➤ The DFS Pattern can also be used to

- ❑ Compute a forest of spanning trees (one for each call to DFS-visit) encoded in a predecessor list $\pi[u]$

- ❑ Label edges in the graph according to their role in the search (see textbook)

 - ✧ **Tree edges**, traversed to an undiscovered vertex

 - ✧ **Forward edges**, traversed to a descendent vertex on the current spanning tree

 - ✧ **Back edges**, traversed to an ancestor vertex on the current spanning tree

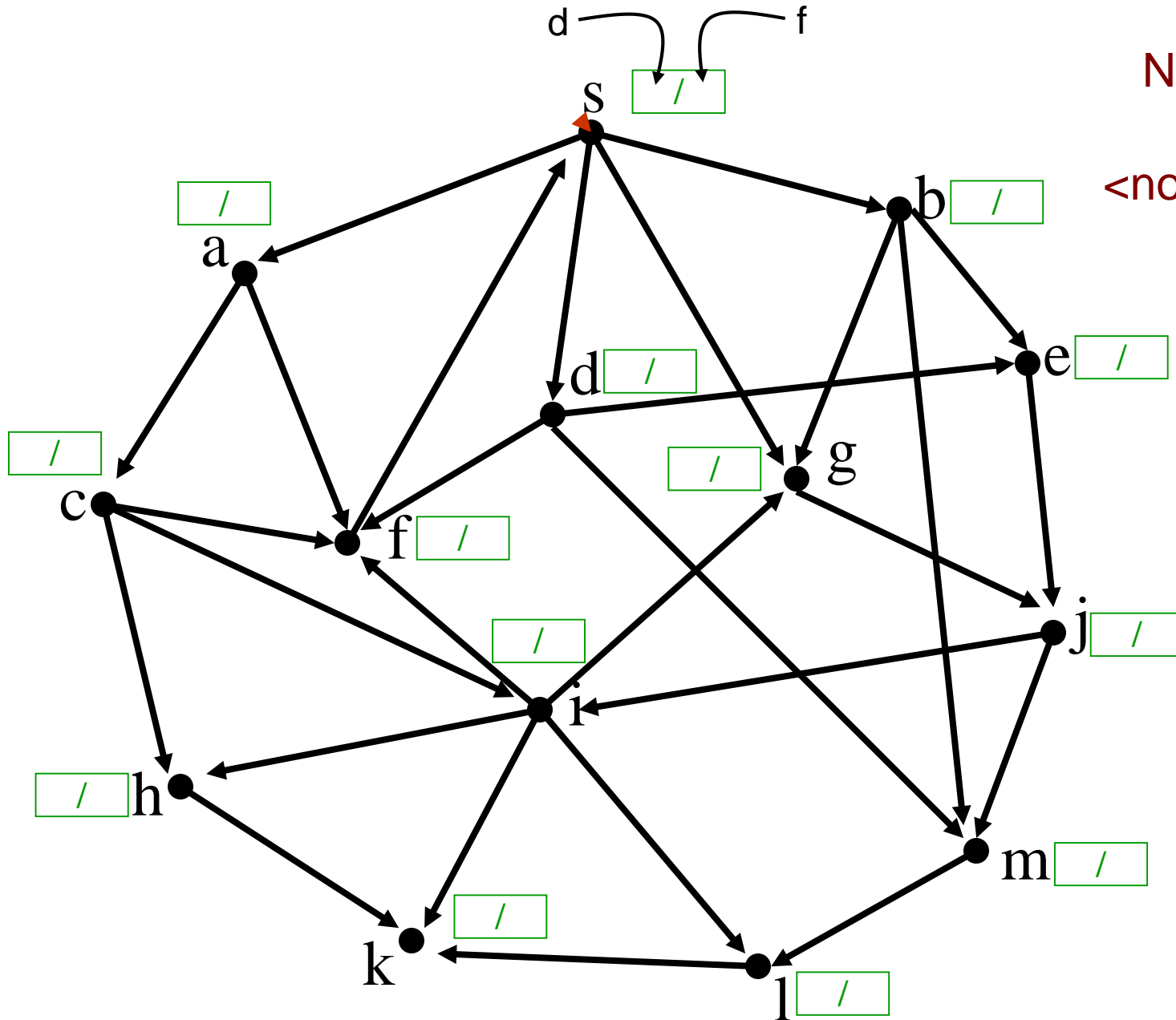
 - ✧ **Cross edges**, traversed to a vertex that has already been discovered, but is not an ancestor or a descendent

Outline

- DFS Algorithm
- **DFS Example**
- DFS Applications

DFS

Note: Stack is Last-In First-Out (LIFO)



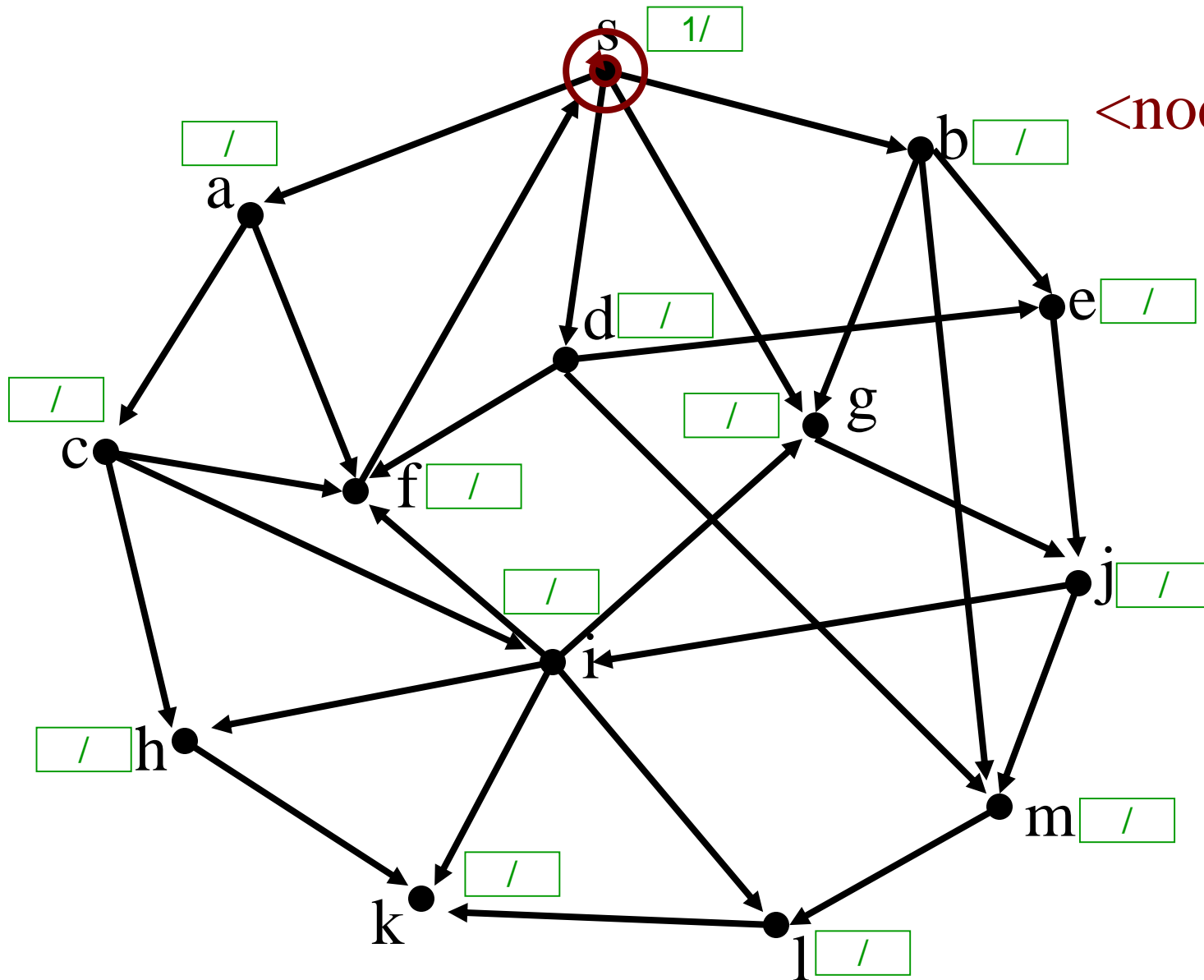
Found
Not Handled
Stack
<node,# edges>



DFS

Found
Not Handled
Stack

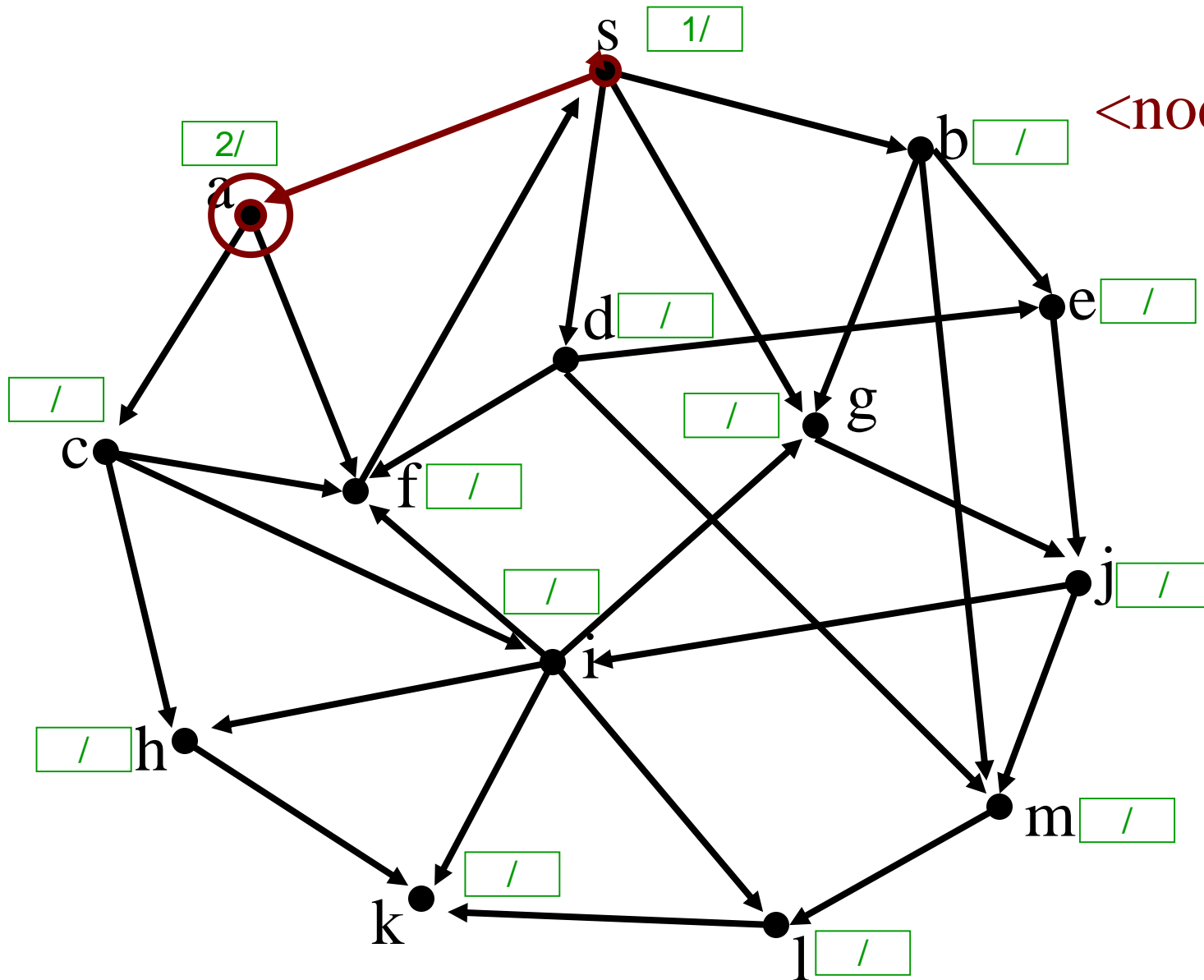
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

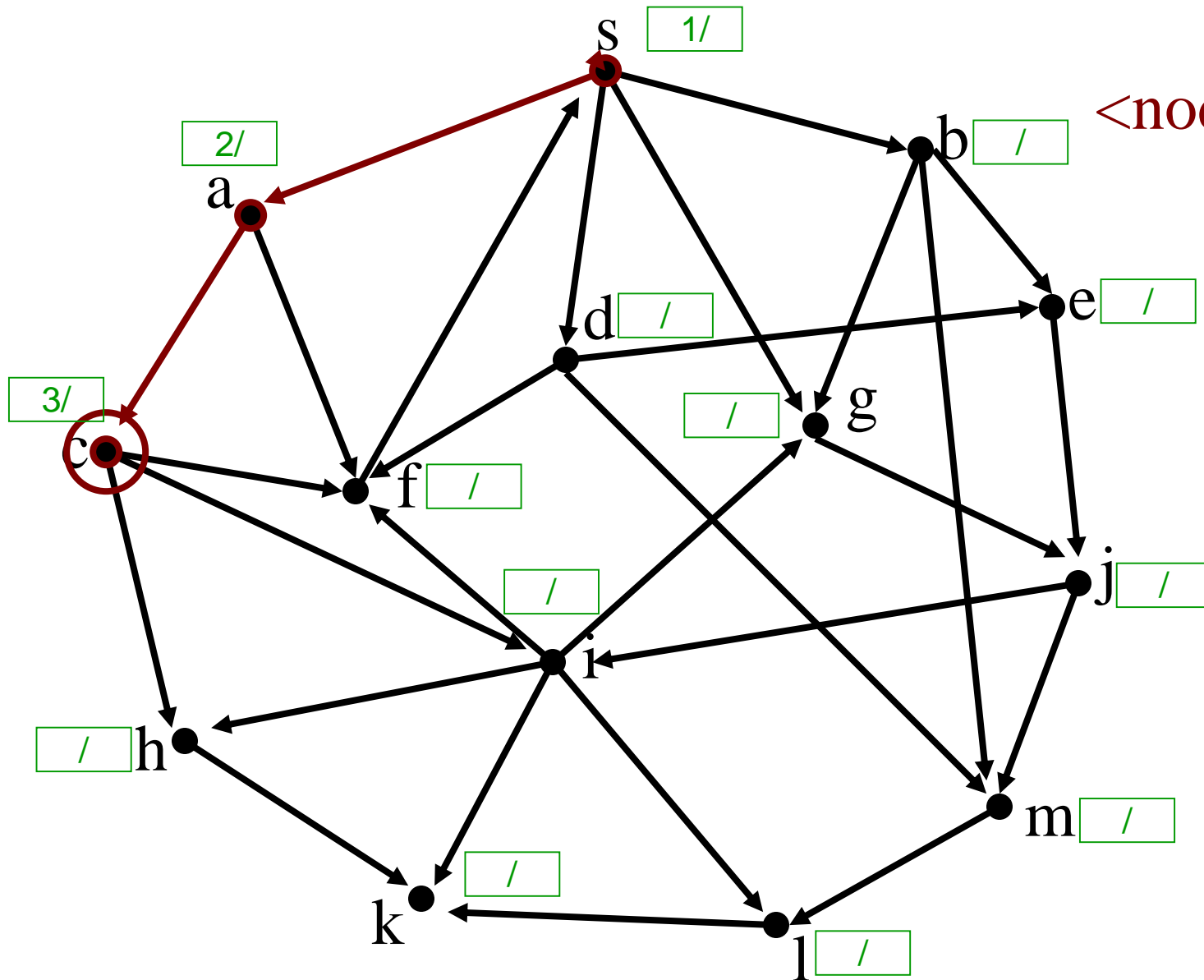


a,0
s,1

DFS

Found Not Handled Stack

<node,# edges>

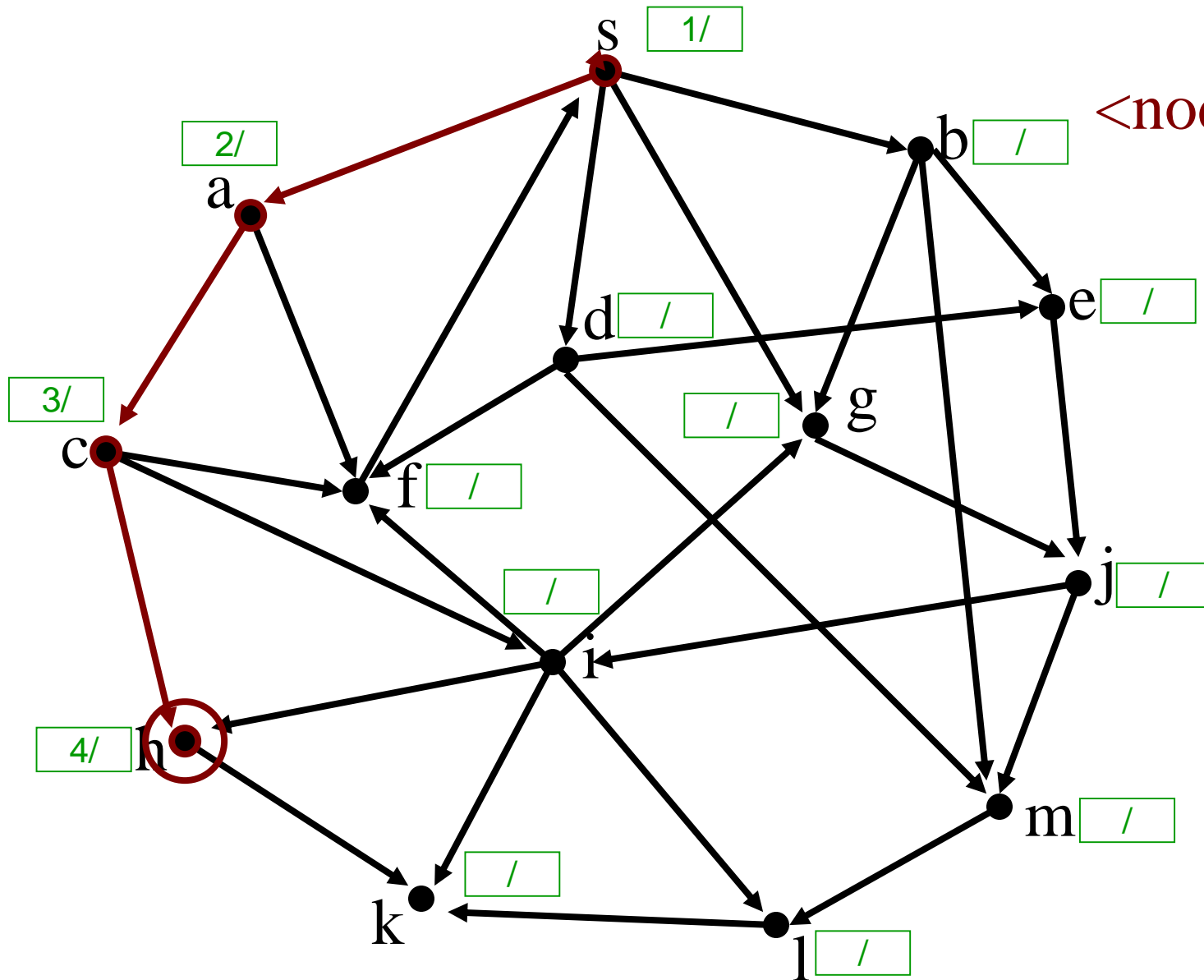


c,0
a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

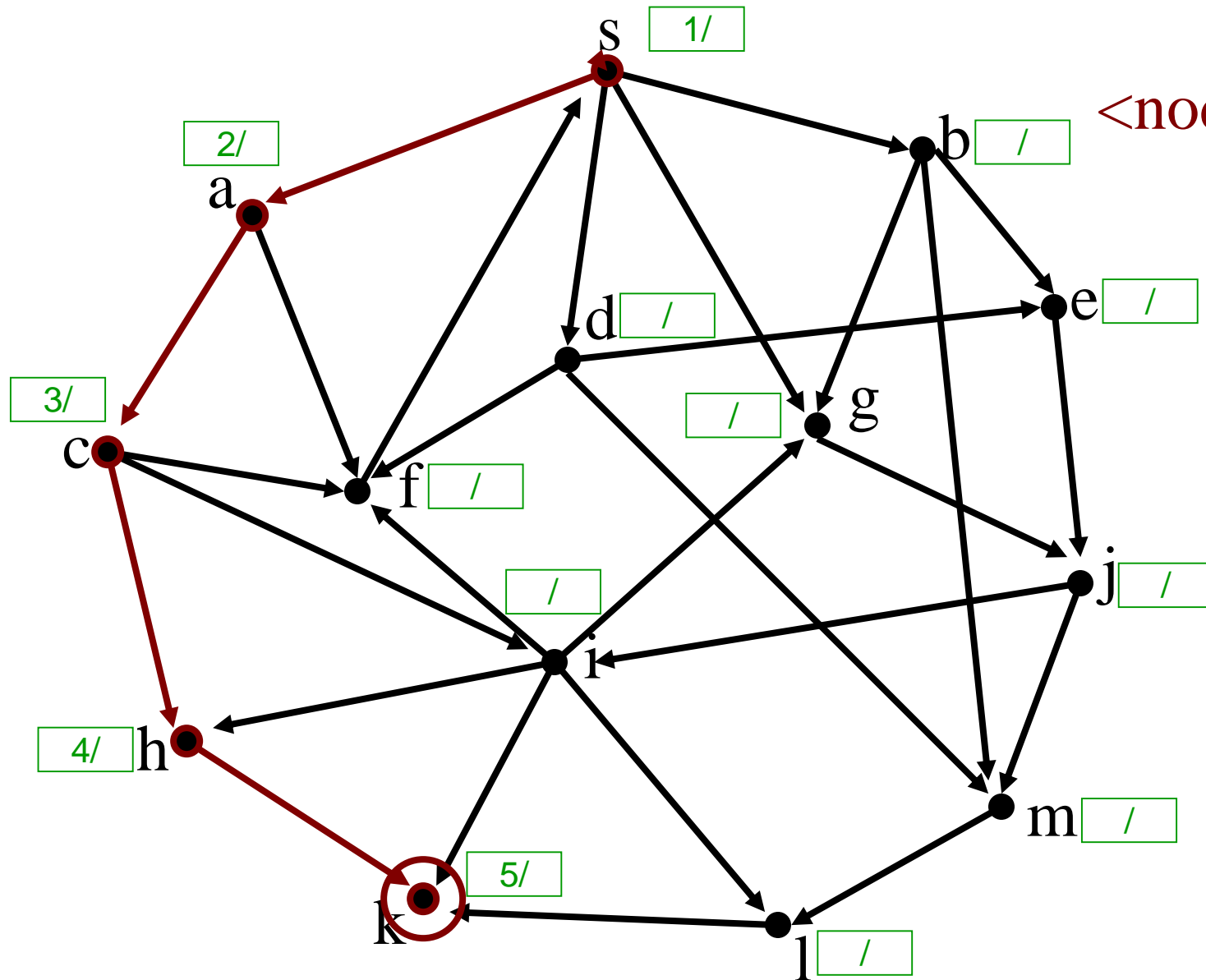


h,0
c,1
a,1
s,1

DFS

Found Not Handled Stack

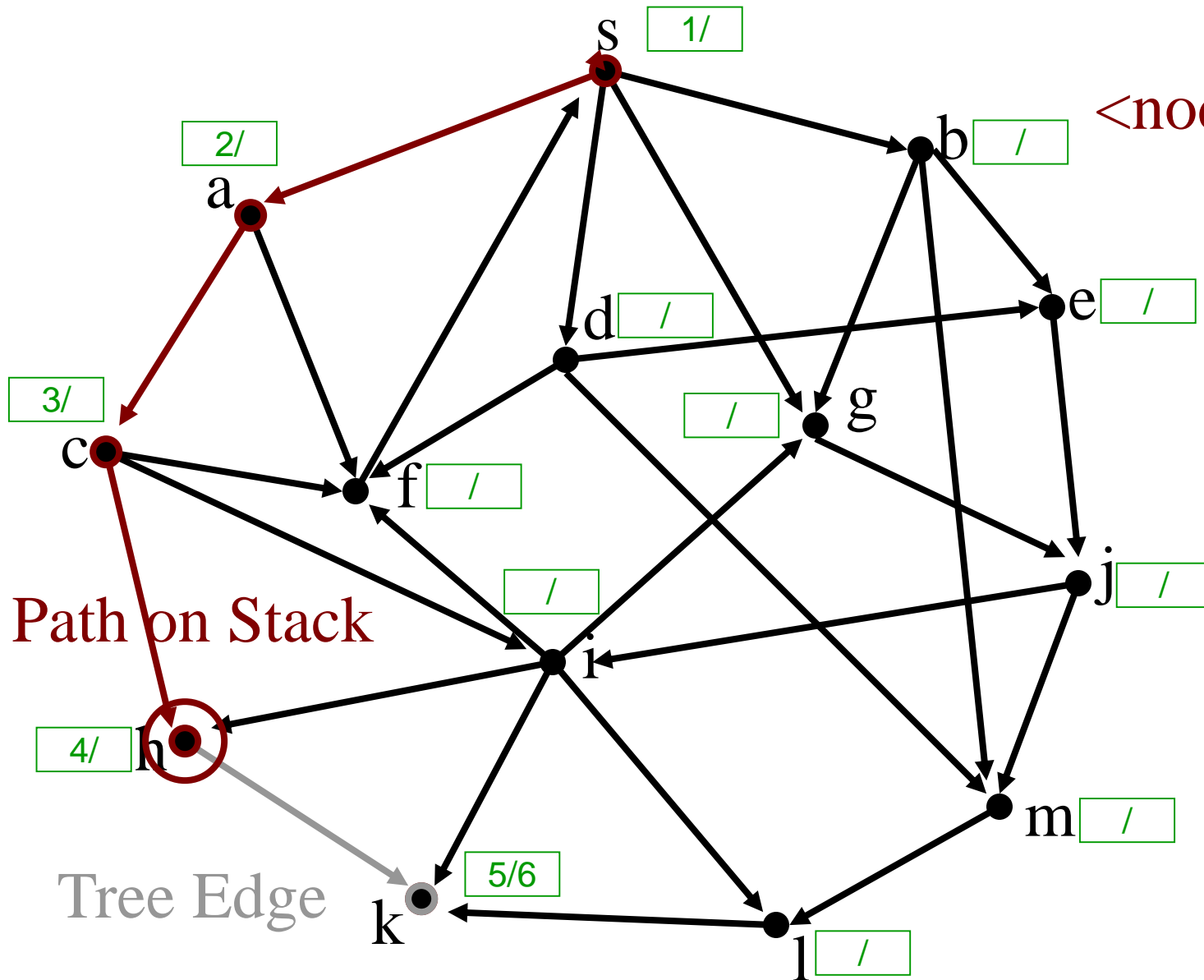
<node,# edges>



DFS

Found
Not Handled
Stack

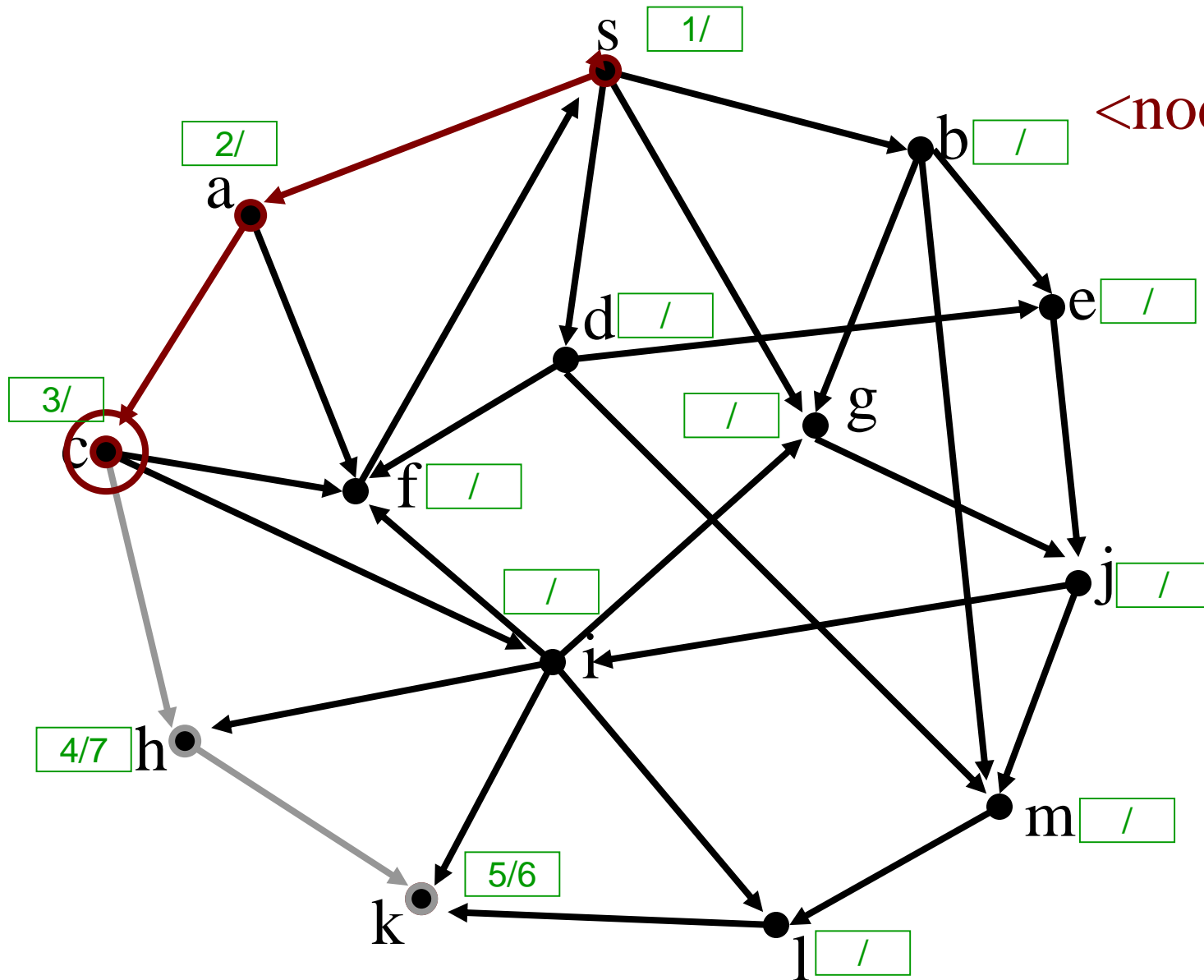
<node,# edges>



DFS

Found Not Handled Stack

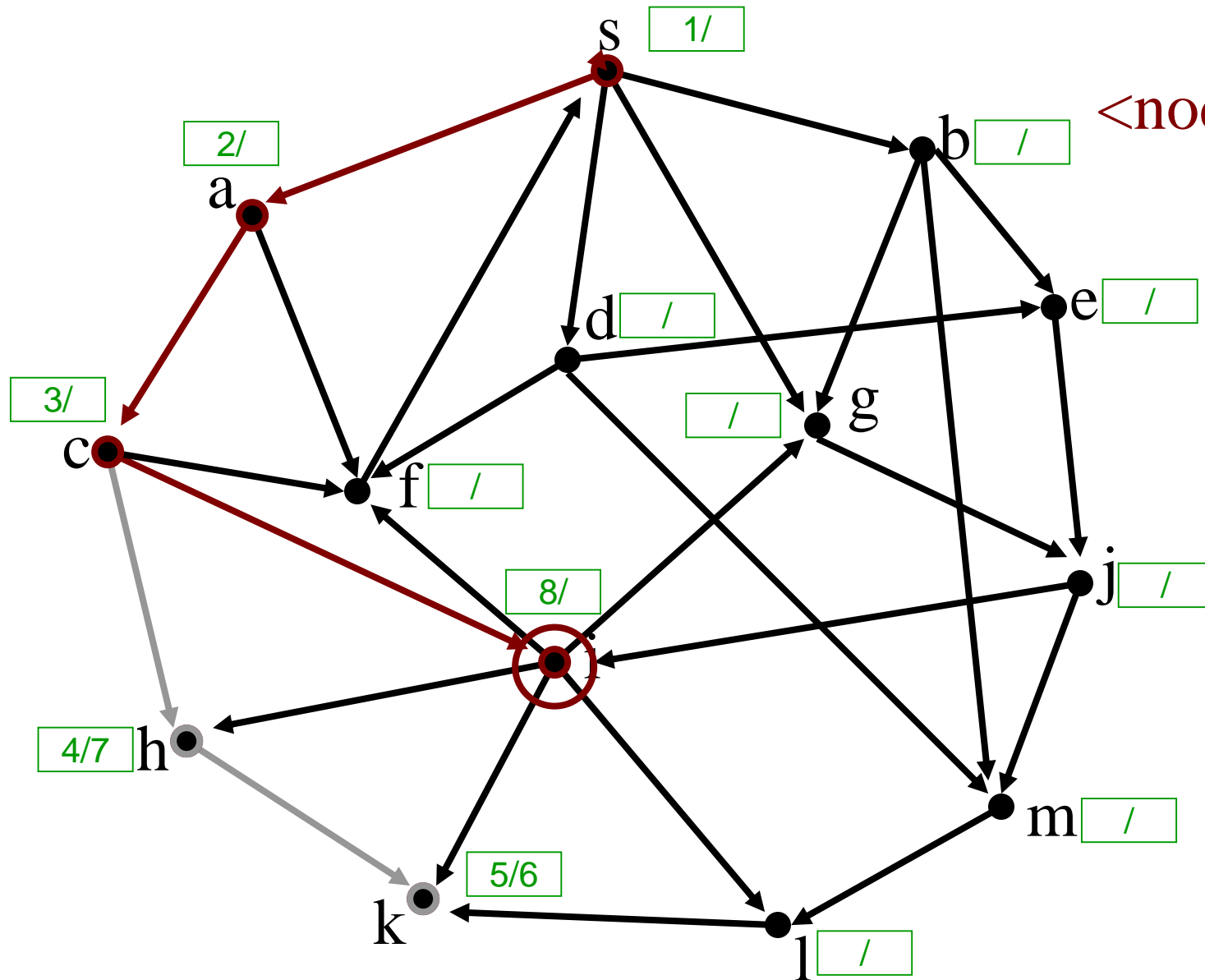
<node,# edges>



DFS

Found Not Handled Stack

<node,# edges>

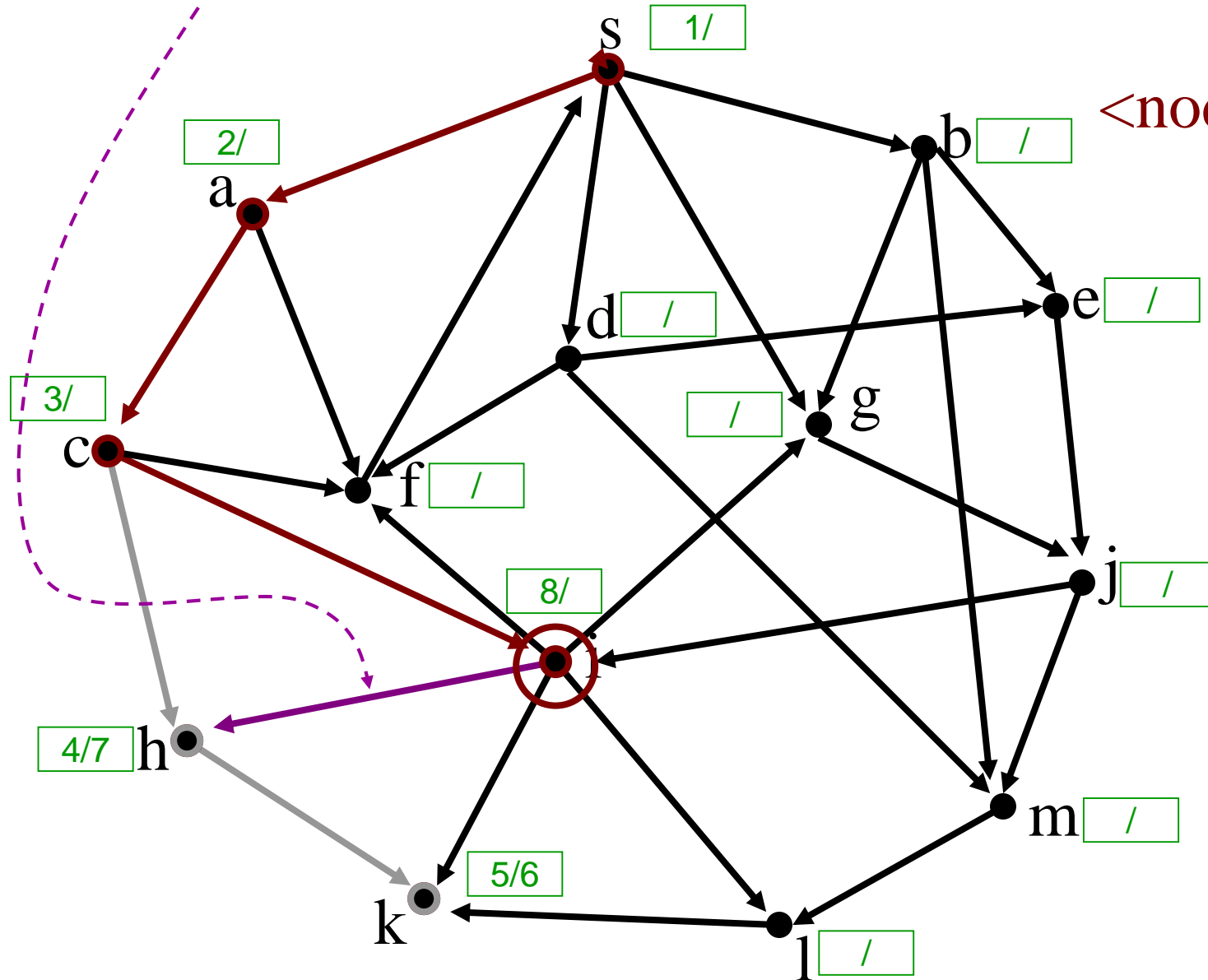


DFS

Found
Not Handled
Stack

<node,# edges>

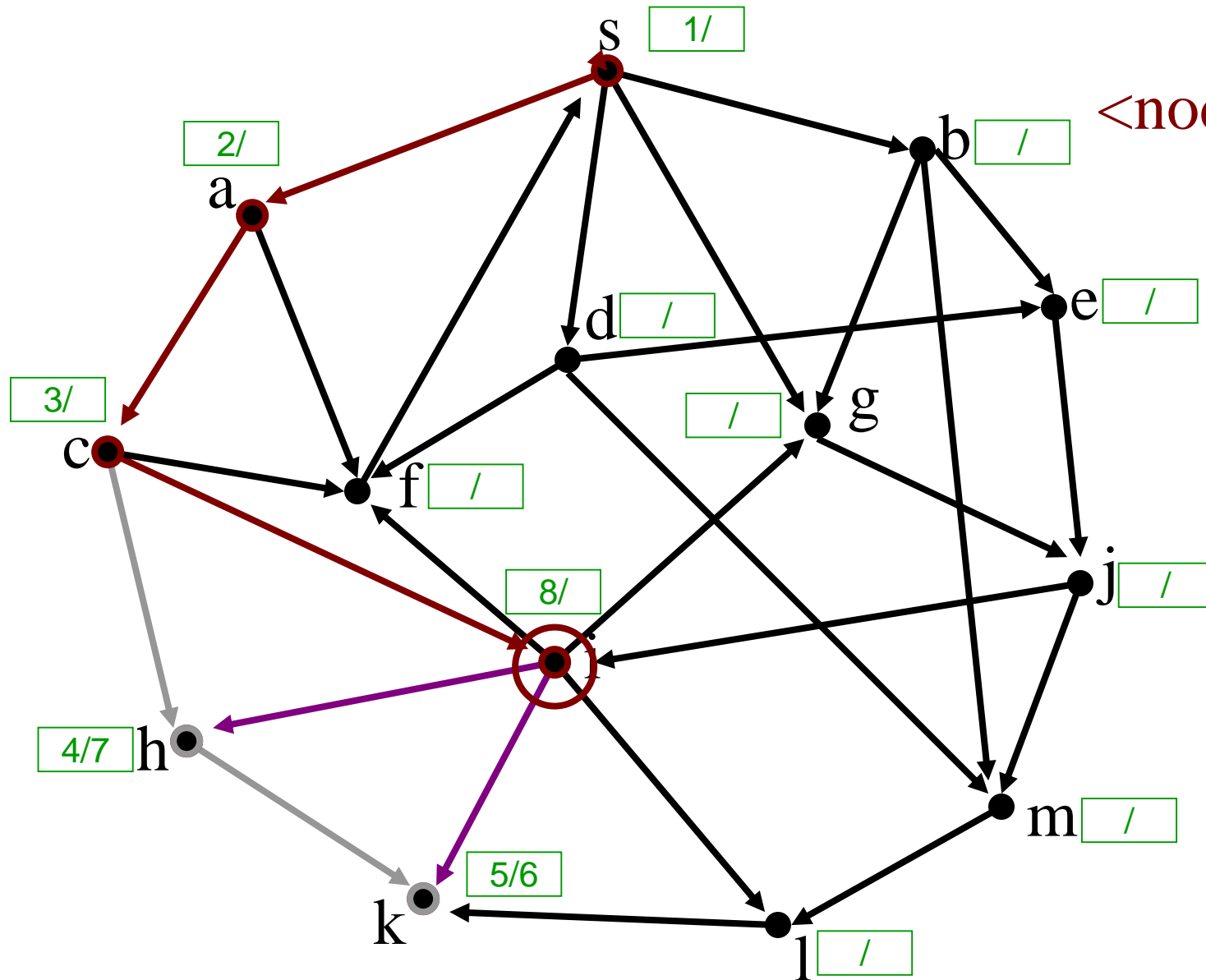
Cross Edge to handled node: $d[h] < d[i]$



DFS

Found Not Handled Stack

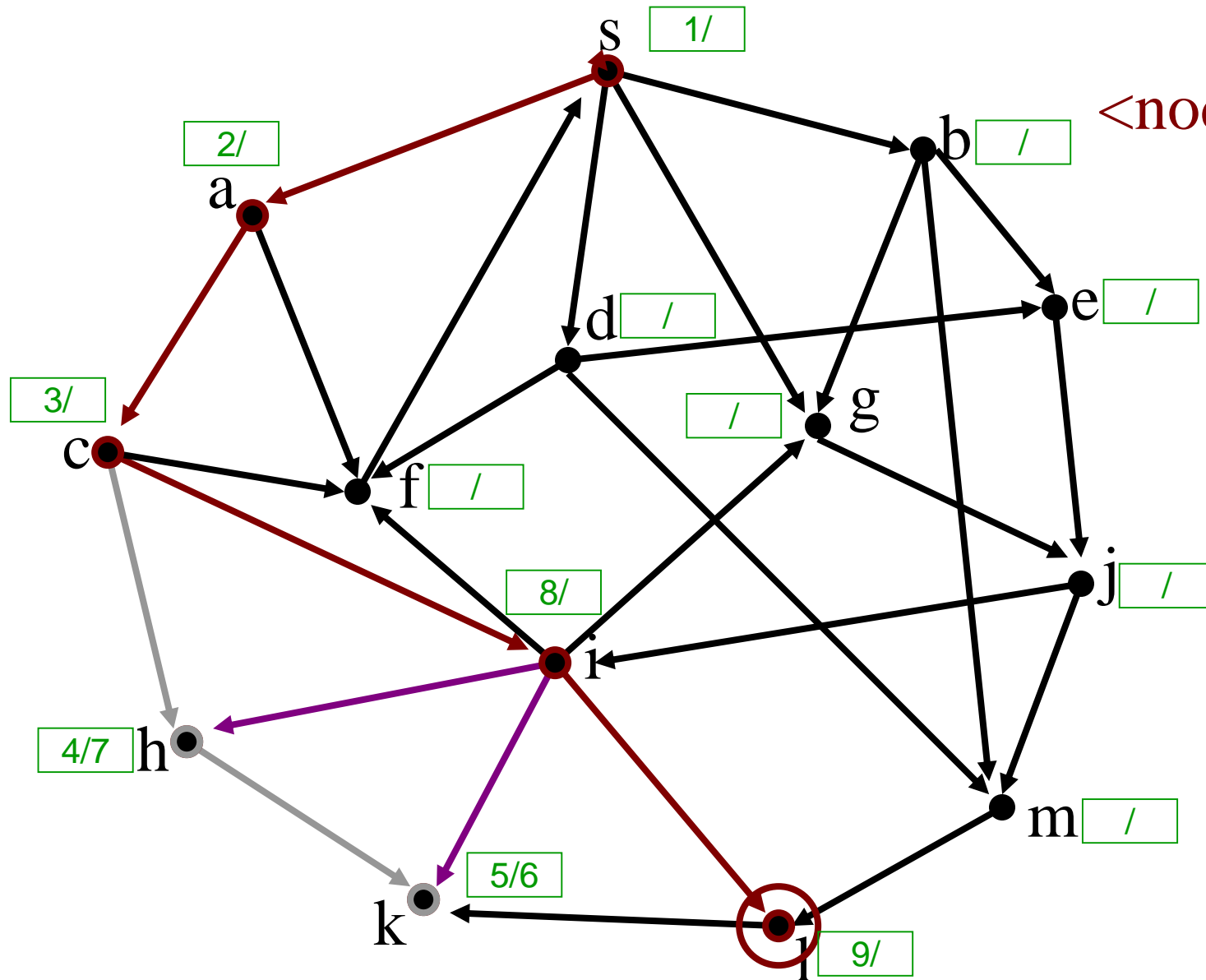
<node,# edges>



DFS

Found Not Handled Stack

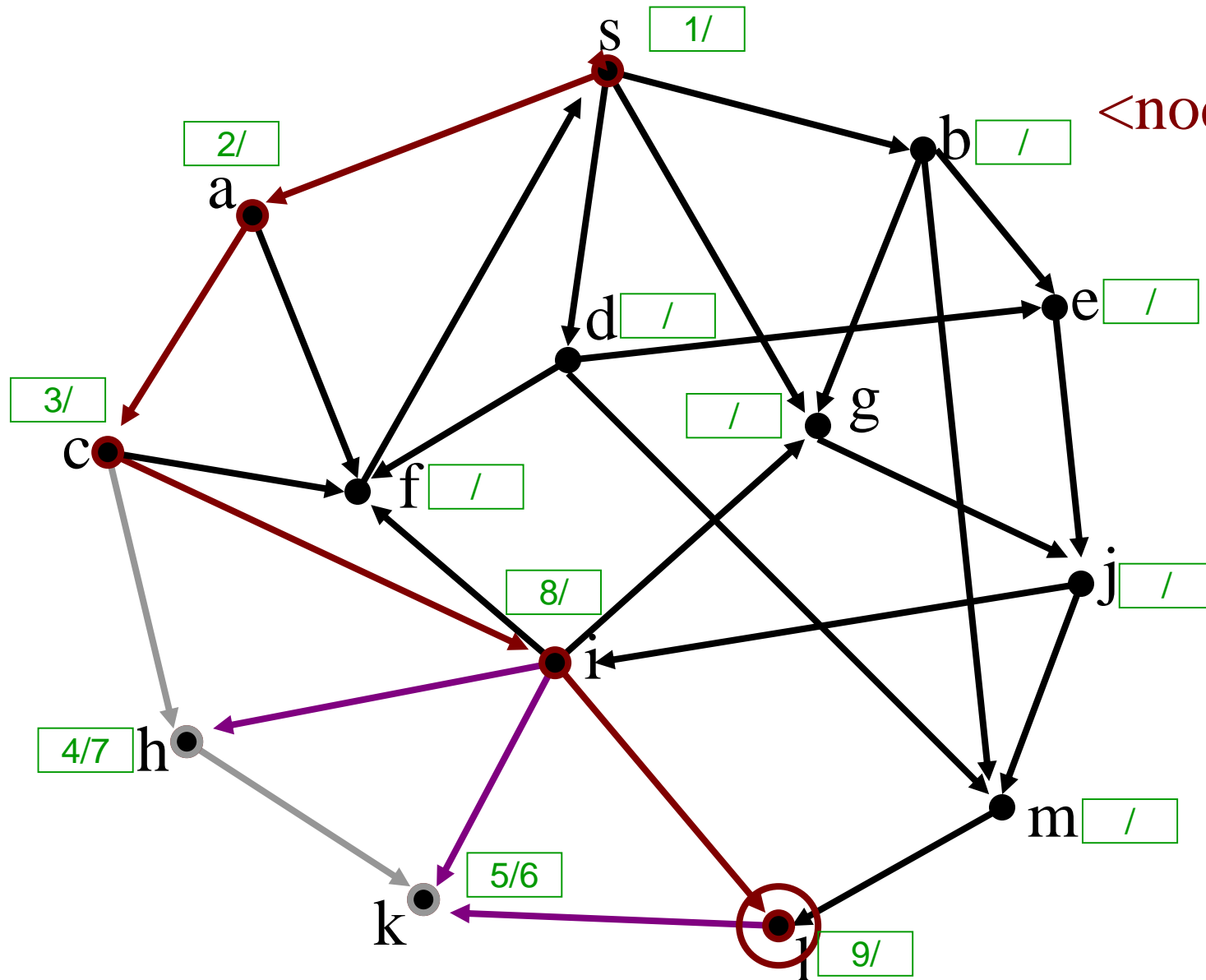
<node,# edges>



DFS

Found Not Handled Stack

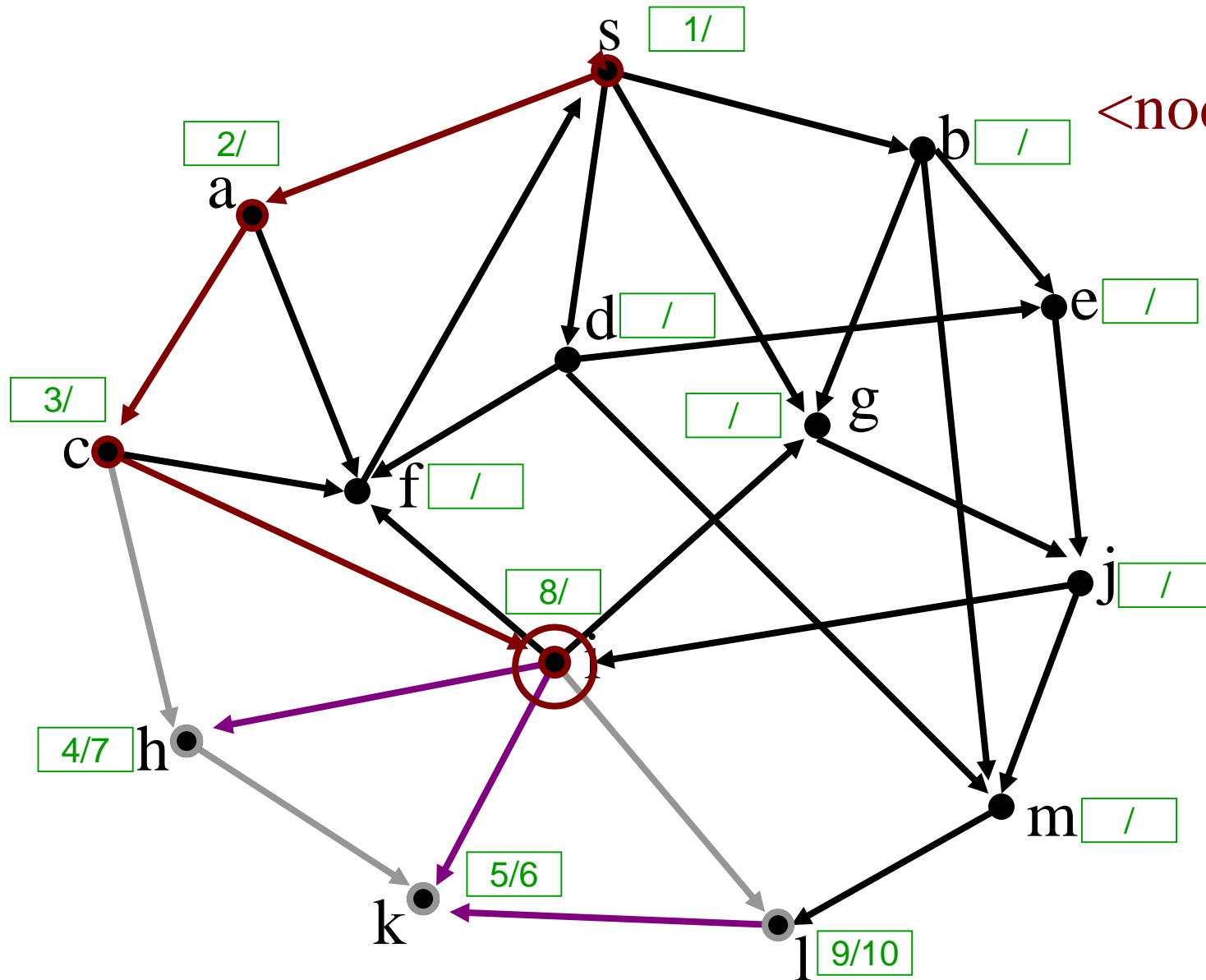
<node,# edges>



DFS

Found Not Handled Stack

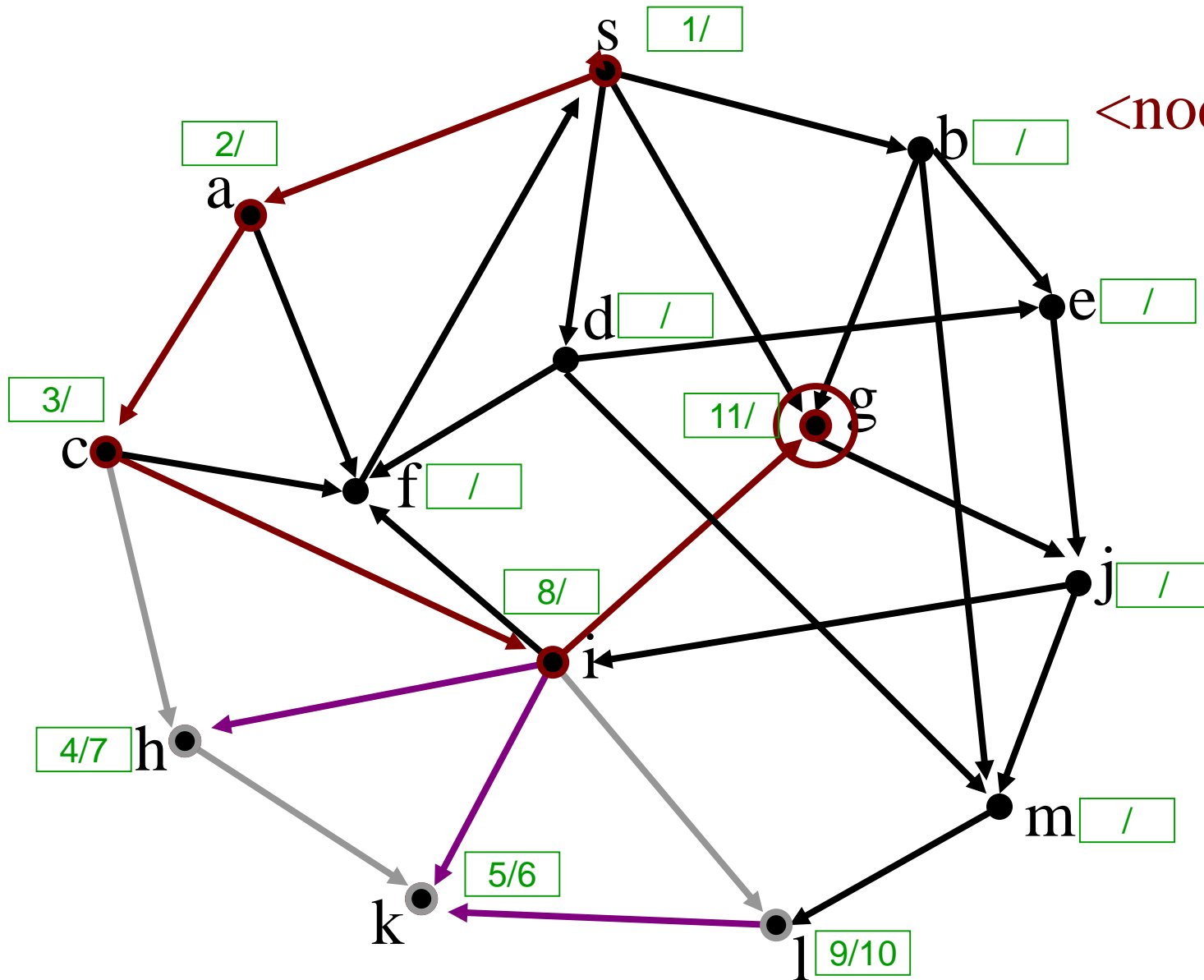
<node,# edges>



DFS

Found Not Handled Stack

<node,# edges>

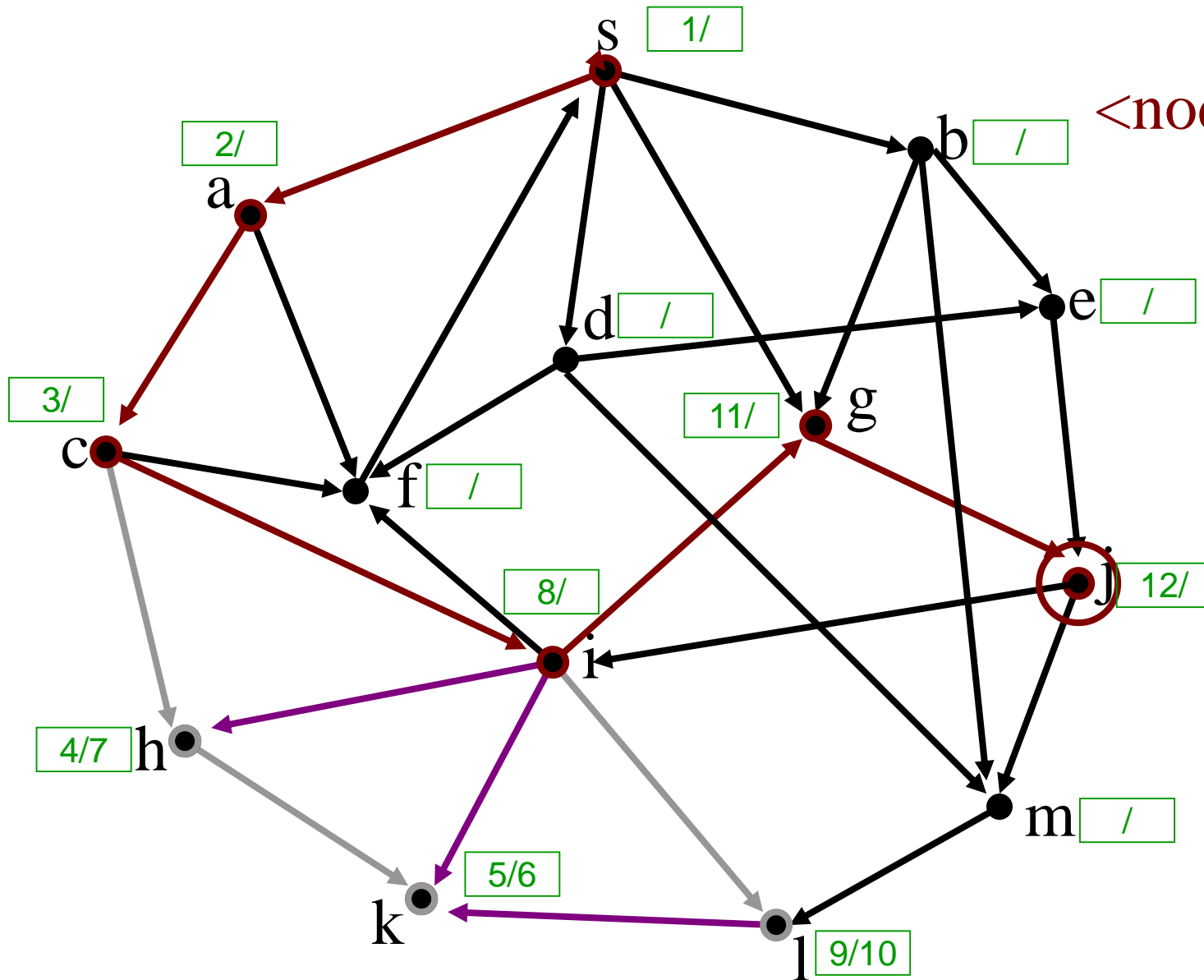


g,0
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>



j,0
g,1
i,4
c,2
a,1
s,1

DFS

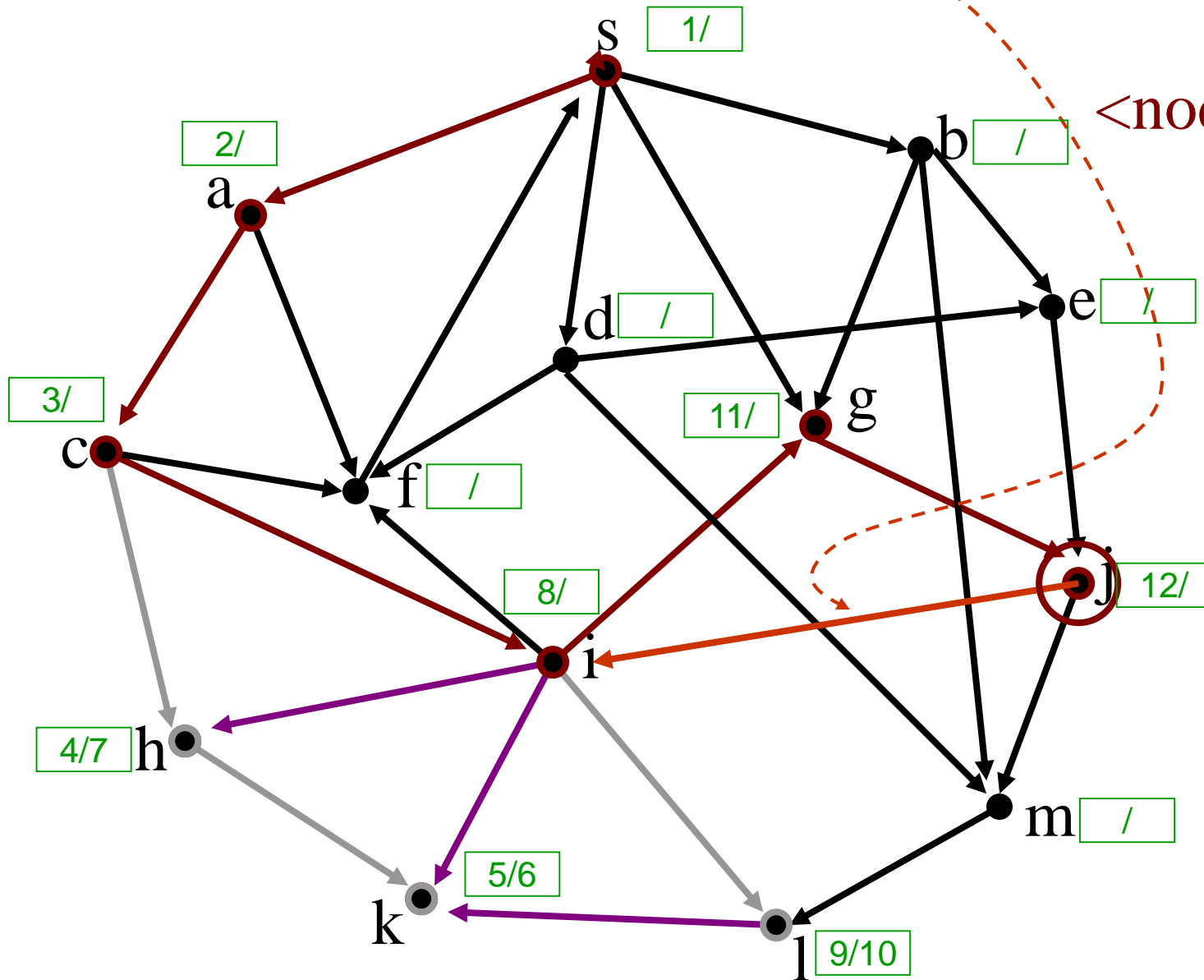
Back Edge to node on Stack:

Found

Not Handled

Stack

<node,# edges>

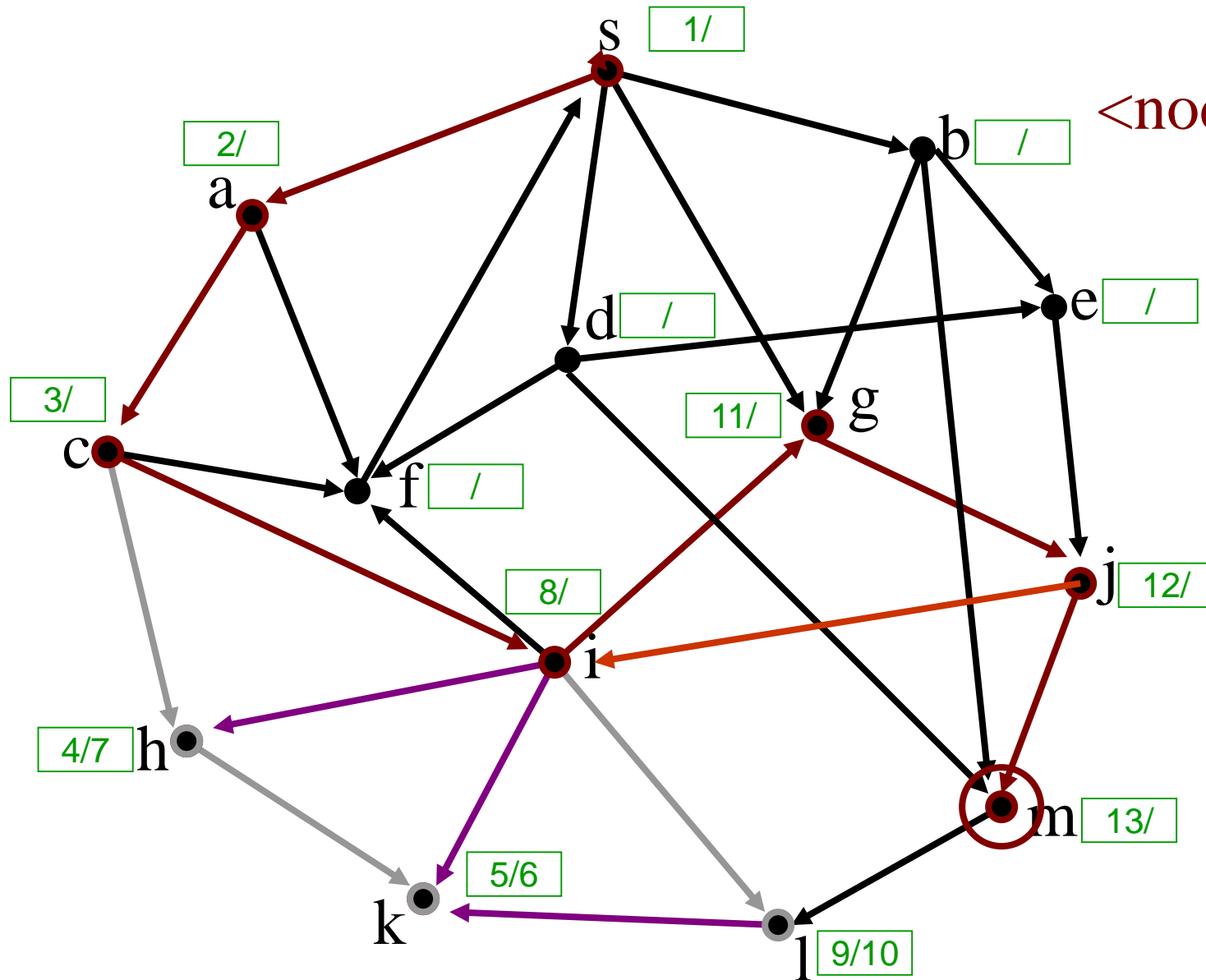


j,1
g,1
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>

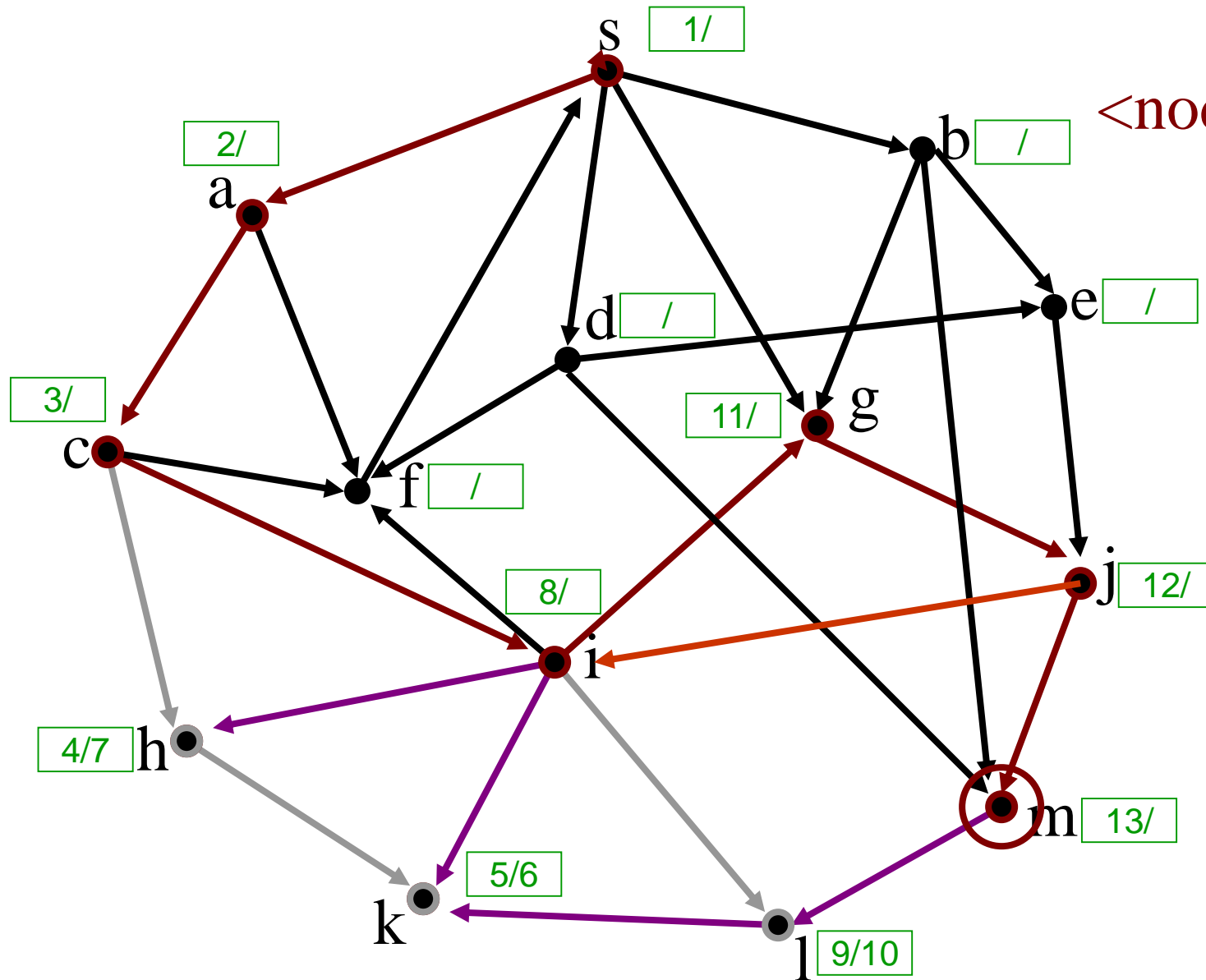


m,0
j,2
g,1
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

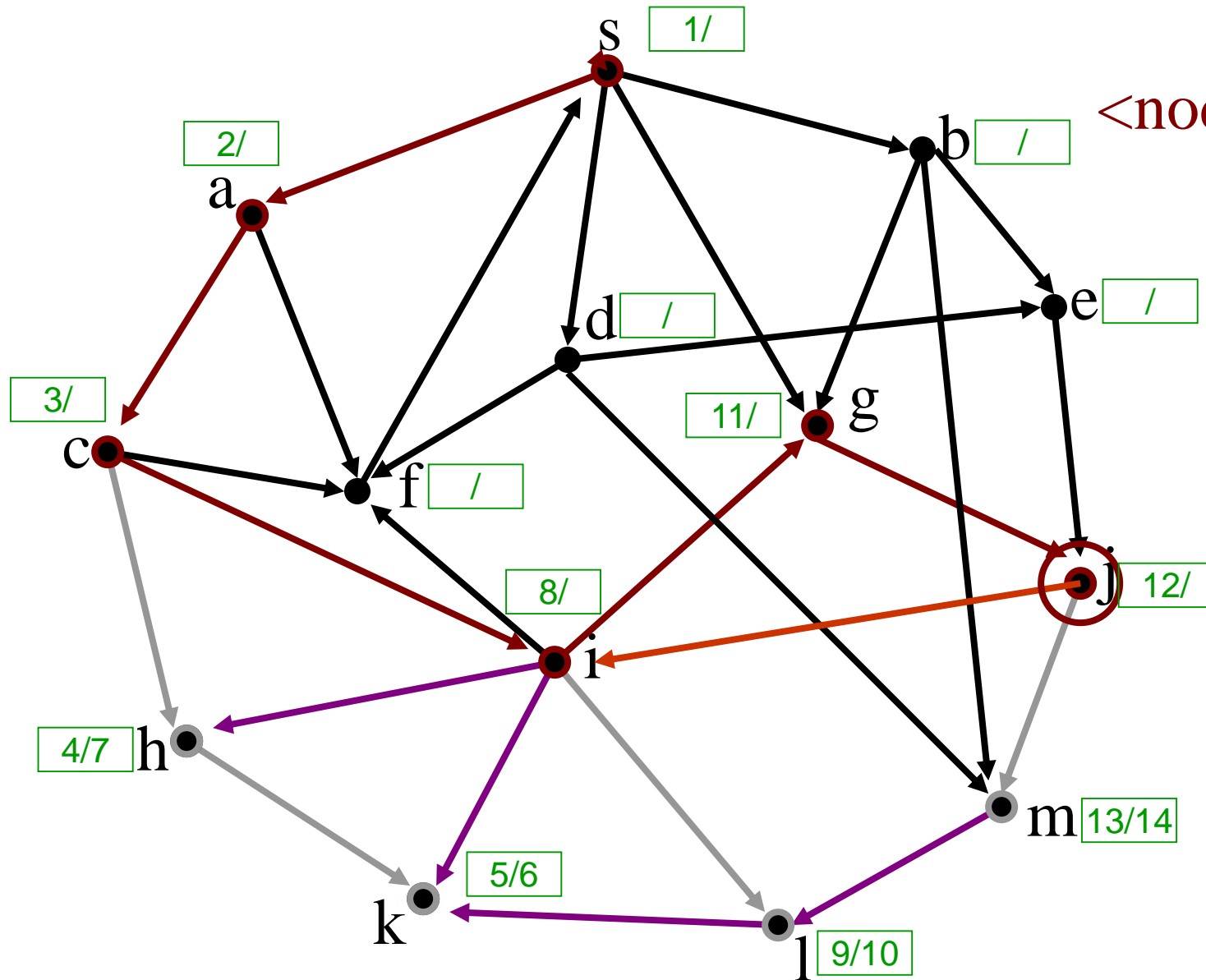
<node,# edges>



DFS

Found Not Handled Stack

<node,# edges>

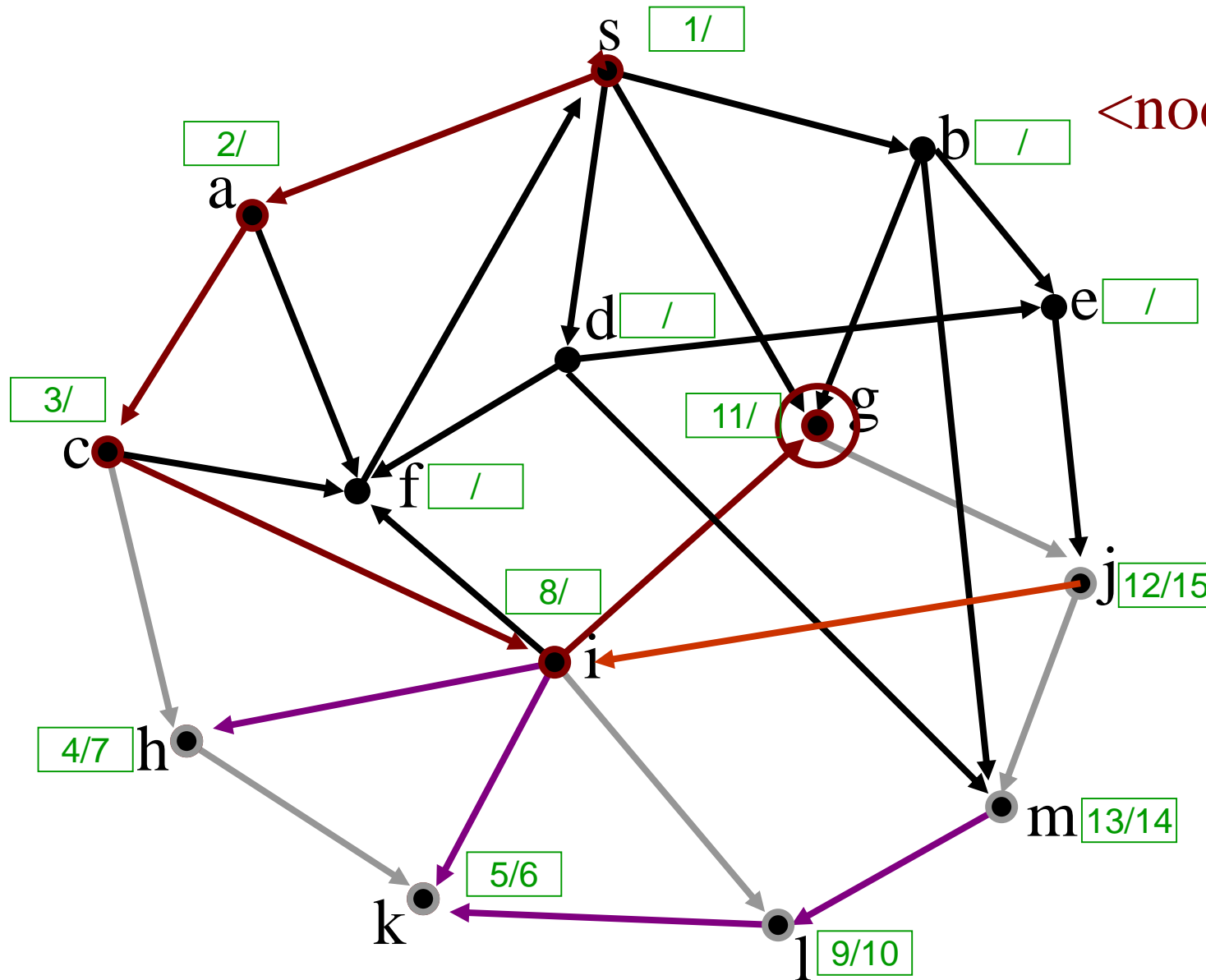


j,2
g,1
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>

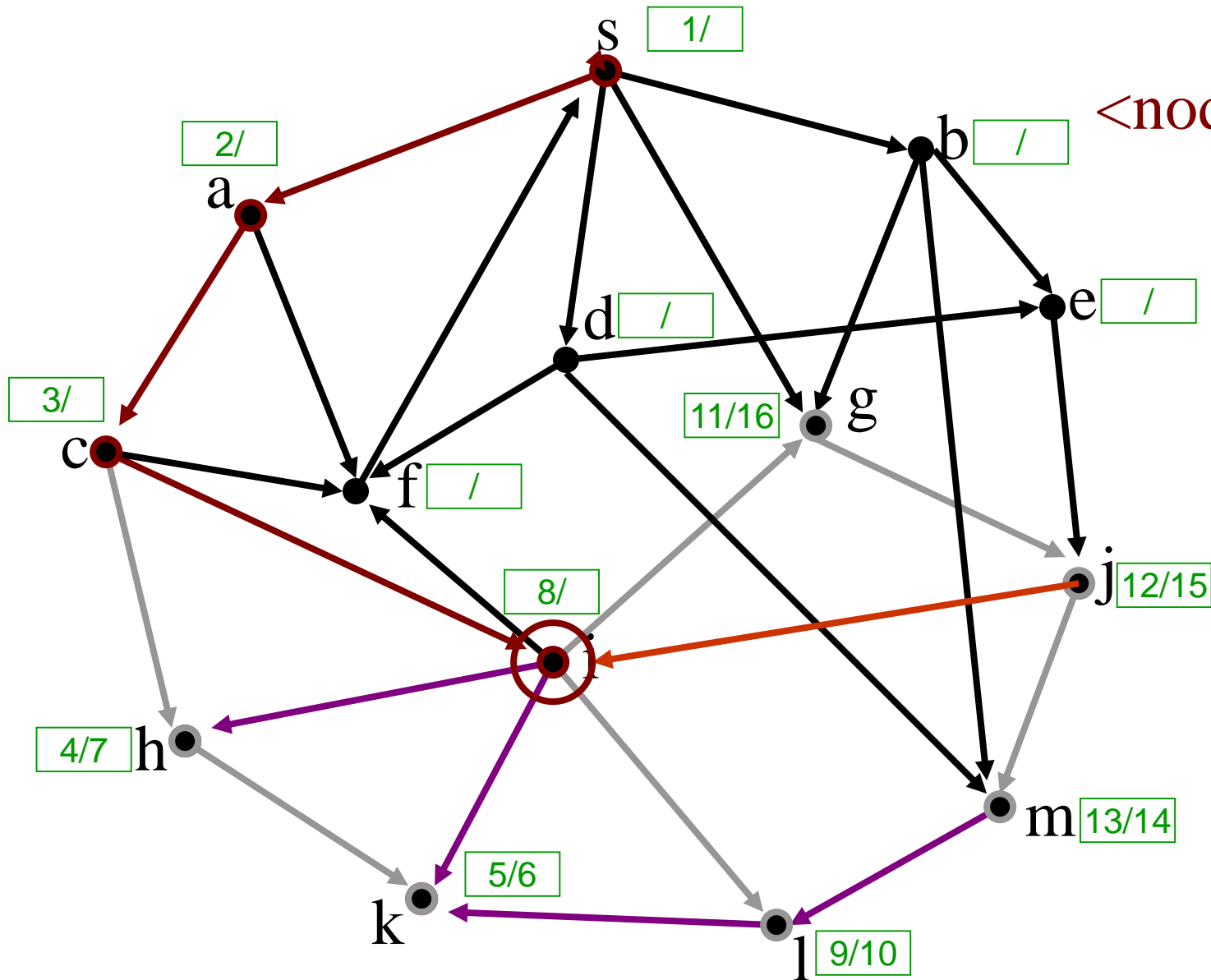


g,1
i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

<node,# edges>

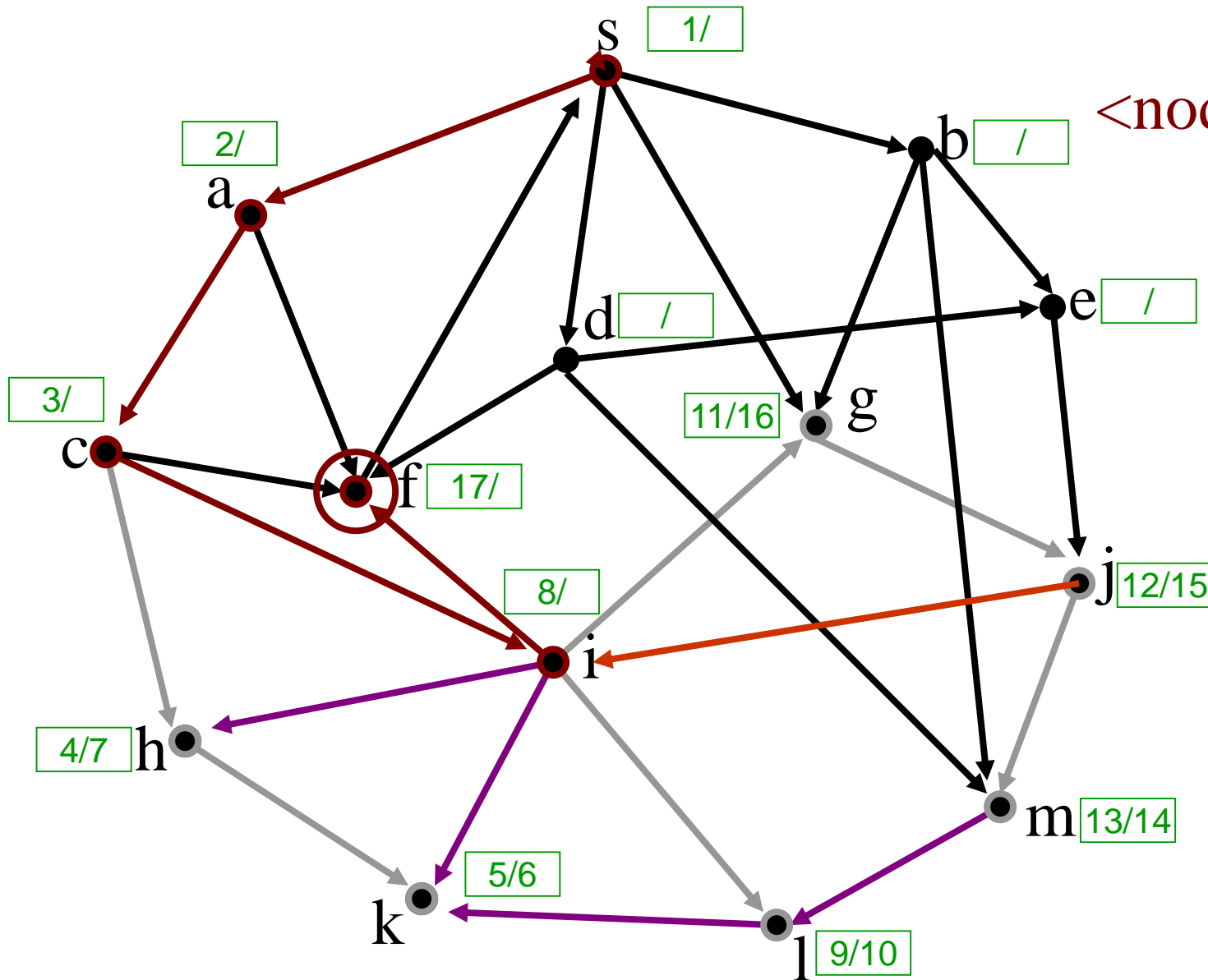


i,4
c,2
a,1
s,1

DFS

Found Not Handled Stack

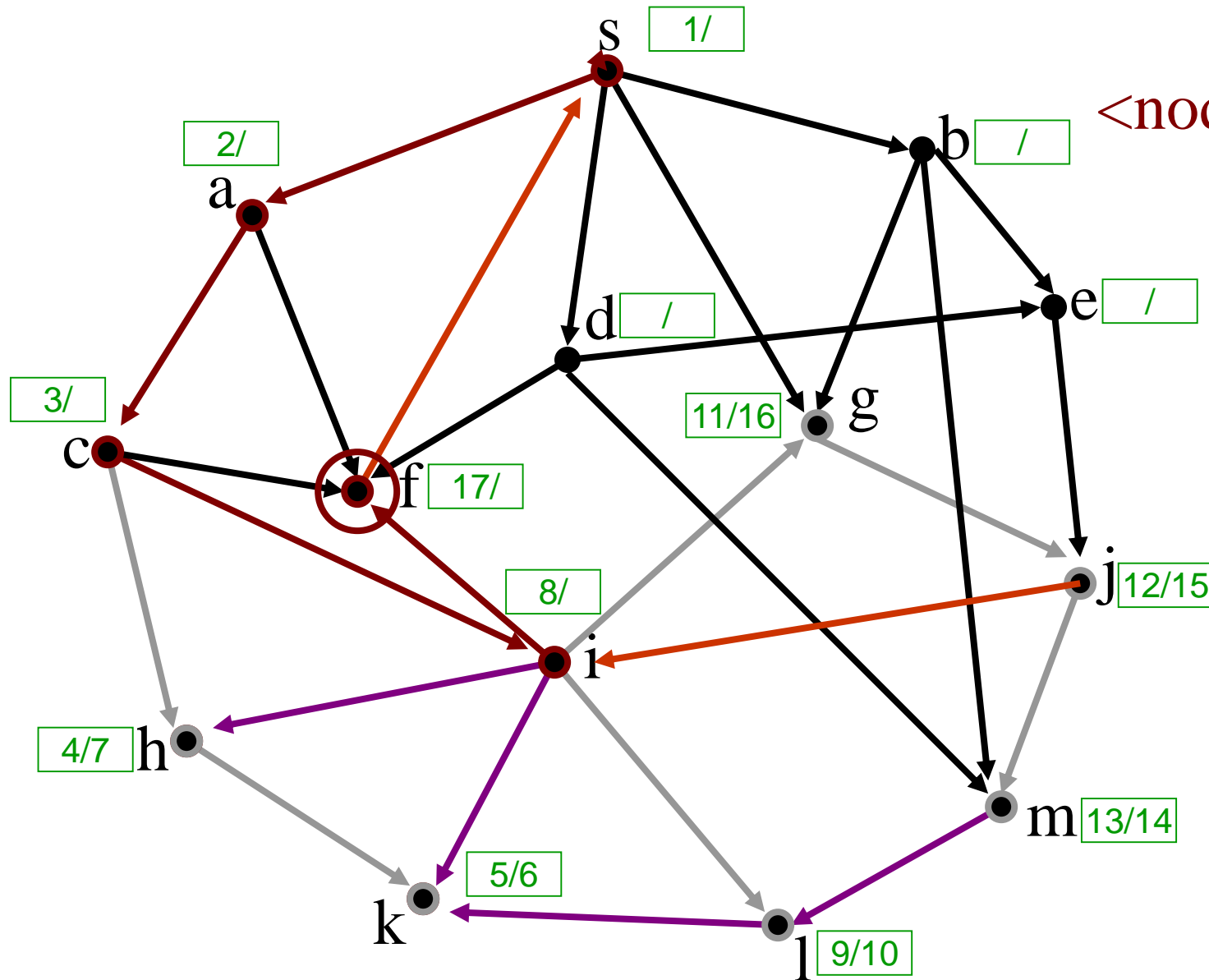
<node,# edges>



DFS

Found Not Handled Stack

<node,# edges>

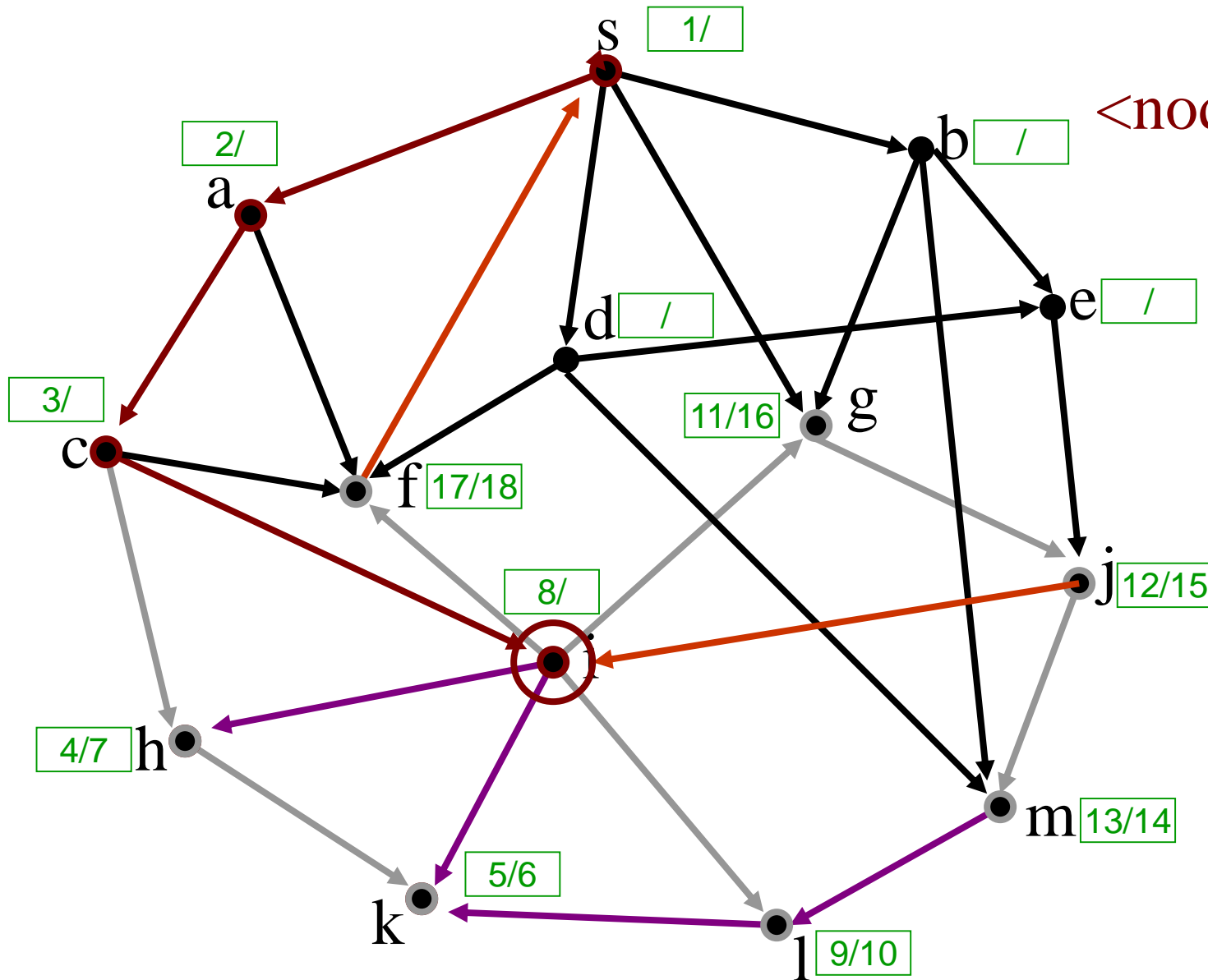


f,1
i,5
c,2
a,1
s,1

DFS

Found Not Handled Stack

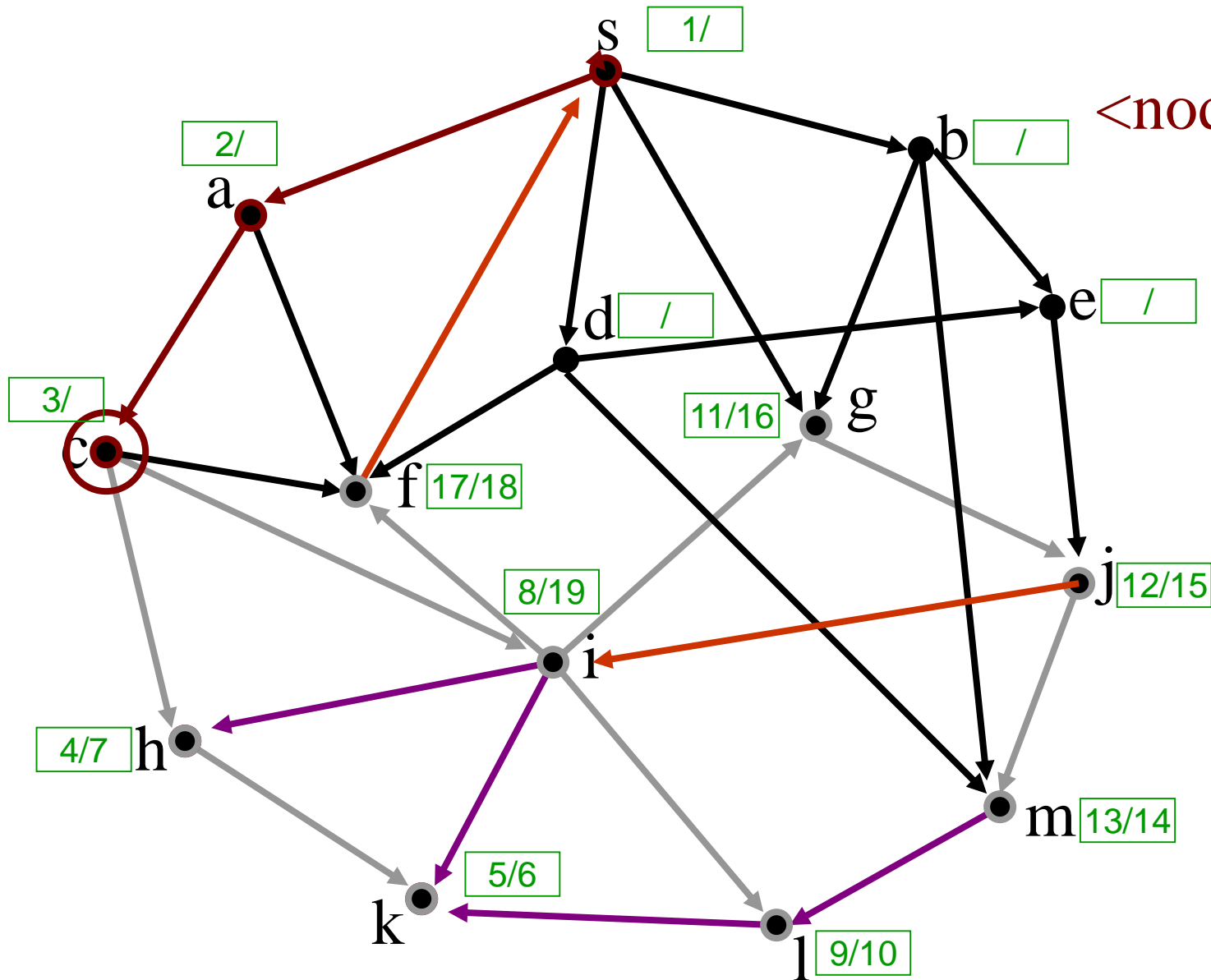
<node,# edges>



DFS

Found Not Handled Stack

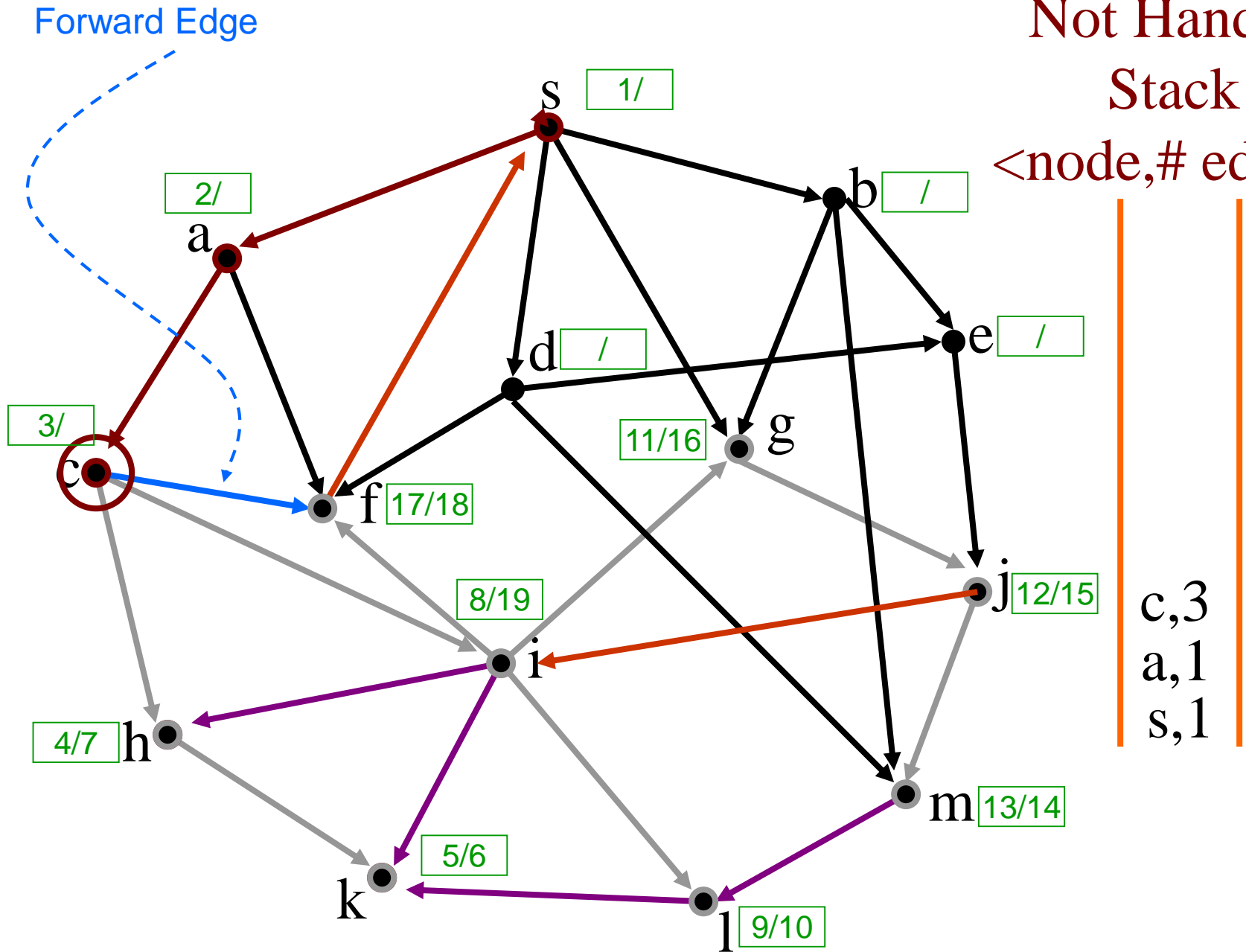
<node,# edges>



DFS

Found Not Handled Stack

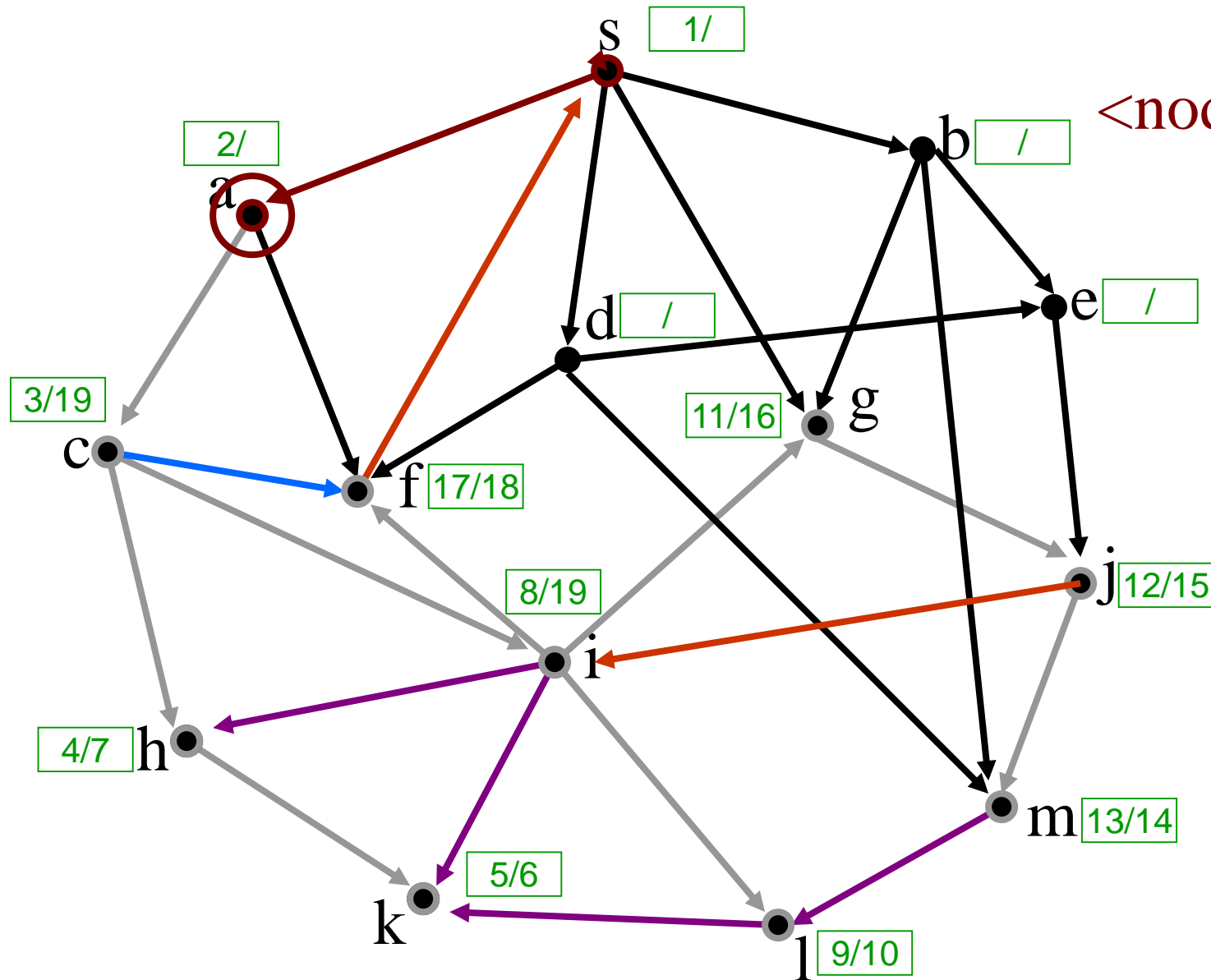
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

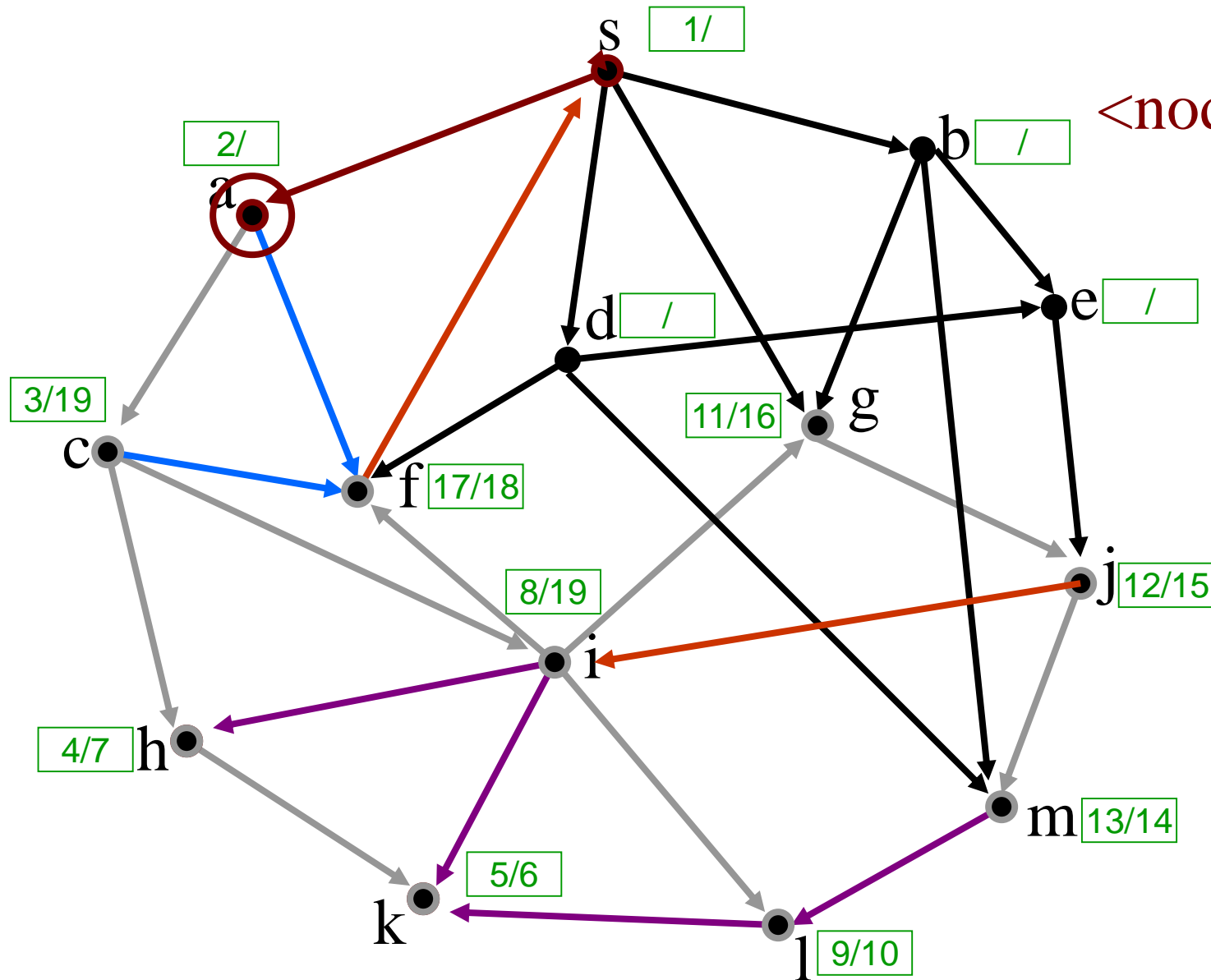


a,1
s,1

DFS

Found
Not Handled
Stack

<node,# edges>

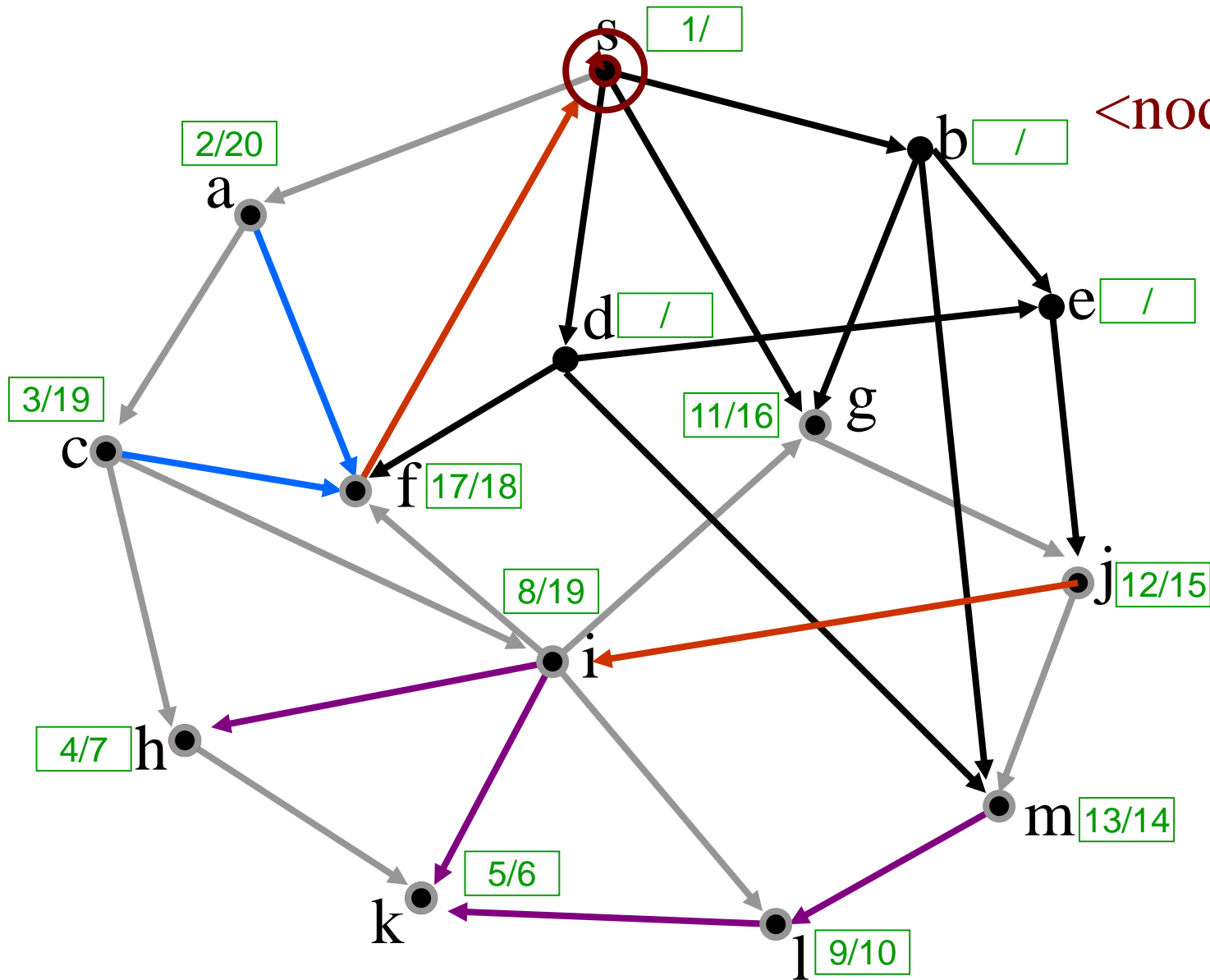


a,2
s,1

DFS

Found Not Handled Stack

<node,# edges>

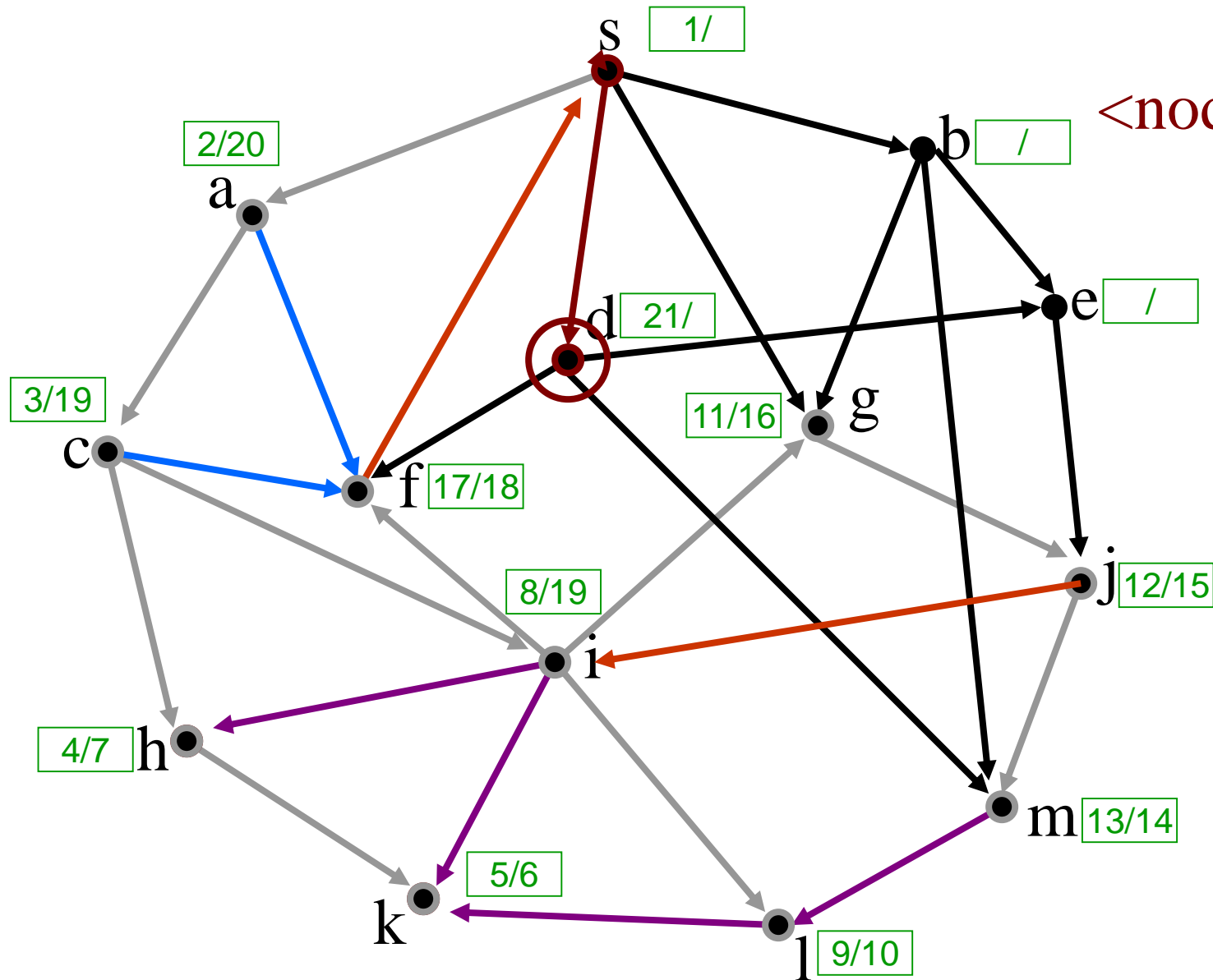


s, 1

DFS

Found
Not Handled
Stack

<node,# edges>

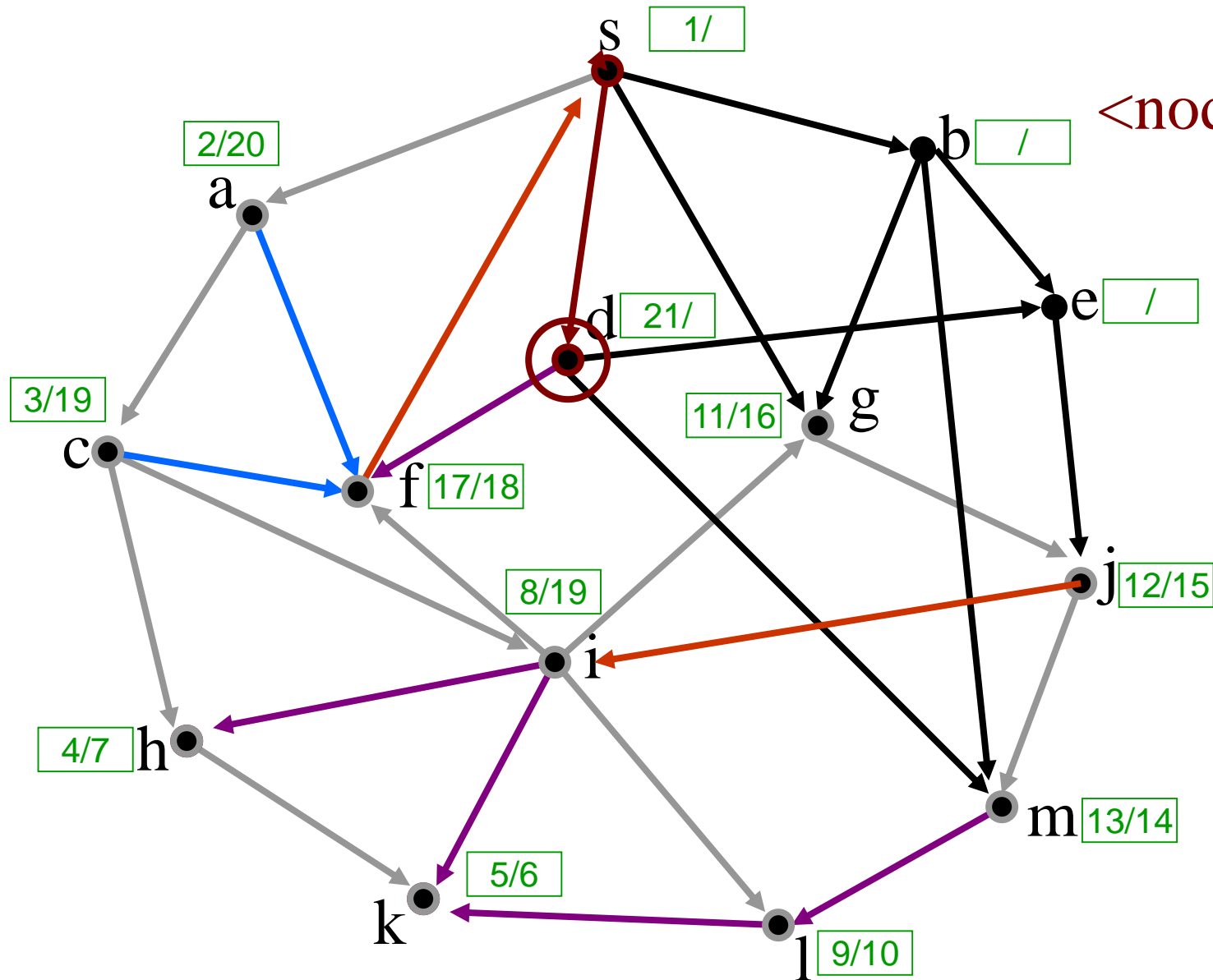


d,0
s,2

DFS

Found
Not Handled
Stack

<node,# edges>

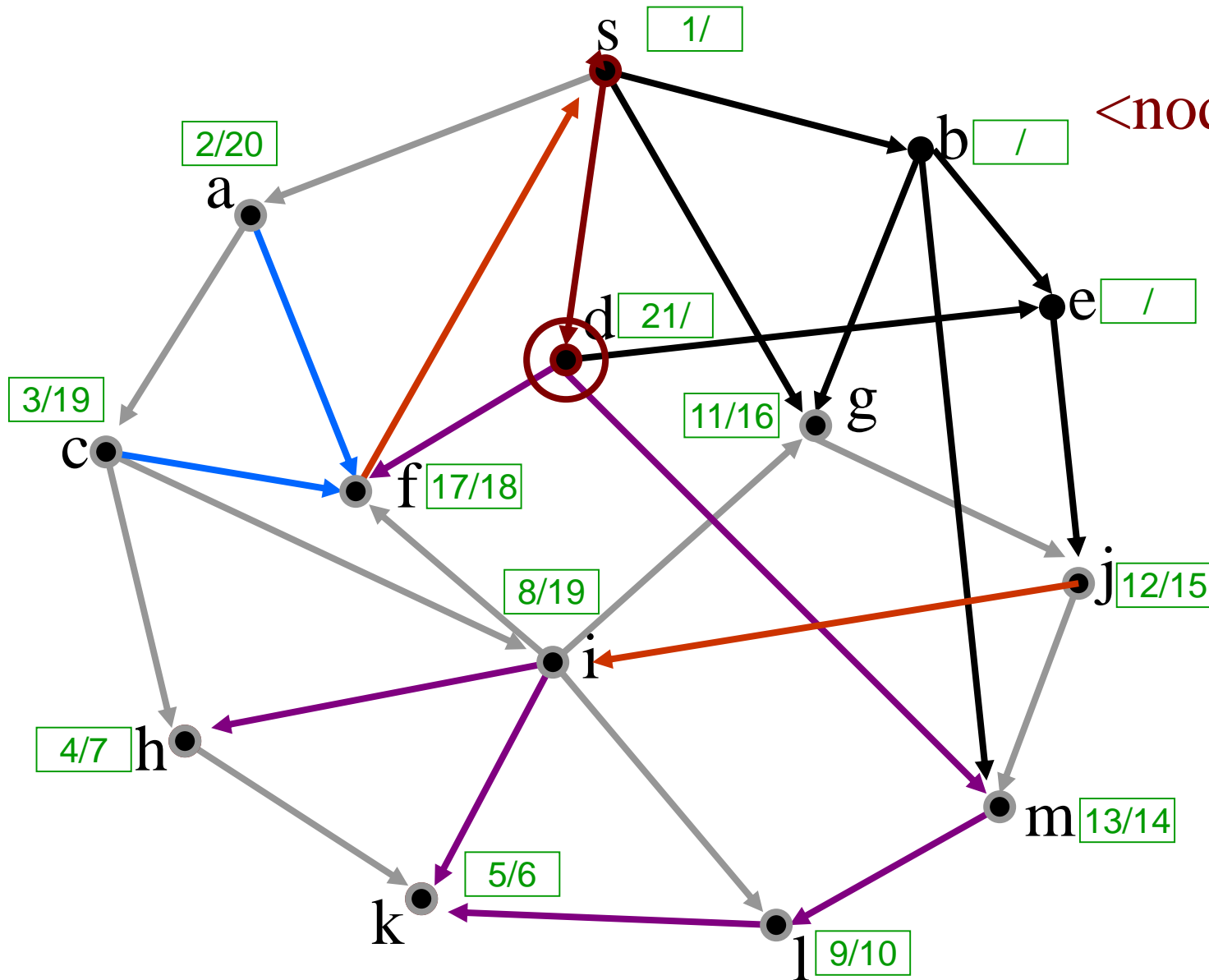


d,1
s,2

DFS

Found
Not Handled
Stack

<node,# edges>

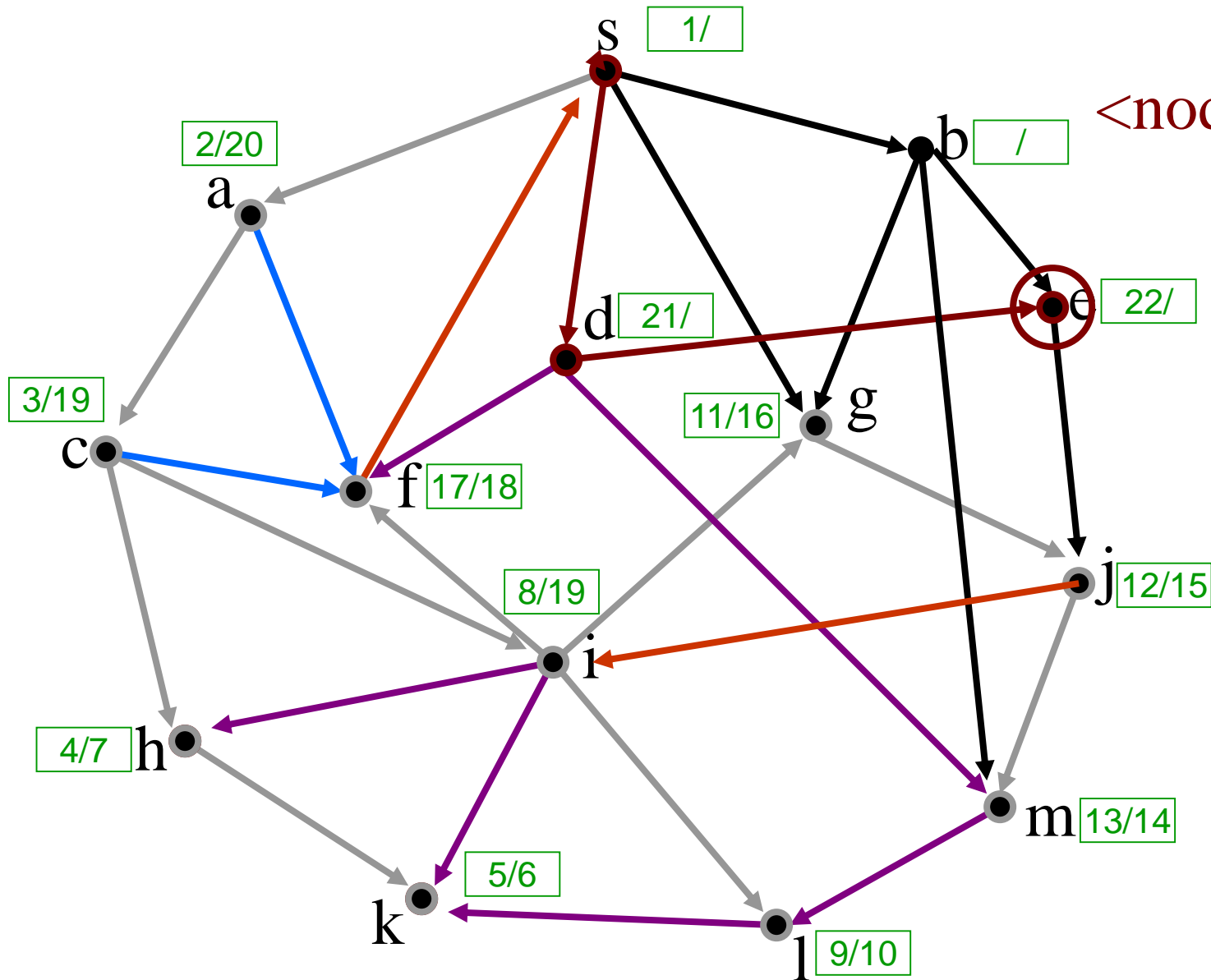


d,2
s,2

DFS

Found
Not Handled
Stack

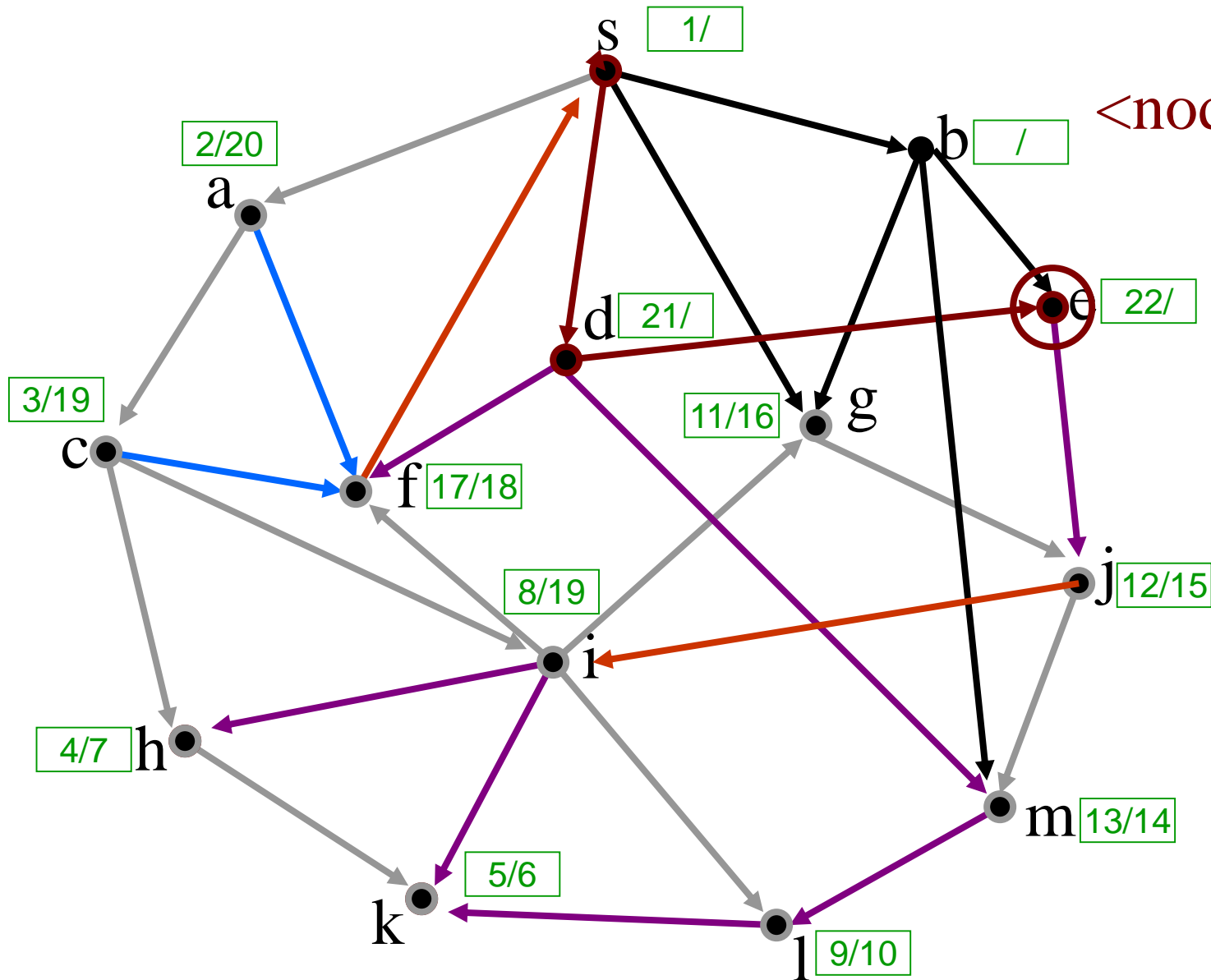
<node,# edges>



DFS

Found
Not Handled
Stack

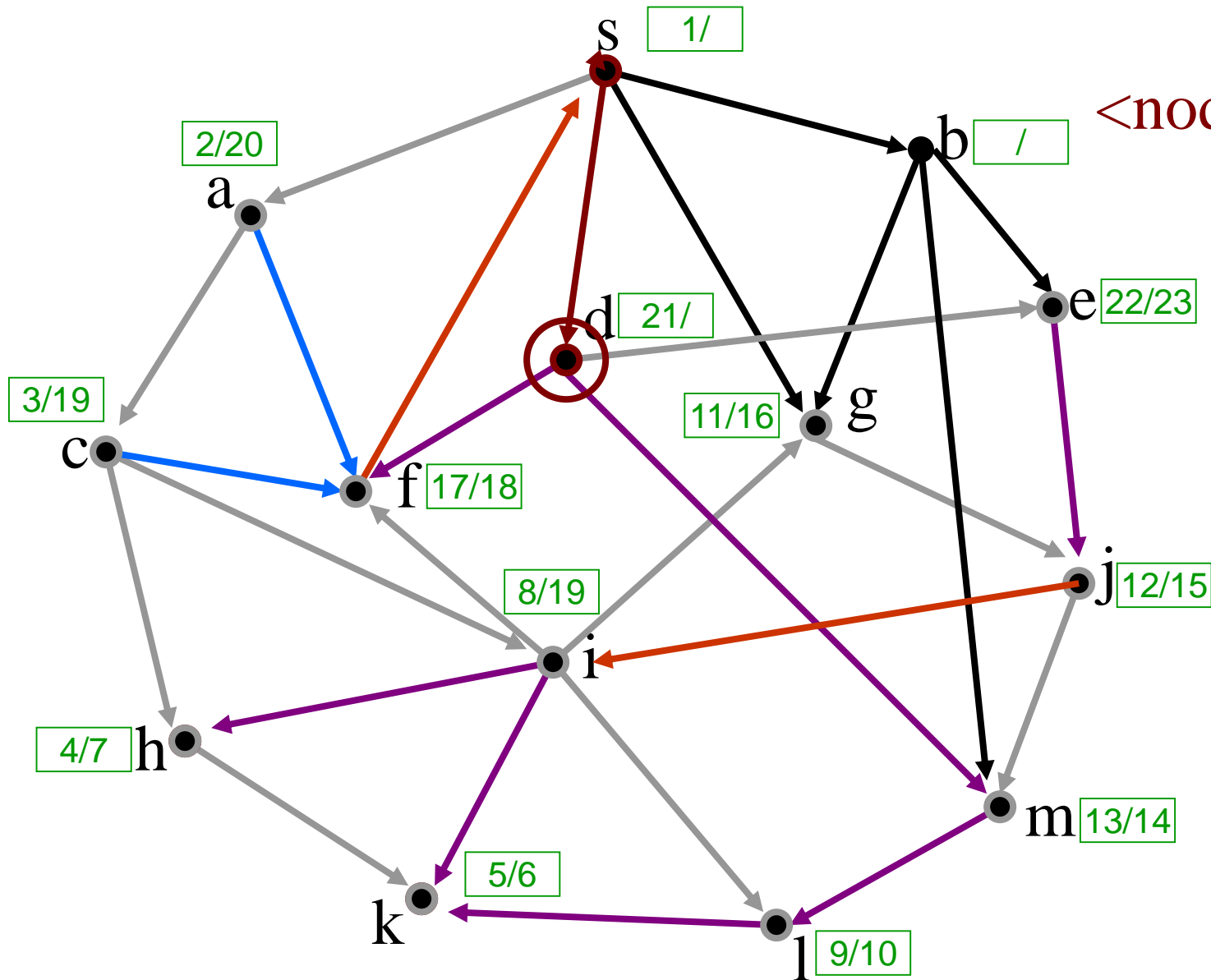
<node,# edges>



DFS

Found
Not Handled
Stack

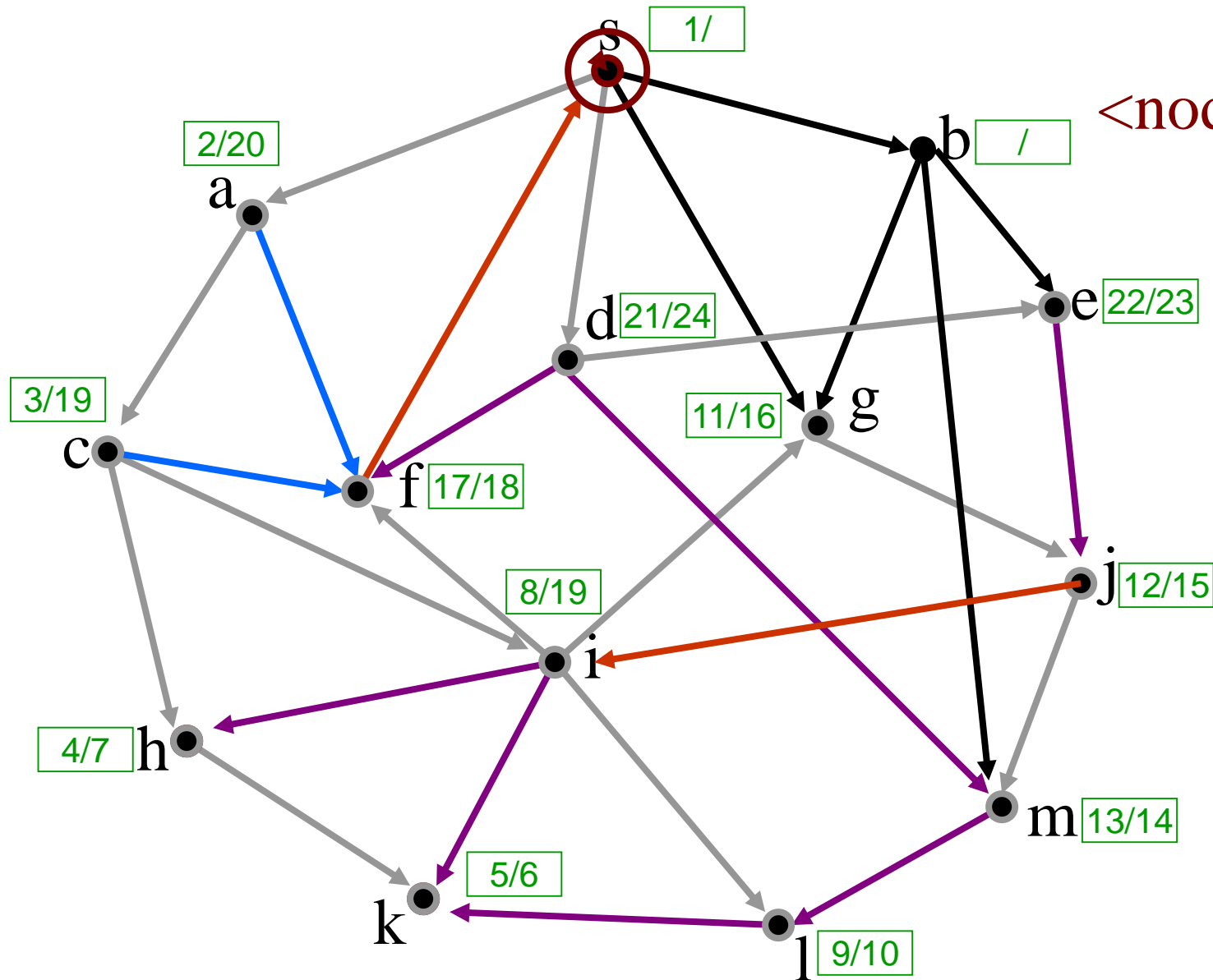
<node,# edges>



DFS

Found
Not Handled
Stack

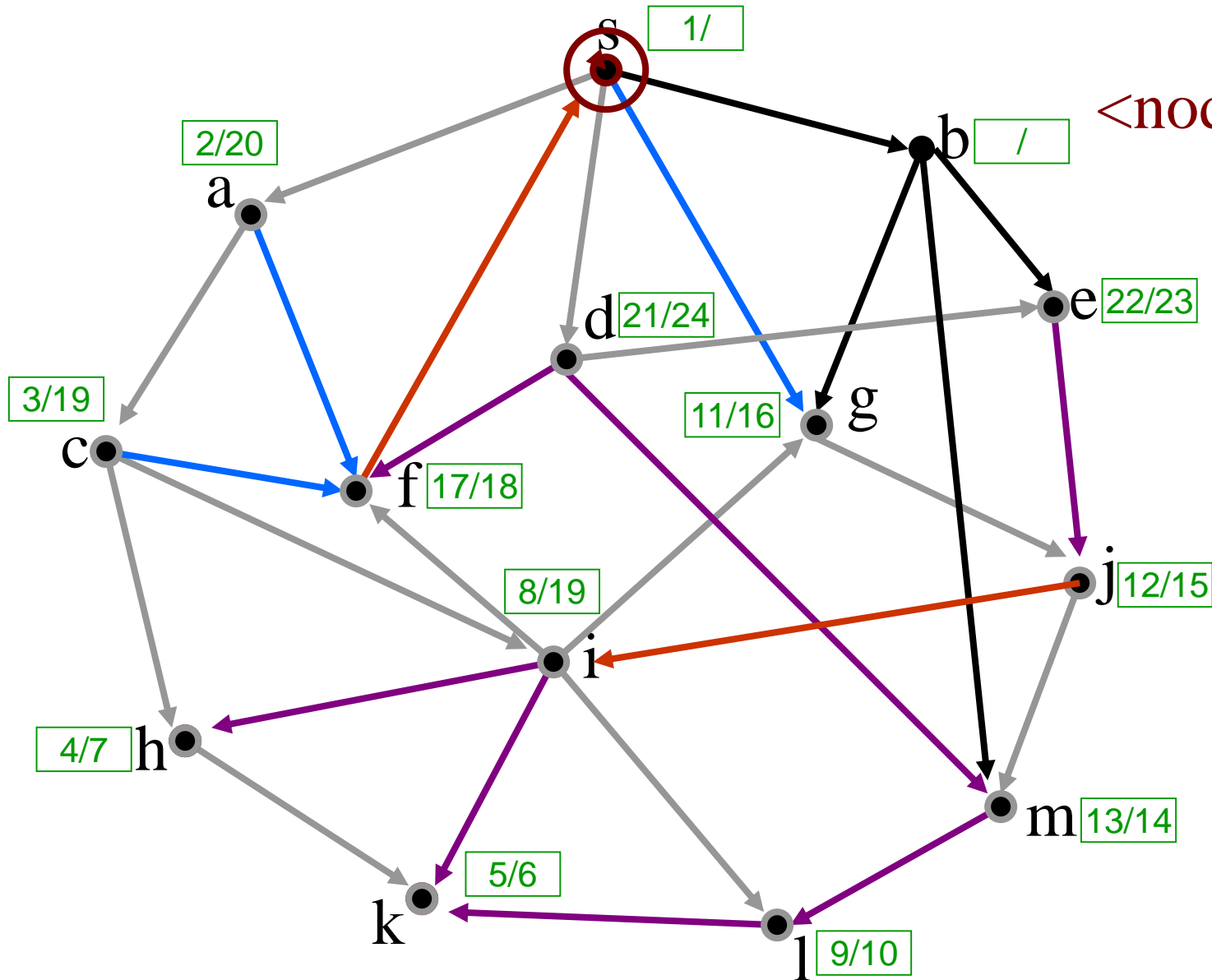
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

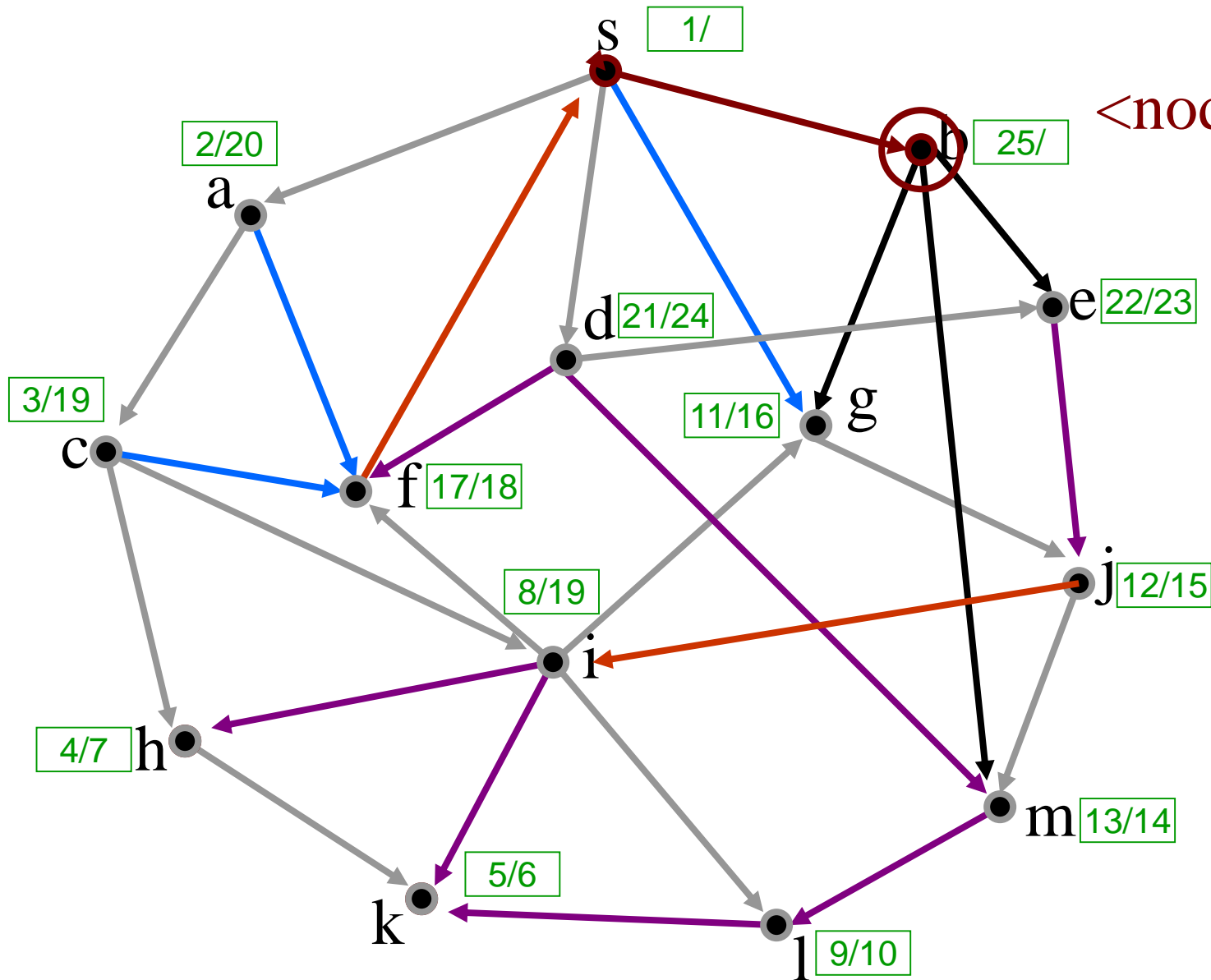


s,3

DFS

Found
Not Handled
Stack

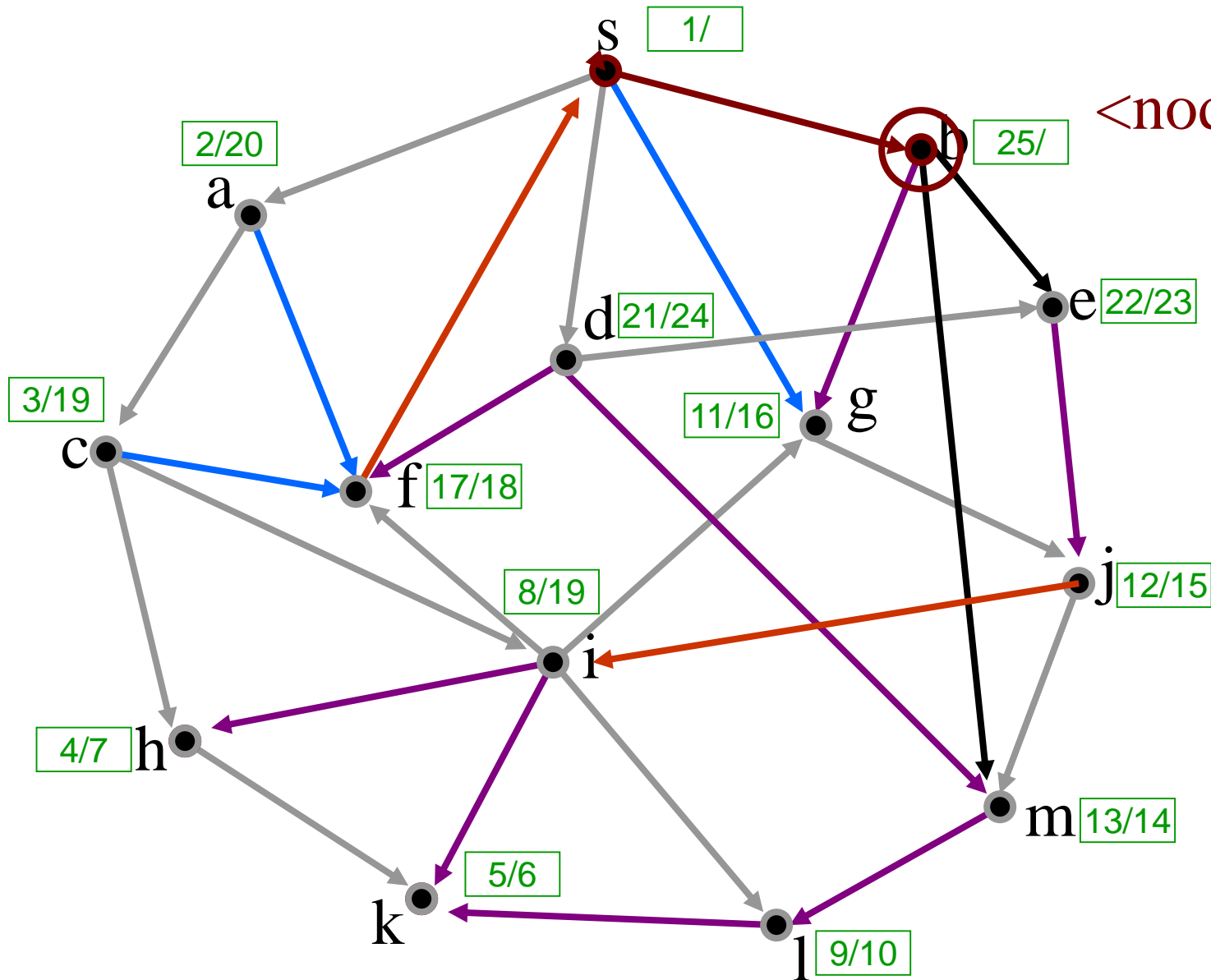
<node,# edges>



DFS

Found
Not Handled
Stack

<node,# edges>

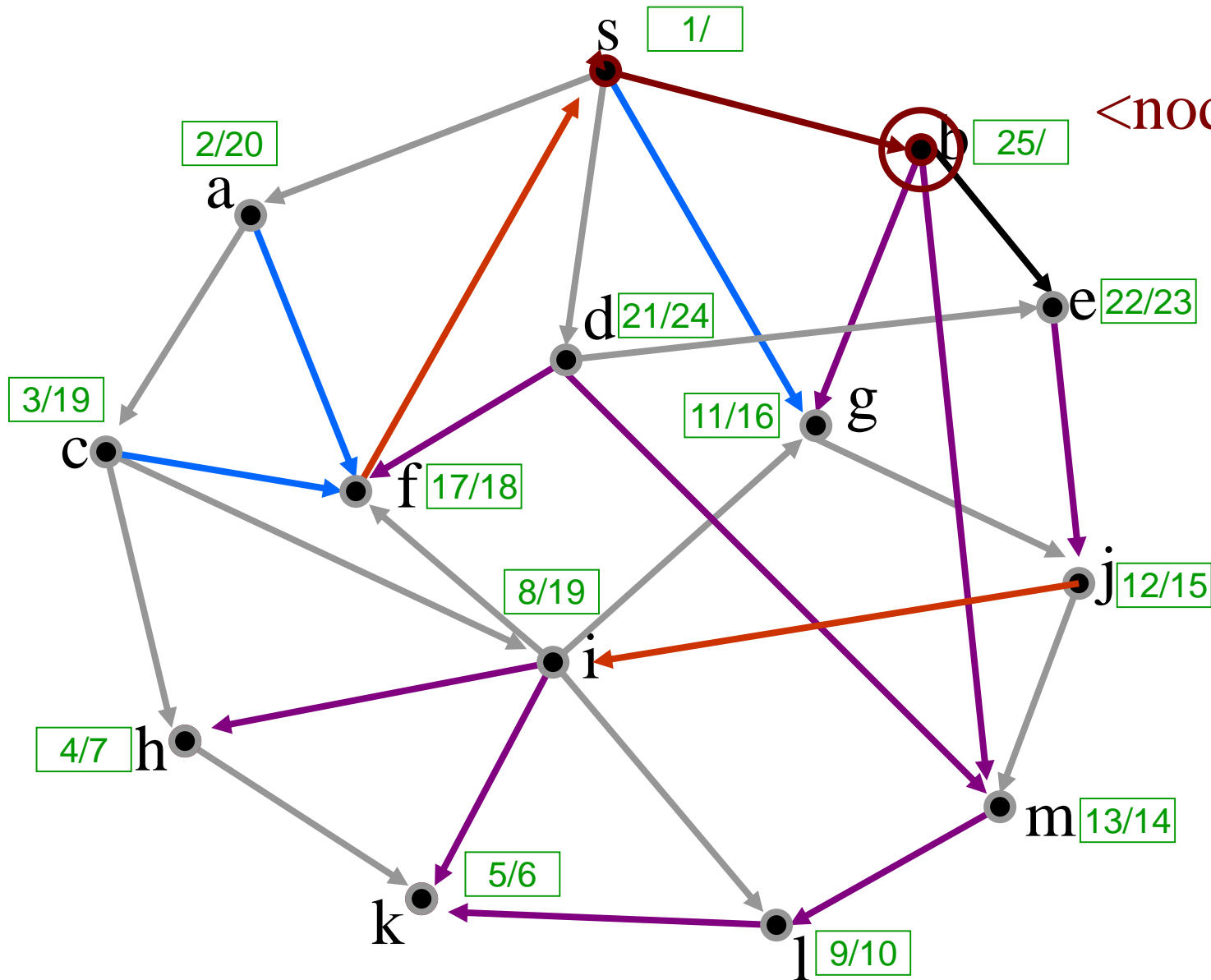


b,1
s,4

DFS

Found
Not Handled
Stack

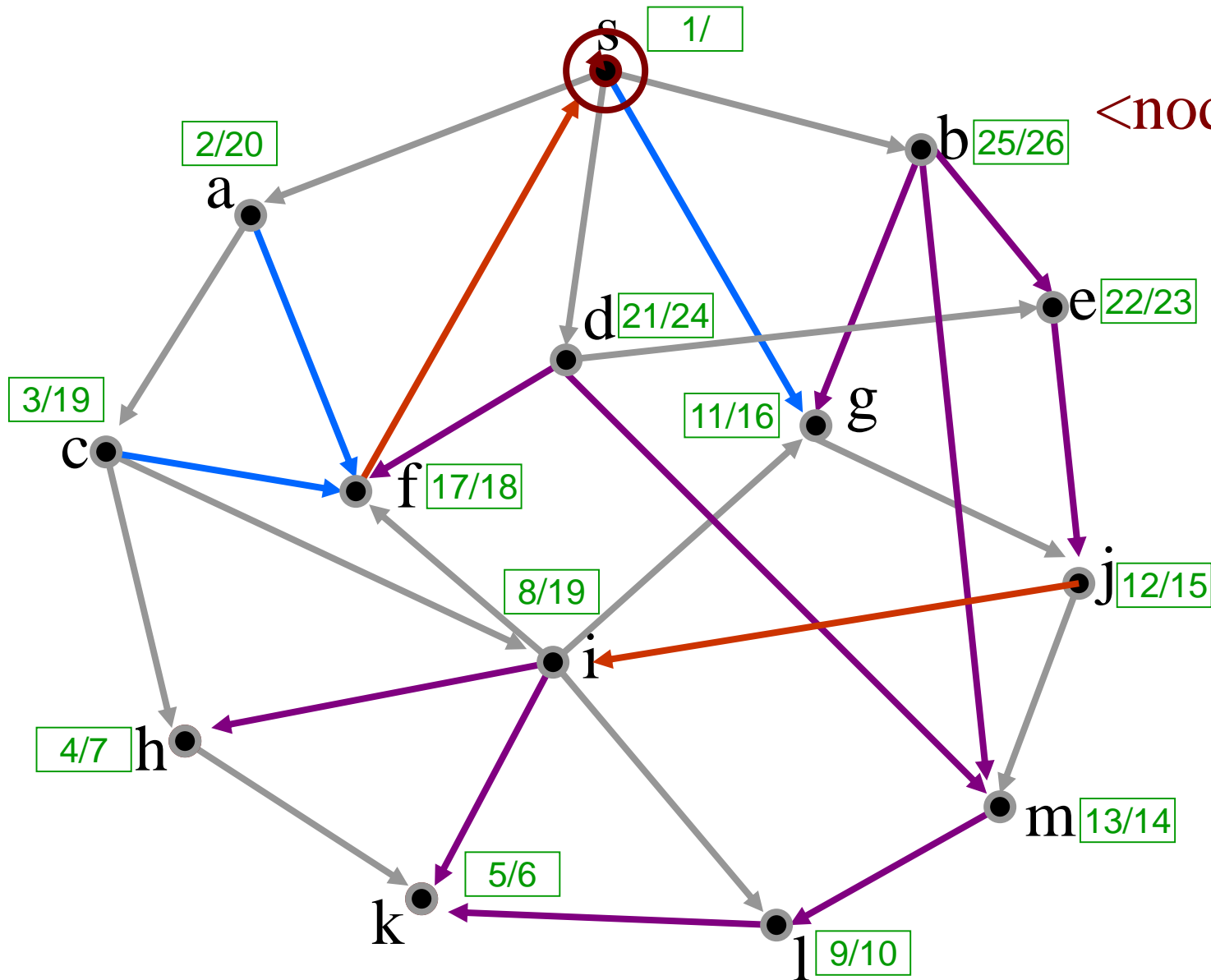
<node,# edges>



DFS

Found Not Handled Stack

<node,# edges>



s,4

DFS

Found
Not Handled
Stack

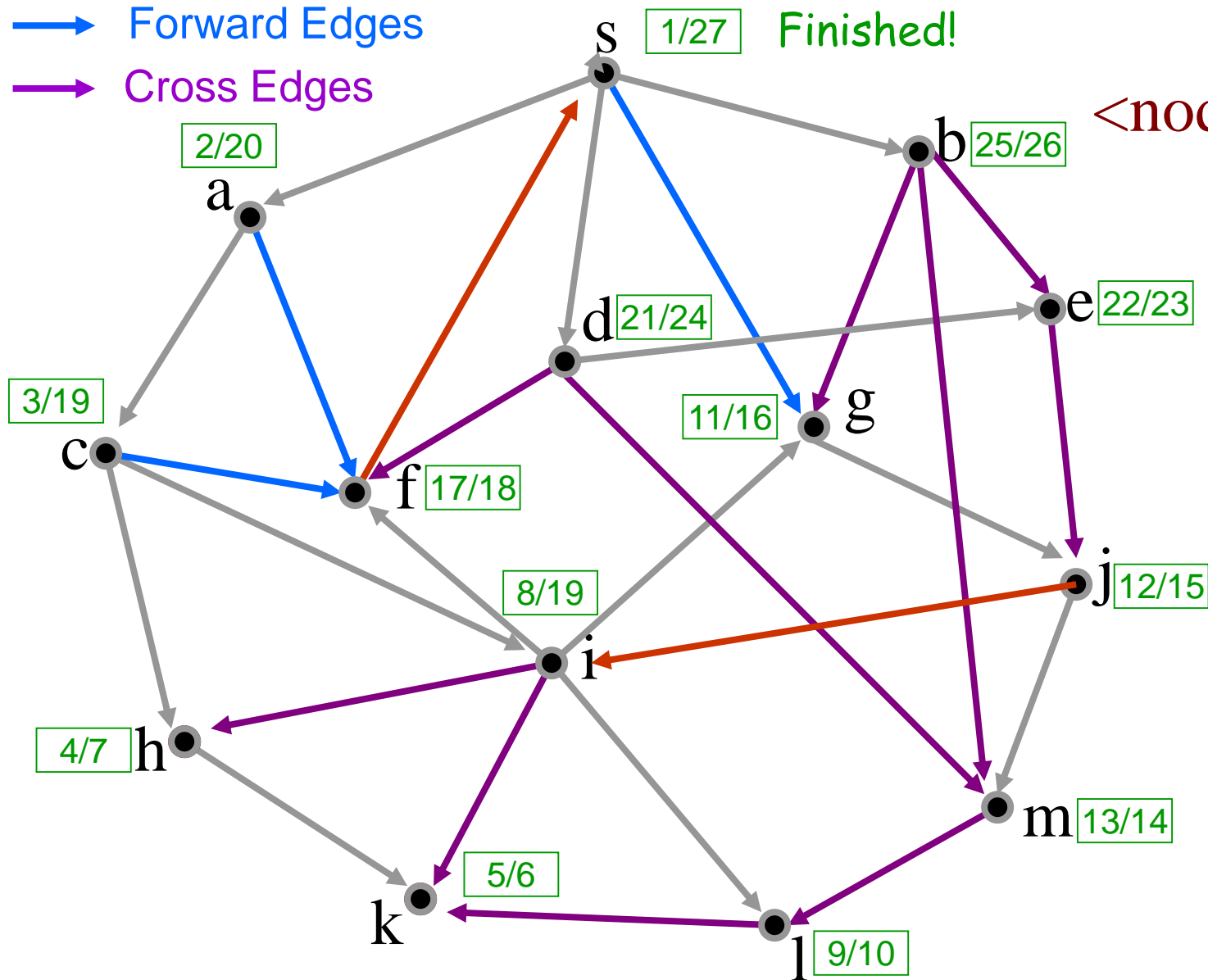
→ Tree Edges

→ Back Edges

→ Forward Edges

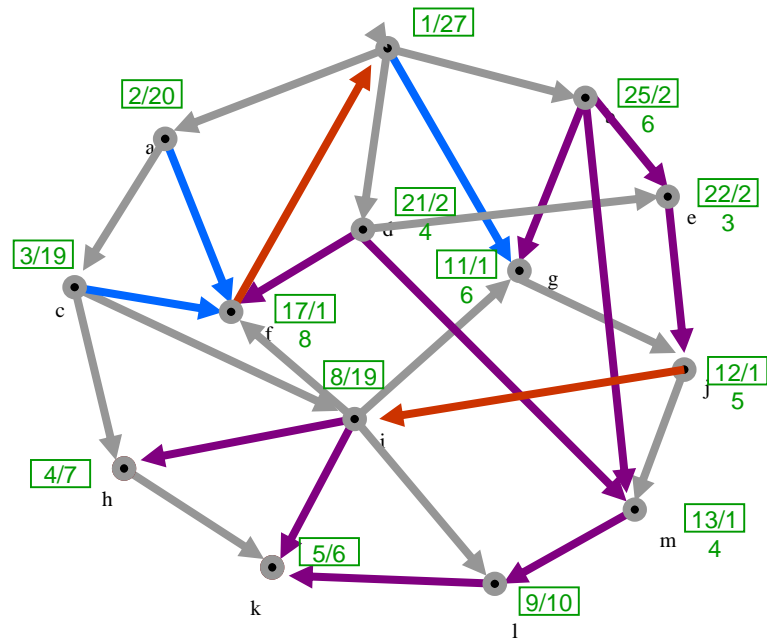
→ Cross Edges

<node,# edges>



Classification of Edges in DFS

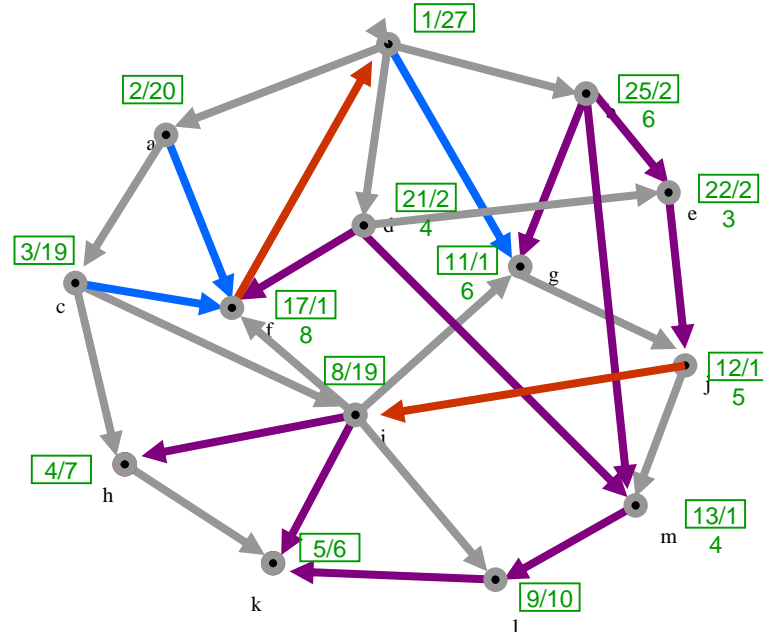
1. **Tree edges** are edges in the depth-first forest G_π . Edge (u, v) is a tree edge if v was first discovered by exploring edge (u, v) .
2. **Back edges** are those edges (u, v) connecting a vertex u to an ancestor v in a depth-first tree.
3. **Forward edges** are non-tree edges (u, v) connecting a vertex u to a descendant v in a depth-first tree.
4. **Cross edges** are all other edges. They can go between vertices in the same depth-first tree, as long as one vertex is not an ancestor of the other.



Classification of Edges in DFS

1. **Tree edges:** Edge (u, v) is a **tree edge** if v was **black** when (u, v) traversed.
2. **Back edges:** (u, v) is a **back edge** if v was **red** when (u, v) traversed.
3. **Forward edges:** (u, v) is a **forward edge** if v was **gray** when (u, v) traversed and $d[v] > d[u]$.
4. **Cross edges** (u, v) is a **cross edge** if v was **gray** when (u, v) traversed and $d[v] < d[u]$.

Classifying edges can help to identify properties of the graph, e.g., a graph is acyclic iff DFS yields no **back edges**.

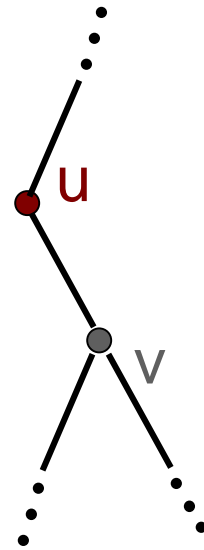


DFS on Undirected Graphs

- In a depth-first search of an *undirected* graph, every edge is either a **tree edge** or a **back edge**.
- **Why?**

DFS on Undirected Graphs

- Suppose that (u,v) is a **forward edge** or a **cross edge** in a DFS of an undirected graph.
- (u,v) is a **forward edge** or a **cross edge** when v is already **handled (grey)** when accessed from u .
- This means that all vertices reachable from v have been explored.
- Since we are currently handling u , u must be **red**.
- Clearly v is reachable from u .
- Since the graph is undirected, u must also be reachable from v .
- Thus u must already have been handled: u must be **grey**.
- **Contradiction!**



Outline

- DFS Algorithm
- DFS Example
- **DFS Applications**

DFS Application 1: Path Finding

- The DFS pattern can be used to find a path between two given vertices u and z , if one exists
- We use a stack to keep track of the current path
- If the destination vertex z is encountered, we return the path as the contents of the stack

DFS-Path ($u, z, stack$)

Precondition: u and z are vertices in a graph, $stack$ contains current path

Postcondition: returns true if path from u to z exists, $stack$ contains path

colour[u] \leftarrow RED

push u onto $stack$

if $u = z$

 return TRUE

for each $v \in Adj[u]$ //explore edge (u, v)

 if color[v] = BLACK

 if DFS-Path($v, z, stack$)

 return TRUE

colour[u] \leftarrow GRAY

pop u from $stack$

return FALSE

DFS Application 2: Cycle Finding

- The DFS pattern can be used to determine whether a graph is acyclic.
- If a back edge is encountered, we return true.

DFS-Cycle (u)

Precondition: u is a vertex in a graph G

Postcondition: returns true if there is a cycle reachable from u .

$colour[u] \leftarrow RED$

for each $v \in Adj[u]$ //explore edge (u,v)

if $color[v] = RED$ //back edge

return true

else if $color[v] = BLACK$

if DFS-Cycle(v)

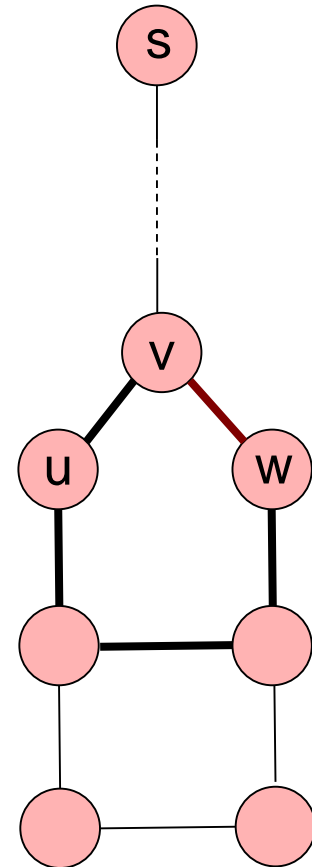
return true

$colour[u] \leftarrow GRAY$

return false

Why must DFS on a graph with a cycle generate a back edge?

- Suppose that vertex s is in a connected component S that contains a cycle C .
- Since all vertices in S are reachable from s , they will all be visited by a DFS from s .
- Let v be the first vertex in C reached by a DFS from s .
- There are two vertices u and w adjacent to v on the cycle C .
- wlog, suppose u is explored first.
- Since w is reachable from u , w will eventually be discovered.
- When exploring w 's adjacency list, the back-edge (w, v) will be discovered.



DFS Application 3. Topological Sorting (e.g., putting tasks in linear order)

Note: The textbook also describes a breadth-first TopologicalSort algorithm (Section 13.4.3)

DAGs and Topological Ordering

- A directed acyclic graph (DAG) is a digraph that has no directed cycles
- A topological ordering of a digraph is a numbering

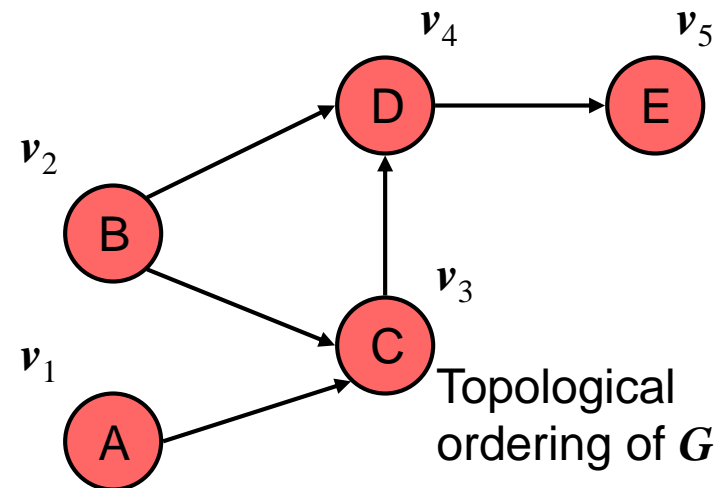
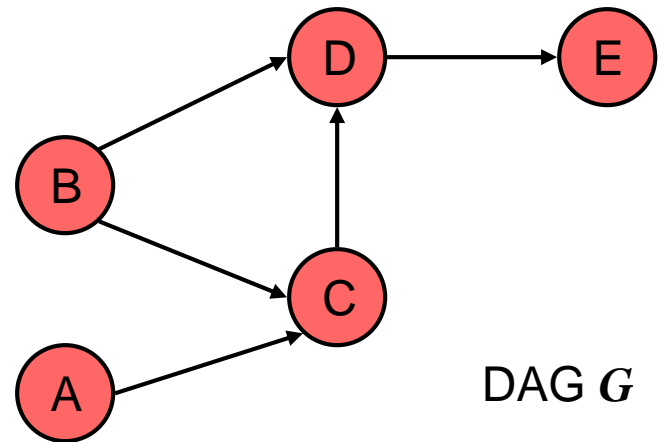
$$v_1, \dots, v_n$$

of the vertices such that for every edge (v_i, v_j) , we have $i < j$

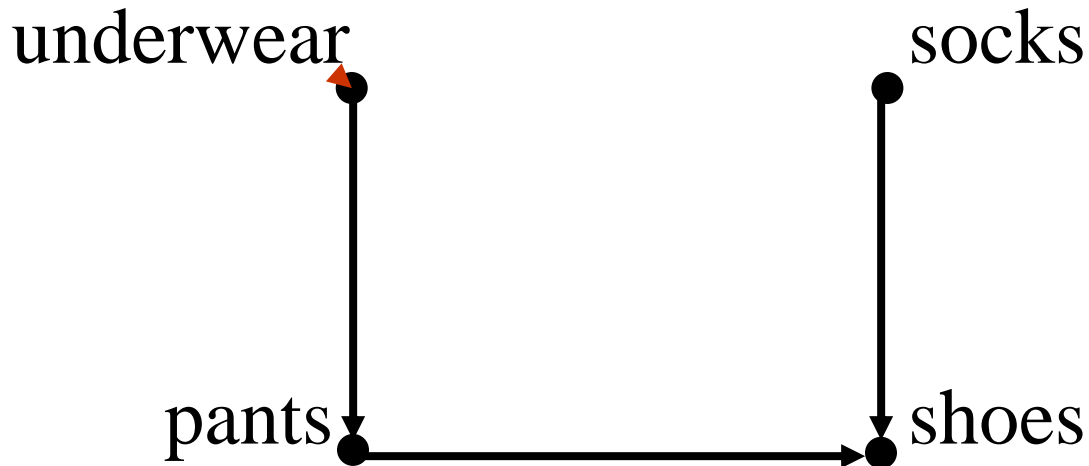
- Example: in a task scheduling digraph, a topological ordering is a task sequence that satisfies the precedence constraints

Theorem

A digraph admits a topological ordering if and only if it is a DAG



Topological (Linear) Order



underwear
pants
socks
shoes

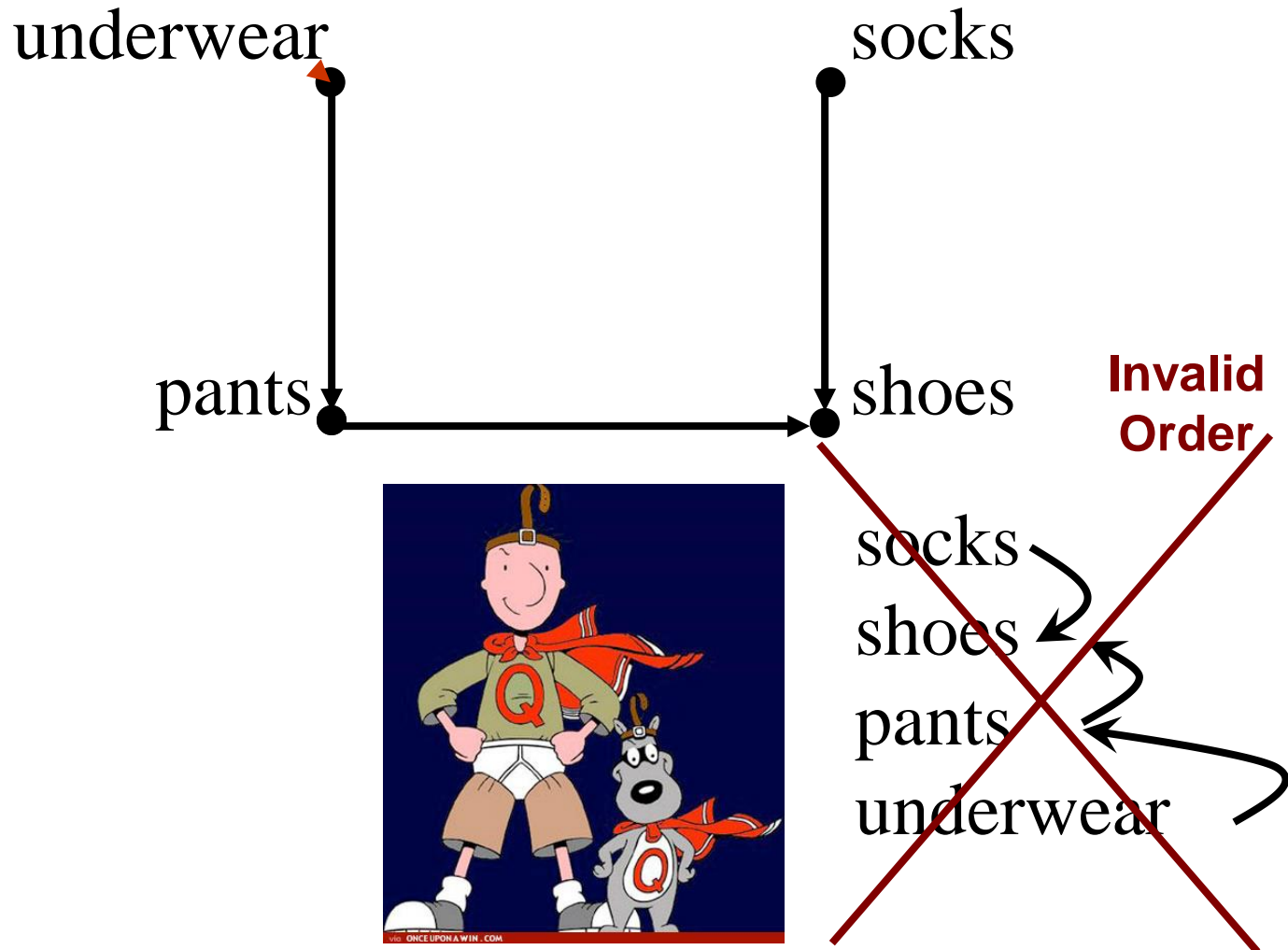
Two curved arrows on the right side of the list point from 'socks' to 'underwear' and from 'shoes' to 'pants', indicating a topological sort where items are listed in the order they can be put on.



socks
underwear
pants
shoes

Two curved arrows on the right side of the list point from 'socks' to 'underwear' and from 'shoes' to 'pants', indicating a topological sort where items are listed in the order they can be put on.

Topological (Linear) Order



Algorithm for Topological Sorting

- Note: This algorithm is different than the one in Goodrich-Tamassia

Method TopologicalSort(**G**)

$H \leftarrow G$ // Temporary copy of **G**

$n \leftarrow G.numVertices()$

while **H** is not empty **do**

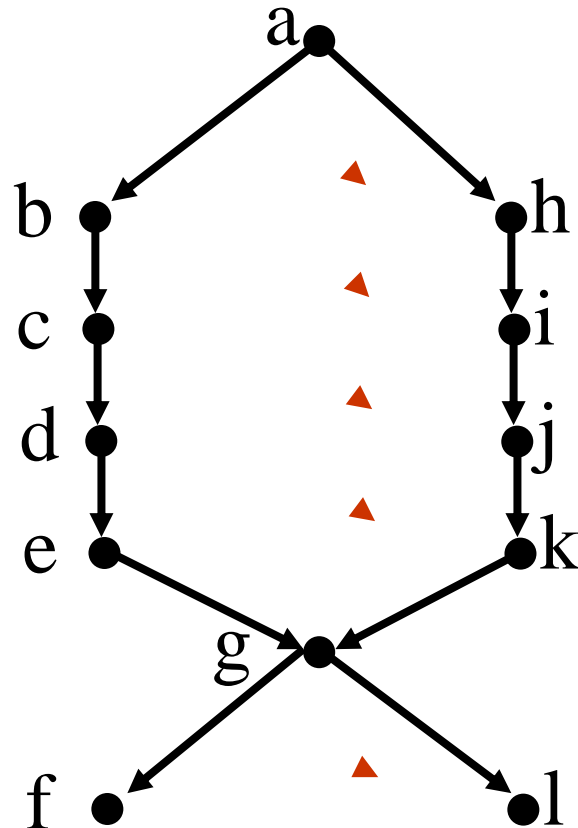
Let **v** be a vertex with no outgoing edges

Label **$v \leftarrow n$**

$n \leftarrow n - 1$

Remove **v** from **H** *//as well as edges involving v*

Linear Order



Pre-Condition:

A Directed Acyclic Graph
(DAG)

Post-Condition:

Find one valid linear order

Algorithm:

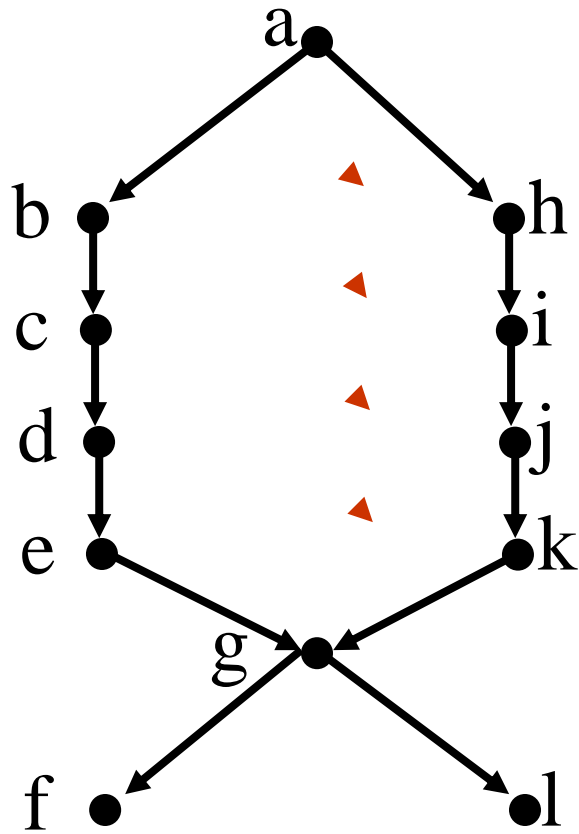
- Find a terminal node (sink).
 - Put it last in sequence.
 - Delete from graph & repeat
- } $O(|V|)$

Running time: $\sum_{i=1}^{|V|} i = O(|V|^2)$

..... 1 Can we do better?

Linear Order

Alg: DFS



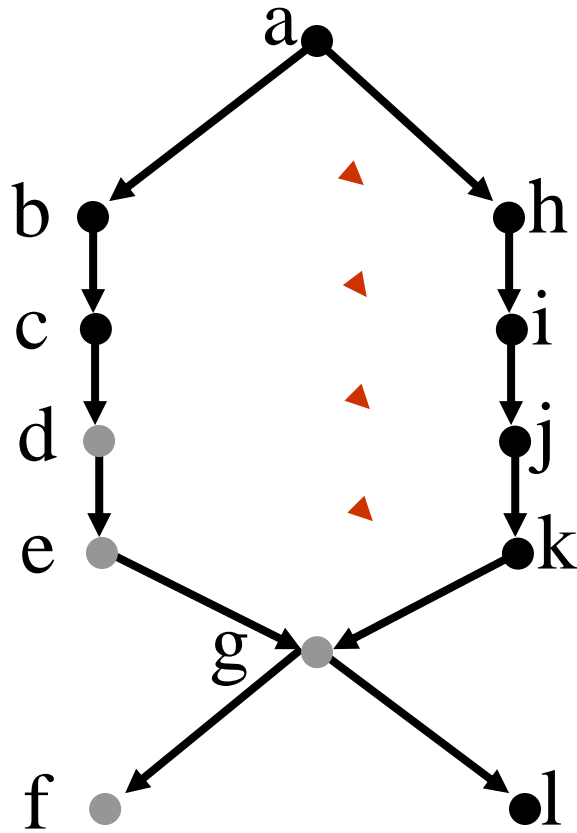
Found
Not Handled
Stack



..... f

Linear Order

Alg: DFS



Found
Not Handled
Stack



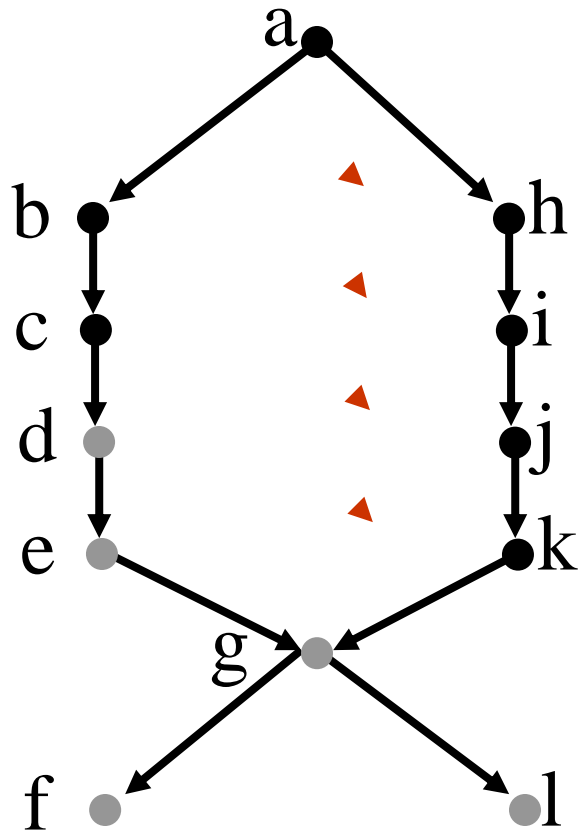
When node is popped off stack, insert at front of linearly-ordered “to do” list.

Linear Order:

..... f

Linear Order

Alg: DFS



Found
Not Handled
Stack

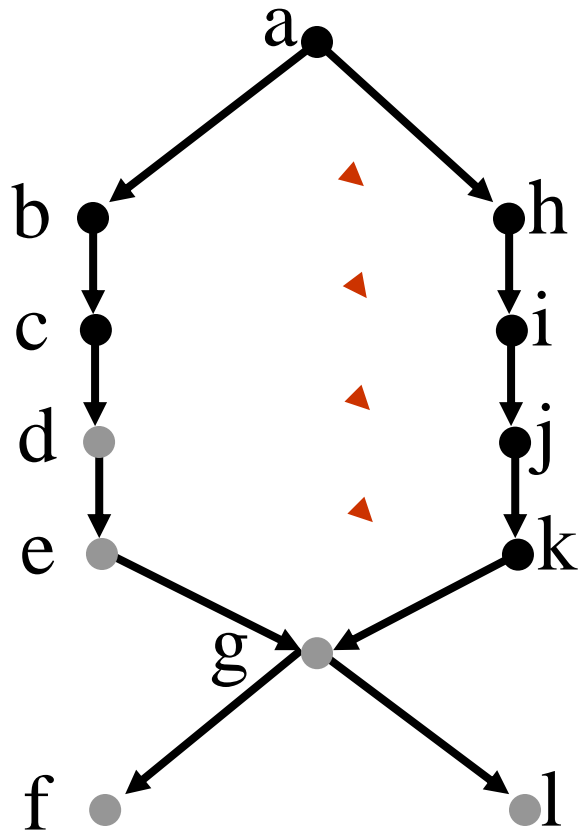


Linear Order:

l,f

Linear Order

Alg: DFS



Found
Not Handled
Stack

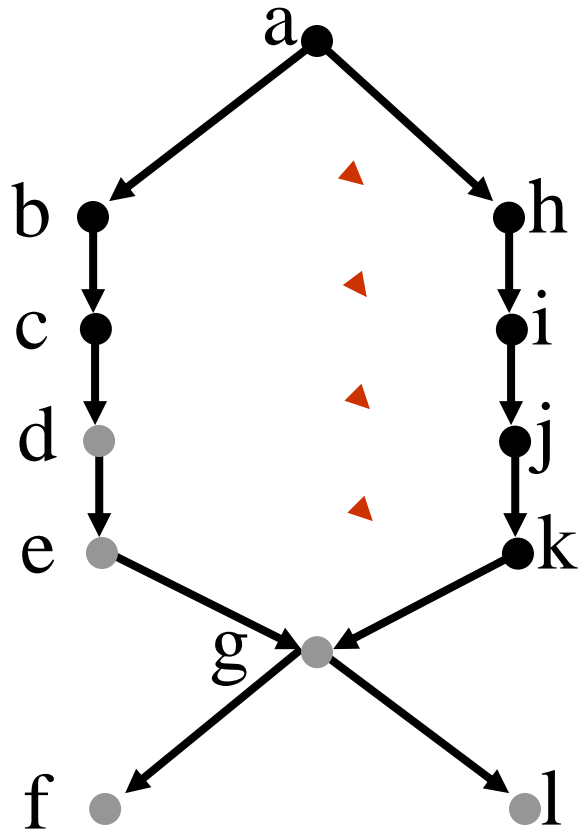


Linear Order:

g,l,f

Linear Order

Alg: DFS



Found
Not Handled
Stack

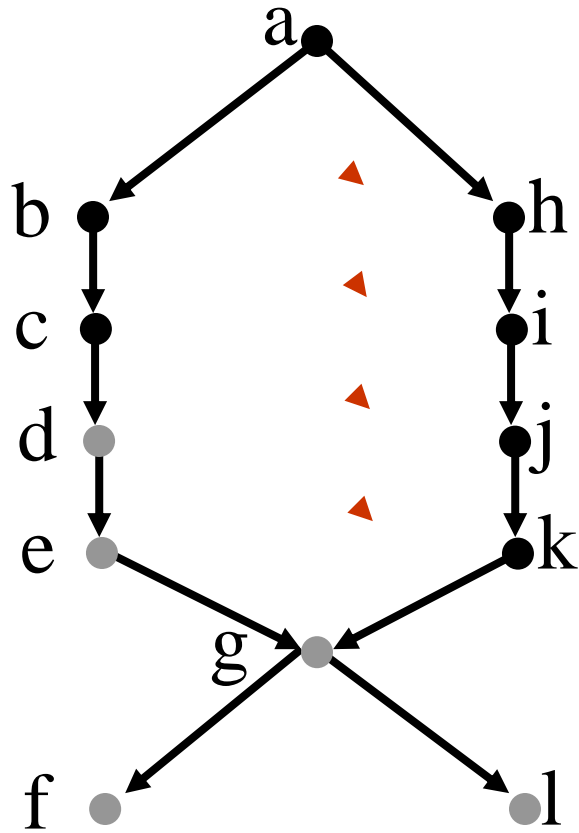


Linear Order:

e,g,l,f

Linear Order

Alg: DFS



Found
Not Handled
Stack

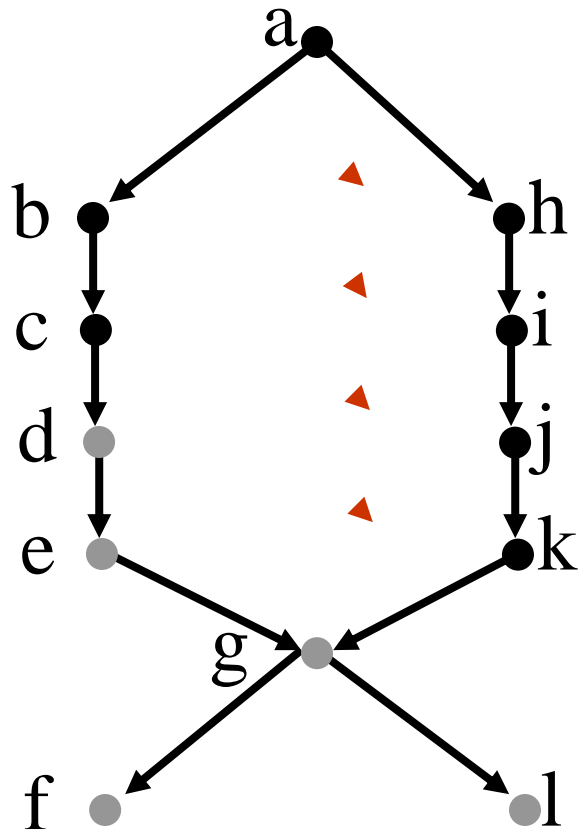


Linear Order:

d,e,g,l,f

Linear Order

Alg: DFS



Found
Not Handled
Stack

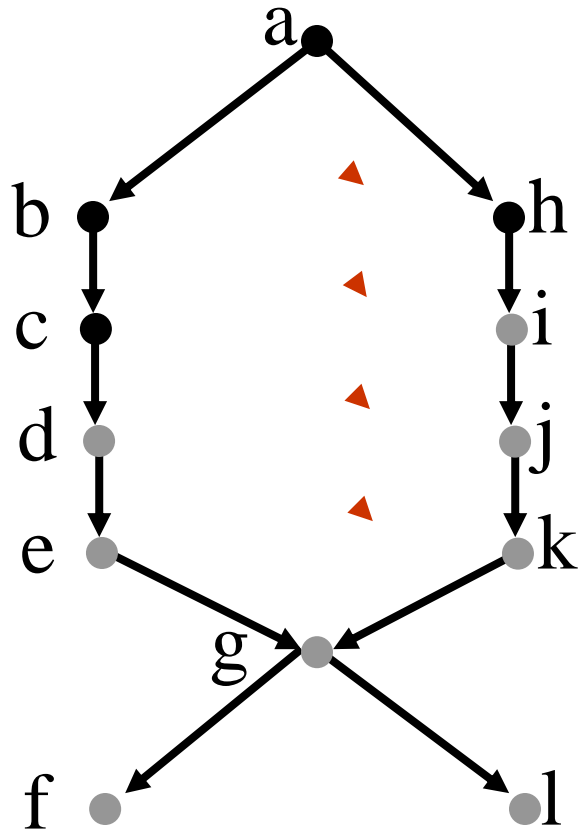
k
j
i

Linear Order:

d,e,g,l,f

Linear Order

Alg: DFS



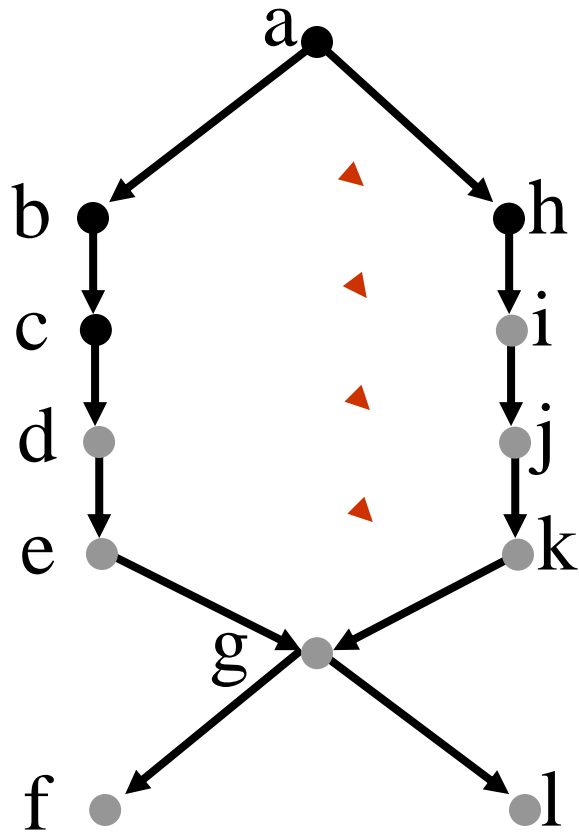
Found
Not Handled
Stack



Linear Order: k,d,e,g,l,f

Linear Order

Alg: DFS



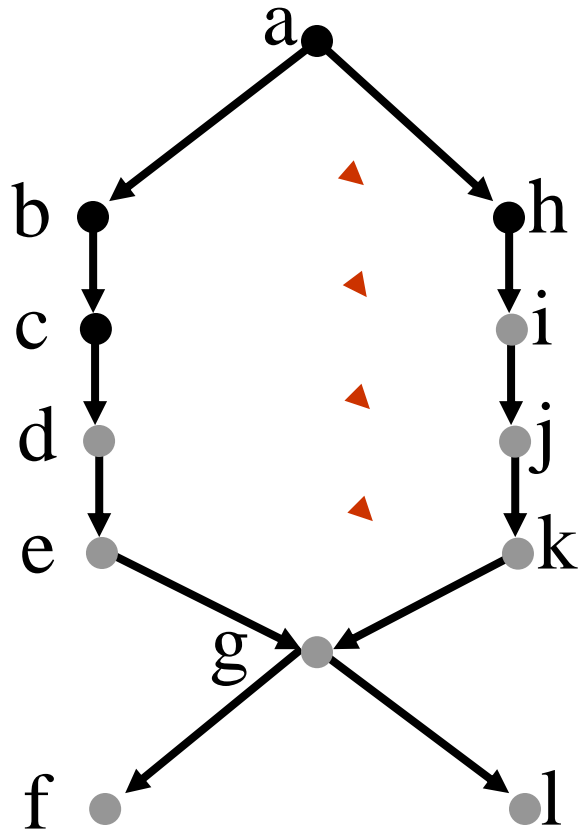
Found
Not Handled
Stack



Linear Order: j,k,d,e,g,l,f

Linear Order

Alg: DFS



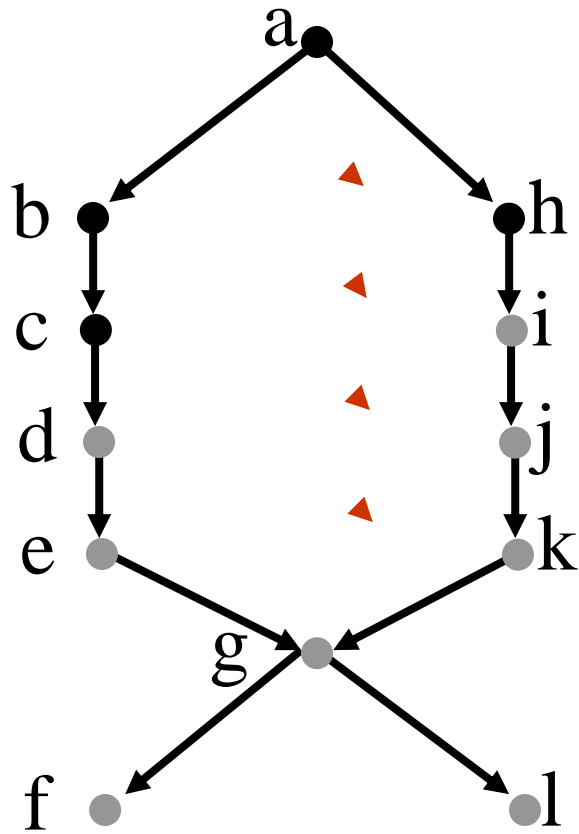
Found
Not Handled
Stack



Linear Order: i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



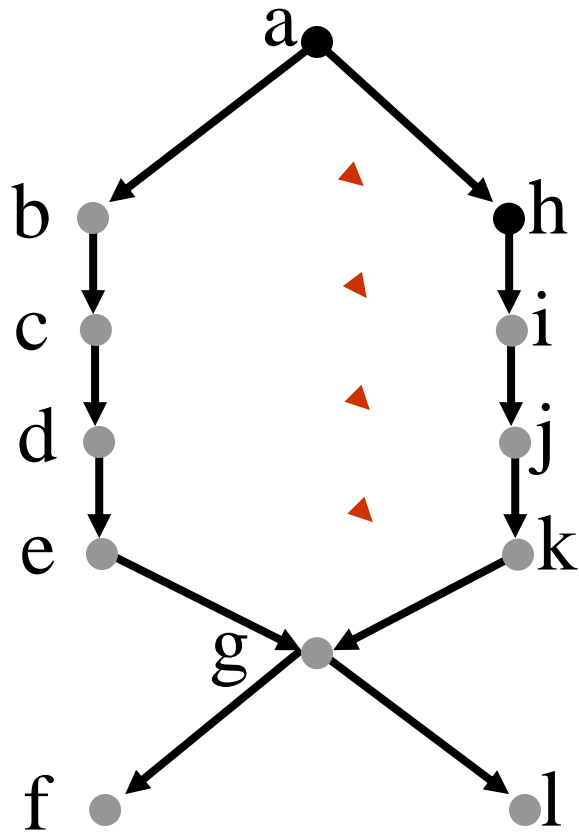
Found
Not Handled
Stack



Linear Order: i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



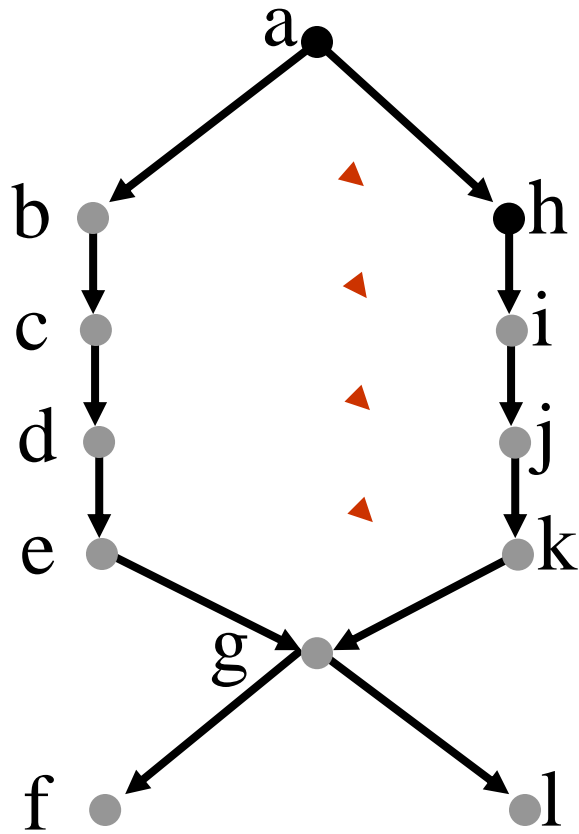
Found
Not Handled
Stack



Linear Order: c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



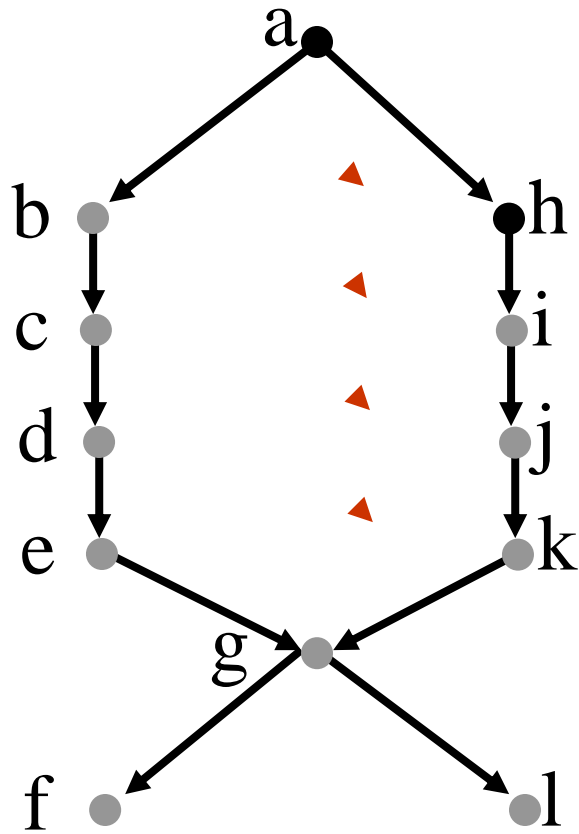
Found
Not Handled
Stack



Linear Order: b,c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS



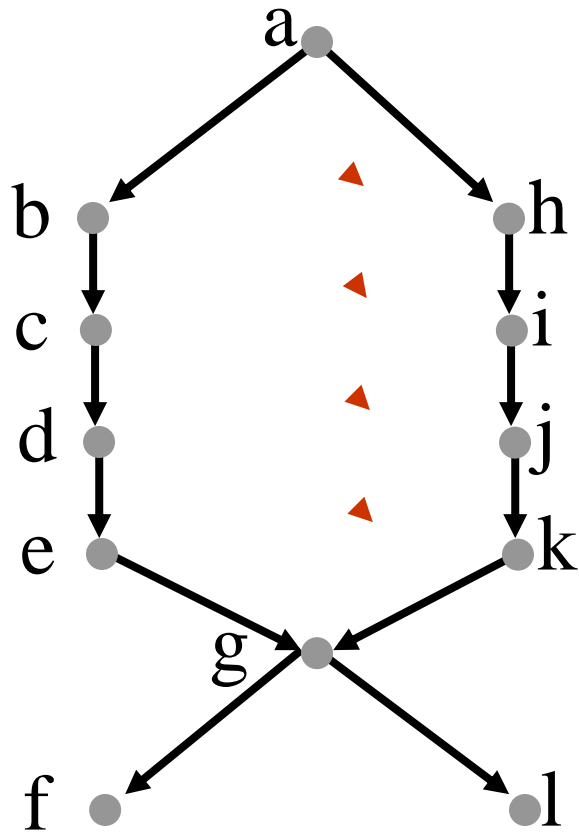
Found
Not Handled
Stack



Linear Order: b,c,i,j,k,d,e,g,l,f

Linear Order

Alg: DFS

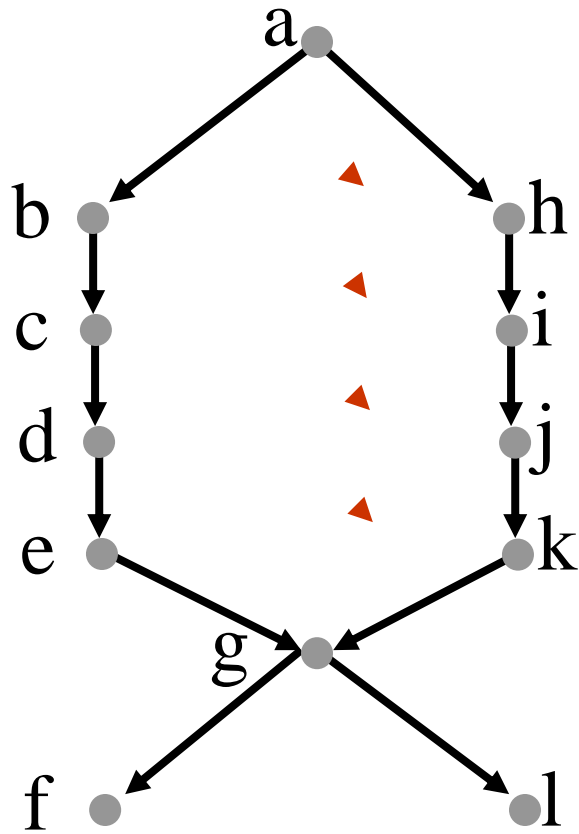


Found
Not Handled
Stack



Linear Order: h,b,c,i,j,k,d,e,g,l,f

Linear Order
Alg: DFS



Found
Not Handled
Stack



Linear Order: a,h,b,c,i,j,k,d,e,g,l,f Done!

DFS Algorithm for Topological Sort

➤ Makes sense. But how do we prove that it works?

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v .
 - Because of edge,
 - v goes on before u comes off
 - v comes off before u comes off
 - v goes after u in order. ☺

Found
Not Handled
Stack



$u \dots v \dots$

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v .
- Case 2: v goes on stack first before u .
 v comes off before u goes on.
- v goes after u in order. 😊

Found
Not Handled
Stack



$u \dots v \dots$

Linear Order

Proof: Consider each edge

- Case 1: u goes on stack first before v.
- Case 2: v goes on stack first before u.
v comes off before u goes on.
- Case 3: v goes on stack first before u.
u goes on before v comes off.
- Panic: u goes after v in order. ☹
- Cycle means linear order
is impossible ☺

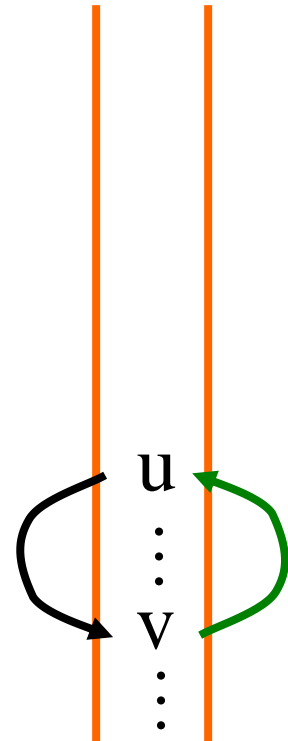


The nodes in the stack form a path starting at s.

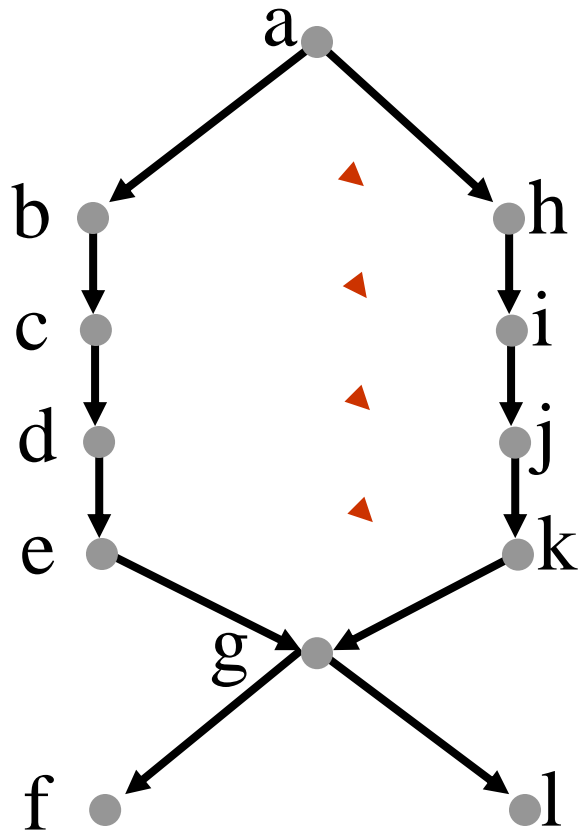
u ● → ● v

v...u...

Found
Not Handled
Stack



Linear Order
Alg: DFS



Found
Not Handled
Stack



Analysis: $\Theta(V+E)$

Linear Order: a,h,b,c,i,j,k,d,e,g,l,f Done!

DFS Application 3. Topological Sort

Topological-Sort(G)

Precondition: G is a graph

Postcondition: all vertices in G have been pushed onto stack in reverse linear order

for each vertex $u \in V[G]$

color[u] = BLACK //initialize vertex

for each vertex $u \in V[G]$

if color[u] = BLACK //as yet unexplored

Topological-Sort-Visit(u)



DFS Application 3. Topological Sort

Topological-Sort-Visit (u)

Precondition: vertex u is undiscovered

Postcondition: u and all vertices reachable from u have been pushed onto stack in reverse linear order

colour[u] \leftarrow RED

for each $v \in \text{Adj}[u]$ //explore edge (u, v)

if color[v] = BLACK

Topological-Sort-Visit(v)

push u onto stack

colour[u] \leftarrow GRAY

Outline

- DFS Algorithm
- DFS Example
- DFS Applications